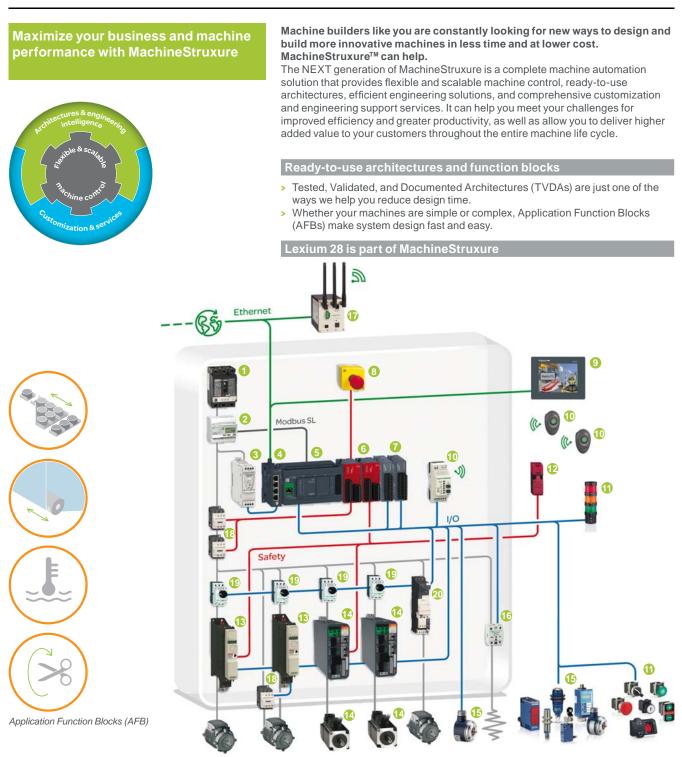
General overview



#### Compact/Hardwired/Logic Controller Modicon M241

#### **Solution Breakdown**

- Compact NSX circuit breaker 1
- 2 IEM32 energy meter
- Phaseo switch mode power supply 3
- 4 Modicon TM4 Ethernet switch module
- 5 Modicon M241 logic controller
- 6 Modicon TM3 functional safety module
- 7 Modicon TM3 I/O expansion module
- 8 Harmony XALK emergency stop
- 9 Magelis STO/STU HMI
- 10 Harmony XB5R wireless and batteryless 18 TeSys D switch connector fuse pushbutton, configurable access point
  - 19 TeSvs GV2L magnetic circuit breaker

units

17 ConneXium wireless Ethernet access

11 Harmony XB4/XB5 Control & signaling

14 Servo Drive Lexium 28, servo motor BCH2

12 Preventa XCS safety switch

13 Altivar 32 variable speed drive

15 OsiSense proximity & photoelectric

sensors, limit switch, encoder

16 Zelio Relay solid-state relay

20 TeSys GV2M/3P D.O.L. / reversing starter

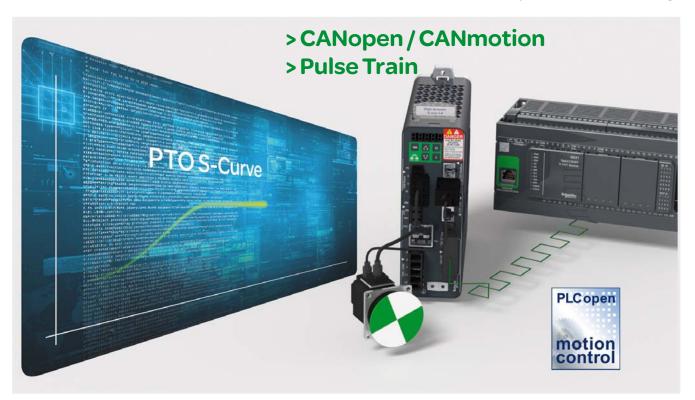


General overview

## Lexium 28 & BCH2: optimized servo bundles for compact machines

#### Servo range with best-in-class performance

The predefined servo bundles of Lexium 28 servo drive & BCH2 servo motor are optimized for easy integration & commissioning in your machine. It includes standard interfaces, embedded safety function and DC-bus sharing.



#### Reduce your time to market

- > Automatic tuning and motor identification
- > PLC open motion library

#### Increase profitability

- > Designed for optimized & cost effective solutions
- > Drive embedded safety function: Safe-Torque-Off

#### Improve efficiency

- > Energy efficient because of DC-bus sharing
- > Predefined servo bundles to fit each machine type

#### Simplify integration & maintenance

- > Standard fieldbus interface CANopen / CANmotion
- > Pulse-train-input (PTI) and Pulse-train-output (PTO) interfaces
- Digital input interface to control simple movements directly by the servo drive: Position sequence mode
- > Analog input interface +/-10 V for speed control mode

General overview

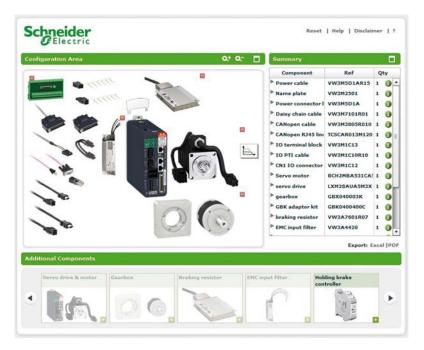
#### Easy to select



Lexium configurator app

#### Online configurator for intuitive product selection

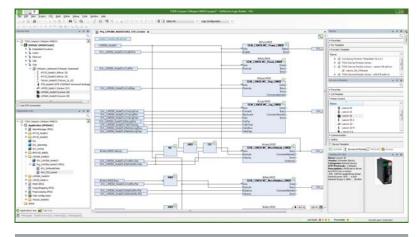
Predefined servo drives and motors bundles include accessories, easy to select because of online configurator... You can get this also as App for mobile devices, see Lexium configurator in App store or Google Play.



#### SoMachine®- One software for commissioning and programming

SoMachine<sup>®</sup> is the universal programming software for machines automated by MachineStruxure controllers. Simple navigation that requires only fewer clicks delivers a more efficient engineering process. The programming, visualization, and commissioning are handled in just one intuitive tool. SoMachine software includes a 21 day free trial. After this period a license is required to continue to benefit from SoMachine. It can be installed from a DVD.

Please consult our catalog "SoMachine configuration software" or on our web site www.schneider-electric.com



#### SoMove Setup software

In addition to SoMachine the SoMove Setup software can be used for the commissioning of Lexium 28. This could be done in just the same way as it is on other Schneider Electric drives and starters, to configure, adjust, debug, and maintain the drive.

## Intuitive commissioning & programming



SoMachine configuration software



### Lexium 28 motion control General overview

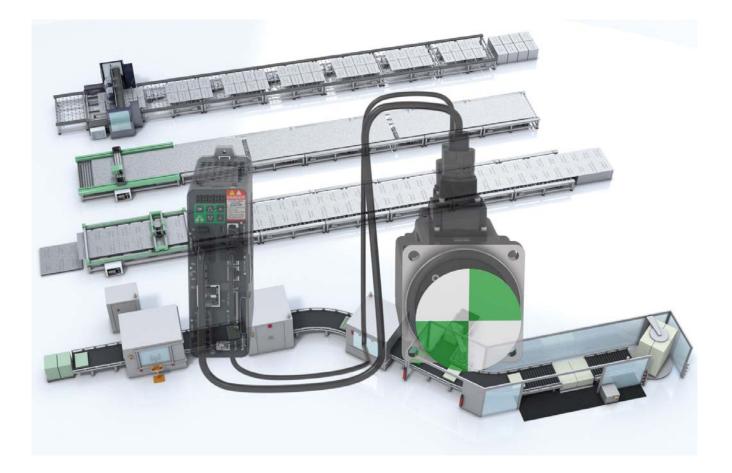
## Achieve benchmark performance

while increasing profitability

Lexium 28 and Lexium BCH2,

the optimized servo bundle for motion control solutions

- > Cost effective
- > Energy efficient
- > Embedded safety



## Make the most of your energy<sup>SM</sup>

Schneider Blectric

Servo drives and servo motors



Material working application



Material handling application



Packaging applicatio



Textile application





Multi-loader tool

SoMove Setup software

#### Presentation

- The Lexium 28 range is defined by AC-servo drives LXM28 for combination with AC-servo motors BCH2.
- The Lexium 28 range offers predeterminated combinations to suit the requirements of motion control applications, and optimize installation's performance.
   The combinations of servo motors with servo drives are based on the power
- class: both servo motor and servo drive have the same power class.

□ The bundle of a servo drive with its related servo motor is designed to cover a nominal power from 0.05 kW up to 4.5 kW (0.067 up to 6.03 hp) with 200..240 V mains supply voltage

- The Lexium 28 servo drives are delivered without EMC filter, the EMC immunity is reached with additional EMC filter.
- The Lexium 28 servo drives have degree of protection IP 20.

■ BCH2 motors provide a nominal torque from 0.16 Nm to 28.6 Nm and a nominal speed of from 1,500 to 3,000 rpm, depending on the model. They are suitable for a wide variety of applications due to the different levels of motor inertia offered.

#### **Compact range**

The compact dimensions of Lexium 28 servo drives mean they fit very easily into small spaces, thus reducing the size of the installation and the cost of the equipment.

#### Applications

- Material working (multi-axis machines, cutting machines, etc.)
- Material handling (conveying, palletizers, warehousing, etc.)
- Assembly line (clamping, etc.)
- Packaging
- Printing
- Winding and unwinding

#### SoMove Setup software

SoMove Setup software is used for commissioning, parameter setting, diagnostics and maintenance.

- The drives can be configured
- via their integrated HMI interface
- □ using the SoMove Setup software.

It can also be used for fast device replacement in existing machine installations. SoMove Setup software is used in just the same way as it is on other Schneider Electric drives, for configuring and optimizing control loops in automatic or manual mode using the Oscilloscope function and for maintenance of the Lexium 28 drive. See page 62323/10.

#### Multi-loader tool

The Multi-loader tool enables configurations to be copied from a PC or a servo drive and loaded onto another servo drive. The servo drives do not need to be powered-up (see page 62323/10).

#### Flexibility

Lexium 28 servo drives have digital and analog I/O as standard, an interface for CANopen/CANmotion fieldbus and an encoder interface for BCH2 servo motors. The servo drives incorporate numerous functions, including auto-tuning, position, speed, torque control, and the position sequence mode.

This open communication concept enables integration into numerous different control system architectures.

#### Mounting and maintenance

Connecting the servo drives is simplified by identified plug-in connectors, which are easily accessed, mainly on the front panel and also on top of the drive (see Description page 62323/9).

Schneider

Presentation

## Lexium 28 motion control

Servo drives and servo motors

#### Main functions of Lexium 28 servo drives

 Automatic motor identification by the servo drive: the technical data related to the motor is provided from the motor to the drive via the encoder connection cable.

Filtering: Anti-vibration function for suppression of resonance frequencies of the

- power train connected with the moving mass of the application
- Monitoring functions:
- Status monitoring, I/O monitoring □ Log function to memorize alarm and warning messages (in the drive)
- Reset function of alarms and warnings
- Monitoring of drive variables related to motor control and closed loop control

#### Additional main functions of Lexium 28 servo drives

- Movement control with digital input interface directly in the servo drive:
- □ Relative or absolute positioning mode
- Velocity mode
- Torque control mode

Position sequence mode: a sequence of up to 32 movements, controlled by a 

digital input interface

#### Control via I/O interface or CANopen/CANmotion fieldbus

The Lexium 28 servo drive is controlled through "CN4 CAN" interface with a CANopen/CANmotion fieldbus control interface.

It can also be controlled through numerous digital and analog signals, accessible by "CN1 I/O" interface:

- 2 digital inputs for high performance position capture
- □ 8 digital inputs
- □ 5 digital outputs
- 2 analog inputs
- 2 analog outputs

□ 1 digital input for the safety function "Safe-Torque-Off"

#### Drive functions activated by commissioning software or directly by the HMI interface

Jog mode: Velocity movement 

"Easy tuning" one-button tuning mode: this function is used to optimize application performance.

2 additional tuning functions, which can be activated by the SoMove Setup commissioning software or by the HMI interface:

 "Comfort tuning" with predefined settings for different mechanical systems such as spindle axes (e.g. portal axes), transportation belt, vertical axes (e.g. cantilever axes)

□ "Auto-adaptive tuning"

#### Operating modes for the Lexium 28 via PTI / PTO interface

Lexium 28 drives movement can be managed by a machine controller (Modicon M221 logic controller) with pulse-train-output (PTO) interface or the PTO interface from another (Lexium28) servo drive.

The corresponding pulse-train-input (PTI) of the Lexium 28 drive is then electrically connected to CN1 I/O interface.

#### Operating modes for the Lexium 28 via the CANopen and CANmotion fieldbus

The following operating modes are available:

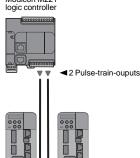
- Homing (in accordance with functional profile CiA DSP 402)
  - Point-to-point mode (in accordance with functional profile CiA DSP 402)
- Position gear mode
- Cyclic synchronous position mode, cyclic synchronous velocity mode, cyclic synchronous torque mode (with CANmotion interface)

For more details of each integrated function, please consult our web site: www. schneider-electric.com.

#### **Embedded safety function STO**

The Lexium 28 range of servo drives is an integral part of the MachineStruxure™ safety system "Preventa solutions for efficient machine safety" with its drive embedded Safe-Torque-Off (STO) function.

This STO function meets the requirements of SIL 2 according IEC 61800-5-2 / IEC62061 / IEC 61508 as well as up to category 3 and PL d according to EN ISO 13849-1. It simplifies the setup of installations requiring complex safety equipment and improves performance during maintenance operations.



Modicon M221

Lexium 28 Lexium 28

Example of architecture with control by Modicon M221 logic controller



Lexium 28

Example of a Lexium28 drive controlling another Lexium 28 drive with PTO/PTI interface



Guard monitoring safety function held by Lexium 28. More details on our web site: www.schneider-electric.com > Solutions > Process Systems, Machine Control > Machine Safety

### Combinations

Available

hp

power

output

kW

Nominal

speed of

rotation

rpm

## Lexium 28 motion control

Servo drive

BCH2 servo motor/Lexium 28 servo drive combinations

ft lbf Nm

Maximum

peak torque

ft lbf

Nominal

torque

Nm

Single-phase supply voltage: 200/240 VAC

Combinations: Lexium 28 servo drive and BCH2 servo motor

Servo motor

Inertia

(without

holding

brake)

kgcm<sup>2</sup>

Motor

inertia

type



Lexium 28 50 W, 100 W, 200 W, 400 W and 750 W



Lexium 28 1 kW and 1.5 kW



Lexium 28 2 kW



4.5

6.03

1,500

Sing	jie-pna	se supply v	oitage:	200/24	U VAC					
0.05	0.067	3,000	0.16	0.11	0.48	0.35	LXM28AUA5M3X	BCH2MBA53•C•5C	0.054	Medium
0.1	0.13	3,000	0.32	0.23	0.96	0.70	LXM28AU01M3X	BCH2MB013•C•5C	0.075	Medium
0.2	0.26	3,000	0.64	0.47	1.92	1.41	LXM28AU02M3X	BCH2LD023•C•5C	0.16	Low
0.3	0.41	1,000	2.86	2.10	8.59	6.33	LXM28AU04M3X	BCH2MM031eCe6C	6.63	Medium
0.4	0.53	3,000	1.27	0.93	3.81	2.81	LXM28AU04M3X	BCH2LD043•C•5C	0.27	Low
0.4	0.53	3,000	1.27	0.93	3.81	2.81	LXM28AU04M3X	BCH2LF043•C•5C	0.67	Low
0.5	0.67	2,000	2.39	1.76	7.16	5.28	LXM28AU07M3X	BCH2MM052eCe6C	6.63	Medium
0.6	0.80	1,000	5.73	4.22	17.19	12.67	LXM28AU07M3X	BCH2MM061•C•6C	6.63	Medium
0.75	1.00	3,000	2.39	1.76	7.16	5.28	LXM28AU07M3X	BCH2HF073•C•5C	1.54	High
0.75	1.00	3,000	2.39	1.76	7.16	5.28	LXM28AU07M3X	BCH2LF073•C•5C	1.19	Low
0.85	1.13	1,500	5.39	3.97	13.8	10.17	LXM28AU10M3X	BCH2MM081eCe6C	13.5	Medium
0.9	1.21	1,000	8.59	6.33	25.77	19.01	LXM28AU10M3X	BCH2MM091•C•6C	9.7	Medium
1	1.34	3,000	3.18	2.34	9.54	7.03	LXM28AU10M3X	BCH2LH103•C•6C	2.4	Low
1	1.34	2,000	4.77	3.51	14.3	10.54	LXM28AU10M3X	BCH2MM102•C•6C	6.63	Medium
1.5	2.01	2,000	7.16	5.28	21.48	15.84	LXM28AU15M3X	BCH2MM152eCe6C	9.7	Medium
3 ph	ase su	pply voltage	e: 200/2	40 VAC	)					
0.05	0.067	3,000	0.16	0.11	0.48	0.35	LXM28AUA5M3X	BCH2MBA53•C•5C	0.054	Medium
0.1	0.13	3,000	0.32	0.23	0.96	0.70	LXM28AU01M3X	BCH2MB013eCe5C	0.075	Medium
0.2	0.26	3,000	0.64	0.47	1.92	1.41	LXM28AU02M3X	BCH2LD023•C•5C	0.16	Low
0.3	0.41	1,000	2.86	2.10	8.59	6.33	LXM28AU04M3X	BCH2MM031eCe6C	6.63	Medium
0.4	0.53	3,000	1.27	0.93	3.81	2.81	LXM28AU04M3X	BCH2LD043•C•5C	0.27	Low
0.4	0.53	3,000	1.27	0.93	3.81	2.81	LXM28AU04M3X	BCH2LF043•C•5C	0.67	Low
0.5	0.67	2,000	2.39	1.76	7.16	5.28	LXM28AU07M3X	BCH2MM052eCe6C	6.63	Medium
0.6	0.80	1,000	5.73	4.22	17.19	12.67	LXM28AU07M3X	BCH2MM061eCe6C	6.63	Medium
0.75	1.00	3,000	2.39	1.76	7.16	5.28	LXM28AU07M3X	BCH2HF073•C•5C	1.54	High
0.75	1.00	3,000	2.39	1.76	7.16	5.28	LXM28AU07M3X	BCH2LF073•C•5C	1.19	Low
0.85	1.13	1,500	5.39	3.97	13.8	10.17	LXM28AU10M3X	BCH2MM081eCe6C	13.5	Medium
0.9	1.21	1,000	8.59	6.33	25.77	19.01	LXM28AU10M3X	BCH2MM091•C•6C	9.7	Medium
1	1.34	3,000	3.18	2.34	9.54	7.03	LXM28AU10M3X	BCH2LH103•C•6C	2.4	Low
1	1.34	2,000	4.77	3.51	14.3	10.54	LXM28AU10M3X	BCH2MM102eCe6C	6.63	Medium
1.5	2.01	2,000	7.16	5.28	21.48	15.84	LXM28AU15M3X	BCH2MM152eCe6C	9.7	Medium
2.0	2.68	3,000	6.37	4.69	19.1	14.08	LXM28AU20M3X	BCH2LH203•C•6C	4.28	Low
2.0	2.68	2,000	9.55	7.04	28.65	21.13	LXM28AU20M3X	BCH2MM202eCe6C	13.5	Medium
2.0	2.68	2,000	9.55	7.04	28.65	21.13	LXM28AU20M3X	BCH2MR202•C•6C	26.5	Medium
3.0	4.02	1,500	19.1	14.08	57.29	42.25	LXM28AU30M3X	BCH2MR301•C•6C	53.56	Medium
3.0	4.02	2,000	14.32	10.56	42.97	31.69	LXM28AU30M3X	BCH2MR302•C•6C	53.56	Medium
3.5	4.69	2,000	16.7	12.31	50.3	37.09	LXM28AU45M3X	BCH2MR352•C•6C	53.56	Medium

28.65 21.13 71.62 52.82 LXM28AU45M3X

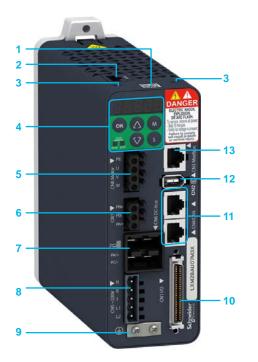
Lexium 28 3 kW and 4.5 kW Medium

BCH2MR451•C•6C 73.32

### Description, references, dimensions, weight

## Lexium 28 motion control

Lexium 28 servo drive



#### Lexium 28 servo drive

Description

#### On the drive top side:

- 1 QR code for access to detailed technical data, wiring guide, and installation guide
- 2 Removable terminal (1) for STO function (marked CN9)
- 3 Slot for application name plate

#### On the drive front side:

- 4 HMI interface, 7-segment display, 5 buttons (OK, mode, set, value up, value down) and servo drive status LED
- 5 Removable terminal (1) for motor connection (marked CN8 Motor)
- 6 Removable terminal (1) for braking resistor connection (marked CN7)
- 7 DC-bus connector with status LED "DC-bus charged" (marked CN6 DC-bus)
- 8 Removable terminal (1), 5 terminals (R, S, T, L1, L2) for connecting the 220 V  $\sim$  power supply (marked CN5  $\sim$  220 V)
- 9 Protected earth connector (marked =)
- 10 Input/output interface connector (marked CN1 I/O)
- 11 2x RJ 45 connectors for CANopen/CANmotion fieldbus connection (marked CN4 CAN)
- 12 Connector for motor encoder: 20-bit single-turn absolute encoder, type ServoSense R (marked CN2 <sup>©</sup>)
- 13 RJ 45 connector for Modbus serial link (marked CN3 Modbus)

(1) Removable spring terminals are supplied with each Lexium 28 servo drive.

Reference	53												
To order a	a Lexium 28 servo drive	e, ma	ake	up t	he r	efer	enc	e as	foll	ows	S:		
Example		L	Х	М	2	8	Α	U	Α	5	М	3	Х
Lexium 28 A	C servo drive	L	Х	Μ	2	8							
Interface	CANopen and CANmoti	on fi	eldbu	JS			Α						
Power	50 W (0.067 hp)							U	Α	5			
	100 W (0.13 hp)							U	0	1			
	200 W (0.26 hp)								0	2			
	400 W (0.53 hp)							U	0	4			
	750 W (1.00 hp)							U	0	7			
	1 kW (1.34 hp)					U	1	0					
	1.5 kW (2.01 hp)							U	1	5			
	2 kW (2.68 hp)							U	2	0			
	3 kW <i>(4.02 hp)</i>					U	3	0					
	4.5 kW (6.03 hp)							U	4	5			
Supply volta	age 200240 V ~, no EMC	filte	r								м	3	x

#### Dimensions and weight

	Dimensions (overall)	)	Weight				
Servo drives	Width x Height x De	pth (W x H x D)					
	mm in.		kg	lb			
LXM28AUA5M3X LXM28AU01M3X LXM28AU02M3X LXM28AU04M3X LXM28AU07M3X	55 x 150 x 146	2.17 x 5.91 x 5.75	1.000	2.190			
LXM28AU10M3X LXM28AU15M3X	55 x 150 x 170	2.17 x 5.91 x 6.69	1.200	2.630			
LXM28AU20M3X	62 x 170 x 184	2.44 x 6.69 x 7.24	1.700	3.720			
LXM28AU30M3X LXM28AU45M3X	116 x 234 x 186	4.56 x 9.21 x 7.32	3.200	7.010			

# Presentation, references

## Lexium 28 motion control

Lexium 28 servo drive Configuration tools



TCSMCNAM3M002F

Configuration with the SoMove Setup software

13M002P

#### SoMove Setup software Presentation

SoMove Setup software is used on Lexium 28 servo drives in just the same way as it is on other Schneider Electric drives and starters, to configure, adjust, debug, and maintain the drive.

The configuration of Lexium 28 servo drives can be done using the USB/RJ 45 cordset TCSMCNAM3M002P (used between the PC and the Lexium 28, on CN3 interface).

SoMove Setup software can be downloaded from our web site: www.schneiderelectric.com

More information: see catalog "SoMove Setup software" (DIA2ED2140801EN) on our web site: www.schneider-electric.com

References			
Designation	Description	Reference	Weight kg/lb
USB/RJ 45 cordset	<ul> <li>For connecting a PC to the device (Lexium 28)</li> <li>Length: 2.5 m (8.2 ft.)</li> <li>Equipped with a USB connector (PC end), and an RJ 45 connector (Device end)</li> </ul>	TCSMCNAM3M002P	0.160 / <i>0,3</i> 53



Configuration of a Lexium 28 in its packaging with the VW3A8121 Multi-loader tool + VW3A8126 cordset



#### **Multi-loader configuration tool**

#### Presentation

The Multi-loader tool enables several configurations to be copied from a PC or a Lexium 28 servo drive and loaded onto another servo drive. The Lexium 28 servo drives do not need to be powered up.

References			
Designation	Description	Reference	Weight kg/ <i>lb</i>
Multi-loader configuration tool	Supplied with: 1 cordset equipped with two RJ 45 connectors 1 cordset equipped with one type A USB connector and one mini B USB connector 1 x 2 GB SD memory card 1 x female/female RJ 45 adapter 4 AA 1.5 V LR6 round batteries	VW3A8121	0.910/ 2.006
Cordset for multi- loader tool	For connecting the multi-loader tool to the Lexium 28 servo drive in its packaging. Equipped with: □ A non-locking RJ 45 connector with special mechanical catch on the drive end □ An RJ 45 connector on the Multi-loader end	VW3A8126	0.065/ 0.143

### References

## Lexium 28 motion control

Lexium 28 servo drive Connection accessories, Accessories







VW3M4C22





VW3M1C13







Servo drive with application name plate VW3M2501

#### Connection accessories

Cordsets					
Designation	Use	Description	Length m/ <i>ft</i>	Unit reference	Weight kg/lb
Daisy chain connection of the DC-bus (sold in lots of 5)	Between LXM28AeeeeM3X and LXM28AeeeeM3X drives	Equipped with 2 connectors	0.1/0.33	VW3M7101R01	0.150/ <i>0.220</i>
Cable					
Designation	Use	Description	Length m/ <i>ft</i>	Reference	Weight kg/lb
Shielded cable for Daisy chain connection of the DC-bus	Between LXM28A••••M3X and LXM28A••••M3X drives	This cable can be used with DC-bus connector kit VW3M2207	15 <i>  4</i> 9.21	VW3M7102R150	3.650/ <i>8.047</i>

Connectors				
Designation	Use	Description	Unit reference	Weight kg/lb
DC-bus connector kit	Lexium 28	10 connectors for creating extension cordsets for the CN6 DC-bus interface	VW3M2207	0.050/ <i>0.110</i>
Replacement connector sets	50 W (0.067 hp), 100 W (0.13 hp), 200 W (0.26 hp), 400 W (0.53 hp), 750 W (1.00 hp), 1 kW (1.34 hp), and 1.5 kW (2.01 hp) drives (sold in lots of 3)	3 connectors: 1 for CN5, 1 for CN7, and 1 for CN8 interfaces	VW3M4C21	0.100/ 0.220
	2 kW (2.68 hp), 3 kW (4.02 hp), and 4.5 kW (6.03 hp) drives (sold in lots of 2)	3 connectors: 1 for CN5, 1 for CN7, and 1 for CN8 interfaces	VW3M4C22	0.100/ 0.220
I/O connector (sold in lots of 3)	Lexium 28	SUB-D 50-pin connector for CN1 I/O interface	VW3M1C12	0.100/ 0.220
I/O terminal block module	Lexium 28	Terminal block + Cordset Composed with 2x SUB-D 50-pin connectors type VW3M1C12, and one 0.5 m /1.640 ft. cable, for CN1 I/O interface connection	VW3M1C13	0.380/ 0.838
I/O PTI connection	on cordsets			
Description		Length m/ft	Reference	Weight kg/lb
	SUB-D 50-pin connector N1 interface (drive side),	1/3.28	VW3M1C10R10	0.100/ <i>0.220</i>
(item 1)		2/6.56	VW3M1C10R20	0.200/ <i>0.441</i>
		3/9.84	VW3M1C10R30	0.300/ <i>0.661</i>
STO connection	cordsets			
	Molex 4-pin connector for interface (drive side), and r side)	1/3.28	VW3M1C20R10	0.100/ <i>0.220</i>
(item 2)	·•/	2/6.56	VW3M1C20R20	0.200/ <i>0.441</i>
		3/9.84	VW3M1C20R30	0.300/ <i>0.661</i>
Accessories				

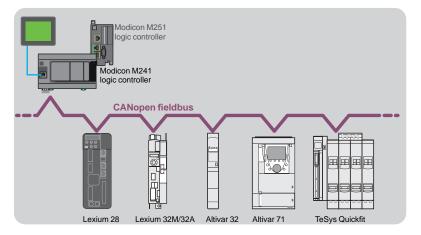
Accessories				
Designation	Use	Dimensions mm <i>lin.</i>	Unit reference	Weight kg/ <i>lb</i>
Application name plate (sold in lots of 50)	This contains information about the servo drive. To be inserted onto a dedicated slot on the top of the servo drive	38.5 x 13 / 1.516 x 0.512	VW3M2501	0.100/ <i>0.220</i>

Lexium 28 servo drive Communication on CANopen/CANmotion fieldbus

#### CANopen and CANmotion fieldbus

#### Presentation

Lexium 28 servo drives integrate the CANopen communication protocol as standard.



The CANopen fieldbus is specifically designed for integration in control system architectures. It provides openness and interoperability for various devices (drives, motor starters, smart sensors, etc.).

A tiered CANopen connectivity solution reduces costs and optimizes the creation of the control system architecture, providing:

- Reduced cabling time
- Greater reliability of the load
- Flexibility should you need to add or remove equipment
- This facilitates the set up.

#### Connection

Lexium 28 servo drives are connected to CANopen/CANmotion fieldbus via 2 RJ 45 connectors, providing an optimized solution for daisy chain connection to the CANopen fieldbus.

The same communication port provides access to either the CANopen or CANmotion fieldbus.

 2x RJ 45 connectors, marked CN4 CAN



References

## Lexium 28 motion control

Lexium 28 servo drive Communication on CANopen/CANmotion fieldbus

#### CANopen/CANmotion fieldbus for Lexium 28 servo drives

Lexium 28 servo drives can be directly connected to CANopen/CANmotion fieldbus using the RJ 45 connectors.

The communication function provides access to the servo drive's configuration, adjustment, control, and monitoring functions.

To simplify daisy chain connection, each servo drive is equipped with two RJ 45 connectors (marked CN4 CAN).

Cordsets and cables (1)				
Description	Item	Length	Reference	Weight
	no.	m/ft		kg/ <i>lb</i>
<b>CANopen cordsets</b> (1) Equipped with 2 RJ 45	1	0.3/ 0.98	VW3CANCARR03	0.320/ <i>0.705</i>
connectors		1/ 3.28	VW3CANCARR1	0.500/ 1.102
<b>CANopen cordsets</b> (1) Equipped with one 9-way female		1/ 3.28	VW3M3805R010	0.080/ <i>0.176</i>
SUB-D connector with integrated line terminator and one RJ 45 connector		3/ 9.843	VW3M3805R030	0.139/ <i>0.306</i>
<b>CANopen cables</b> (1) Standard cables,	3	50/ 164.04	TSXCANCA50	4.930/ 10.869
C€ marking, Low smoke, zero halogen, Flame retardant (IEC 60332-1)		100/ 328.08	TSXCANCA100	8.800/ 19.401
Flame relardant (IEC 60332-1)		300/ 984.25	TSXCANCA300	24.560/ 54.145
<b>CANopen cables</b> (1) UL certification, C€ marking,	3	50/ 164.04	TSXCANCB50	3.580/ 7.893
Flame retardant (IEC 60332-2)		100/ 328.08	TSXCANCB100	7.840/ 17.284
		300/ 984.25	TSXCANCB300	21.870/ <i>4</i> 8.215
<b>CANopen cables</b> (1) Cables for harsh environments	3	50/ 164.04	TSXCANCD50	3.510/ 7.738
(2) or mobile installation,		100/ 328.08	TSXCANCD100	7.770/ 17.130
C€ marking, Low smoke, zero halogen, Flame retardant (IEC 60332-1)		300/ 984.25	TSXCANCD300	21.700/ 47.840
Connection accessories (	1)			
Description	ltem no.	Use	Reference	Weight kg/ <i>lb</i>
CANopon line terminator for	4	Lovium28	TCSCAP012M120	0.000/

CANopen line terminator for 4 Lexium28 TCSCAR013M120 0.009/ RJ 45 connector 0.020

120 Ω

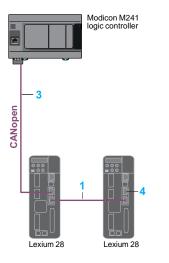
(1) For other CANopen fieldbus connection accessories, please consult our web site: www. schneider-electric.com

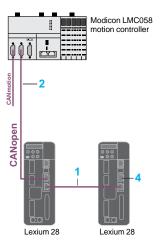
(2) Harsh environment:

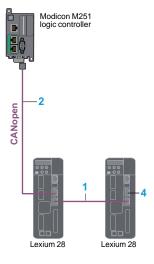
- Resistance to hydrocarbons, industrial oils, detergents, solder splashes - Relative humidity up to 100%

- Saline atmosphere

- Significant temperature variations - Operating temperature between - 10 °C/+ 14 °F and + 70 °C/+ 158 °F







Example of architectures with control by Modicon M241/M251 logic controllers or LMC058 motion controller

# Presentation, references

### Lexium 28 motion control Lexium 28 servo drive

Options: braking resistors for servo drives

#### Options: braking resistors for servo drives Presentation

#### Internal braking resistor

A braking resistor is built into the servo drive to absorb the braking energy. If the DC-bus voltage in the servo drive exceeds a specified value, this braking resistor is activated. The restored energy is converted into heat by the braking resistor. It enables maximum transient braking torque.

#### External braking resistor

When the servo motor has to be braked frequently, an external braking resistor is required to dissipate the excess braking energy. In this case, the internal braking resistor must be deactivated.

Several external braking resistors can be connected in parallel. The servo drive monitors the power dissipated in the braking resistor.

The casing degree of protection is IP 65 for VW3A7601R•• to VW3A7607R•• braking resistors and IP 20 for VW3A770• braking resistors.

The operating temperature around the unit can be between 0 and + 50 °C (+ 32 and + 122 °F).

To optimize the size of the braking resistor, the DC-buses on Lexium 28 servo drives in the same installation can be connected in parallel.

#### Applications:

Machines with high inertia, driving loads, and machines with fast cycles.

References							
External bra	iking r	esistor					
Ohmic value		inuous	Peak energy			Reference	Weight
0	powe		230 V		ection cable	•	less (1)
Ω	W	hp	Ws	m	ft	1440 A 700 ( D 07	kg/lb
10	400	0.53	13,300	0.75	2.46	VW3A7601R07	1.420/ <i>3.131</i>
				2	6.56	VW3A7601R20	1.470/ 3.241
				3	9.84	VW3A7601R30	1.620/ <i>3.571</i>
10	1,000	1.34	36,500	-	-	VW3A7705	11.000/ <i>24.251</i>
15	1,000	1.34	43,100	-	-	VW3A7704	11.000/ <i>24.251</i>
27	100	0.13	3,800	0.75	2.46	VW3A7602R07	0.630/ 1.389
				2	6.56	VW3A7602R20	0.780/ 1.720
				3	9.84	VW3A7602R30	0.900/ 1.984
	200	0.26	7,400	0.75	2.46	VW3A7603R07	0.930/ 2.050
				2	6.56	VW3A7603R20	1.080/ 2.381
				3	9.84	VW3A7603R30	1.200/ 2.646
	400	0.53	18,100	0.75	2.46	VW3A7604R07	1.420/ 3.131
				2	6.56	VW3A7604R20	1.470/ 3.241
				3	9.84	VW3A7604R30	1.620/ 3.571
72	200	0.26	9,600	0.75	2.46	VW3A7606R07	0.930/ 2.050
				2	6.56	VW3A7606R20	1.080/ <i>2.381</i>
				3	9.84	VW3A7606R30	1.200/ <i>2.64</i> 6
	400	0.53	24,700	0.75	2.46	VW3A7607R07	1.420/ 3.131
				2	6.56	VW3A7607R20	1.470/ 3.241
				3	9.84	VW3A7607R30	1.620/ 3.571

**Note**: The total continuous power dissipated in the external braking resistor(s) must be less than or equal to the nominal power of the Lexium 28 servo drive.



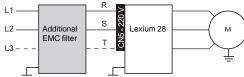
VW3A760∙R∙∙



VW3A770•

Schneider Belectric

Lexium 28 servo drive Additional EMC input filters for servo drives



Lexium 28 servo drive with additional EMC filter



VW3A4420 EMC filter and Lexium 28 servo drive



Additional EMC input filters for servo drives Presentation

Lexium 28 servo drives require external input filters to comply with the EMC standard for variable speed electrical power drive "products" IEC/EN 61800-3, edition 2, category C3 in environment 2, and to comply with the European directive on EMC (electromagnetic compatibility).

#### Applications

Additional EMC filters are mounted next to the device. They have tapped holes for mounting in an enclosure.

The maximum servo motor cable length conforming to IEC/EN 61800-3 category C3 (1) in environment 2 is 20 m (65.62 ft).

#### Use according to the type of line supply

Integrated or additional EMC filters can only be used on TN (neutral connection) or TT (neutral to ground) systems.

Lexium 28 servo drives cannot be used on IT (impedance grounded or isolated neutral) systems. Standard IEC/EN 61800-3, appendix D2.1, states that on IT systems, filters can cause permanent insulation monitors to operate in a random manner.

If a machine has to be installed on an IT system, an isolation transformer must be inserted in order to re-create a TT system on the secondary side.

References				
Designation	Max. nominal power Combination	Line current (A)	Reference	Weight kg/ <i>lb</i>
Single-phase supply	voltage			
Additional EMC input filters for Lexium 28 servo drives	<b>50 W to 750 W</b> (0.067 to 1.00 hp) <b>servo</b> <b>drives</b> 1x EMC filter and a single Lexium 28 servo drive	9	VW3A4420	0.600/ 1.323
	1 kW and 1.5 kW (1.34 hp and 2.01 hp) servo drives 1x EMC filter and a single Lexium 28 servo drive	16	VW3A4421	0.775/ 1.709
	7.5 kW max (10.05 hp max) servo drives 1x common EMC filter and several Lexium 28 servo drives	24	VW3A4426	1.130/ 2.491
Three-phase supply v	oltage			
Additional EMC input filters for Lexium 28 servo drives	50 W to 1.5 kW (0.067 hp to 2.01 hp), 2kW (2.68 hp), and 3kW (4.02 hp) servo drives 1x EMC filter and a single Lexium 28 servo drive	15	VW3A4422	0.900/ 1.984
	<b>4.5 kW</b> (6.03 hp) <b>servo drives</b> 1x EMC filter and a single Lexium 28 servo drive	25	VW3A4423	1.350/ 2.976
	Up to 10 kW (up to 13.40 hp) servo drives 1x common EMC filter and several Lexium 28 servo drives	47	VW3A4424	3.150/ 6.945

(1) Standard IEC/EN 61800-3: EMC immunity and conducted and radiated EMC emissions: - Category C3 in environment 2: industrial premises.

### Combinations

## Lexium 28 motion control

Motor starters Protection using fuses



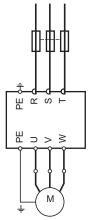








LXM28AU••M3X



Lexium 28 servo drive, BCH2 servo motor with fuse protection

#### **Motor starters**

Presentation

The combinations listed below can be used to create a complete motor starter unit comprising a circuit breaker, a contactor, and a Lexium 28 servo drive.

■ GV2P circuit-breaker provides protection against accidental short-circuits, disconnection and, if necessary, isolation.

LC1 contactor turns on and manages any safety functions, as well as isolating the servo motor on stopping.

 Lexium 28 servo drive controls the servo motor, provides protection against short-circuits between the servo drive and the servo motor, and protects the motor cable against overloads. Overload protection is provided by the servo drive's motor thermal protection.

Combinations						
Servo drive				Circuit-brea	<b>ker</b> (1)	Contactor
Reference	Nom pow		Mains number	Reference	Rating	<b>Reference</b> (2) (3)
	kW	hp	of phases		Α	
Mains supply vol	tage:	2002	40 V $\sim$ 50/60H	z		
LXM28AUA5M3X	0.05	0.067	1 or 3 phases	GV2P14	10	LC1K0610.
LXM28AU01M3X	0.1	0.13	1 or 3 phases	GV2P14	10	LC1K0610.
LXM28AU02M3X	0.2	0.26	1 or 3 phases	GV2P14	10	LC1K0610.
LXM28AU04M3X	0.4	0.53	1 or 3 phases	GV2P14	10	LC1K09●●
LXM28AU07M3X	0.75	1.00	1 or 3 phases	GV2P14	10	LC1K09●●
LXM28AU10M3X	1	1.34	1 or 3 phases	GV2P14	10	LC1K1200
LXM28AU15M3X	1.5	2.01	1 or 3 phases	GV2P16	14	LC1D18●●
LXM28AU20M3X	2	2.68	3 phases	GV2P20	18	LC1D3200
LXM28AU30M3X	3	4.02	3 phases	GV2P20	18	LC1D3200
LXM28AU45M3X	4.5	6.03	3 phases	GV2P21	23	LC1D65●●

(1) Circuit-breakers for single drive installation according to IEC 60364-5-52

(2) Composition of the contactors:

LC1 K06: 3 poles + 1 N/O auxiliary contact

LC1 Dee: 3 poles + 1 N/O auxiliary contact + 1 N/C auxiliary contact

(3) Replace •• with the control circuit voltage reference given in the table below:

	50/60 Hz	M7	P7	U7
	60 Hz	M6	-	U6
LC1D	50 Hz	M5	P5	U5
	Volts $\sim$	220/230	230	230/240
LC1K	50/60 Hz	M7	P7	U7
	Volts $\sim$	220	230	240
		0		

For other available voltages between 24 V and 660 V, or a DC control circuit, please contact our Customer Care Centre.

Please refer to the "Control and protection components" catalog or consult our web site: www. schneider-electric com

Protection using class J fuses (UL certification)											
Servo drive			Fuse to be placed upstream								
Reference	Nomi	nal power (kW/ <i>hp</i> )	(A)								
Mains supply voltage: 200.	Mains supply voltage: 200240 V $\sim$ 50/60Hz										
LXM28AUA5M3X	0.05	0.067	5								
LXM28AU01M3X	0.1	0.13	5								
LXM28AU02M3X	0.2	0.26	5								
LXM28AU04M3X	0.4	0.53	20								
LXM28AU07M3X	0.75	1.00	20								
LXM28AU10M3X	1	1.34	25								
LXM28AU15M3X	1.5	2.01	40								
LXM28AU20M3X	2	2.68	60								
LXM28AU30M3X	3	4.02	80								
LXM28AU45M3X	4.5	6.03	160								

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### Presentation, description

## **Motion control Lexium 28**

BCH2 servo motors



BCH2 with free leads connection



BCH2 servo motor with MIL connectors



#### **BCH2 servo motors**

Presentation

#### BCH2 motors are synchronous AC servo motors.

■ They are equipped as standard with a high resolution (20-bit) single-turn absolute encoder. They are therefore ideal for high performance applications such as material working, machine tools, etc.

BCH2 motors are available in six flange sizes: 40 mm (1.58 in.), 60 mm (2.36 in.),

- 80 mm (3.15 in.), 100 mm (3.94 in.), 130 mm (5.12 in.), and 180 mm (7.08 in.).
- Depending on flange size, the BCH2 motors are supplied with:
  - free leads with connectors
  - or MIL connectors
- BCH2 motors are available with holding brake.

■ With the three available types of motor inertia, ranging from low to high inertia,

- the servo motors can be used in a very wide variety of installations:
  - low inertia: power between 0.2 kW and 1 kW (0.26 hp and 1.34 hp), suitable for textile and packaging applications.
  - medium inertia: power between 0.05 kW and 4.5 kW (0.067 hp and 6.03 hp), suitable for material working and machine tool applications.
  - high inertia: 0.75 kW (1.00 hp) power, suitable for metal working and printing applications.

#### Examples of applications according to motor inertia type:

Type of machine	Inertia						
	Low	Medium	High				
Conveyors							
Packaging machines							
Printers							
Loaders/unloaders							
Presses							
PCB drilling machines							
Electronic card testers	$\mathbf{\nabla}$						
Labelling machines	$\square$						
Knitting and embroidery machines							
Special machines							
Winders/unwinders							

#### Holding brake

BCH2 servo motors can be equipped with an electromagnetic holding brake. Do not use the holding brake as a dynamic brake for deceleration, as this will quickly damage the brake.

#### Integrated encoder

#### BCH2 servo motors are equipped with an absolute encoder.

This encoder performs the following functions:

provides the absolute position of the motor so that flows can be synchronized
 measures the servo motor speed via the associated Lexium 28 servo drive (this information is used by the servo drive's position and speed controller)

□ sends data from the servo motor to the servo drive, which provides automatic identification of the motor when the servo drive starts

This encoder measures the motor angular position with a precision of ± 2.6 arc minutes.

#### Description

BCH2 servo motors, with a 3-phase stator and a rotor with rare earth based permanent magnets, consist of:

- Connector for the power cable
- 2 Connector for the encoder cable
- 3 Casing with RAL 9005 opaque black paint coating
- 4 Smooth or keyed shaft end (depending on the model)
- 5 4-point axial mounting flange (Flange is mechanically compatible for mounting with Asian style servo motors).

Cables and connectors to be ordered separately, for connection to Lexium 28 servo drives. Schneider Electric has taken particular care over the compatibility of BCH2 servo motors and Lexium 28 servo drives. This compatibility is only possible when using cables and connectors sold by Schneider Electric (see page 62323/18).

### References, dimensions

## Lexium 28 motion control

BCH2 servo motors

BCH2 servo moto	3													
References	otor, make up the reference as follow													
Brushless servo motor	tor, make up the reference as follow	из. В	С	н	2	•	•	••	•	•	С	•	•	С
nertia	Low inertia	_			=	L	-							
	Medium inertia					М								
	High inertia					Н								
Flange size	40 mm ( <i>1.58 in.</i> )						в							
- <b>3</b>	60 mm (2.36 in.)						D							
	80 mm ( <i>3.15 in.</i> )						F							
	100 mm ( <i>3.94 in.</i> )						н							
	130 mm ( <i>5.12 in.</i> )						м							
	180 mm (7.08 in.)						R							
Rated output	50 W (0.067 hp)							A5						
•	100 W (0.13 hp)							01						
	200 W (0.26 hp)							02						
	300 W (0.41 hp)							03						
	400 W (0.53 hp)							04						
	500 W (0.67 hp)							05						
	600 W (0.80 hp)							06						
	750 W (1.00 hp)							07						
	850 W (1.13 hp)							08						
	1 kW (1.34 hp)							10						
	1.5 kW (2.01 hp)							15						
	2 kW (2.68 hp)							20						
	3 kW (4.02 hp)							30						
	3.5 kW (4.69 hp)							35						
	4.5 kW (6.03 hp)							45						
Power supply $\sim$ 220 V	1000/1500 rpm								1					
Vinding type	2000 rpm								2					
	3000 rpm								3					
Shaft end	Smooth shaft (shaft IP 54; housing IF	°65)								0				
	Keyed shaft (shaft IP 54; housing IP 6	65)								1				
	Smooth shaft (shaft & housing IP 65)	-								2				
	Keyed shaft (shaft & housing IP 65)									3				
Incoder	High resolution single-turn absolute e	encode	er, 20-bit	resoluti	on						С			
lolding brake	Without brake											Α		
-	With brake (option)											F		
Connections	Free leads with connectors (BCH2•E	8/•D/•I	F motors	only)									5	
	MIL connectors (BCH2+H/+M/+R mo	tors or	nly)										6	
Mechanical motor design	Motor compatible with Asian style mo			de										С

#### **Dimensions and weight**

Dimensions and weigh	Dimensions (overall) Weight										
0		-			,	•					
Servo motor	Pn	Flang	je	Servo motor witho		Servo motor with b		withou	t brake	with brake	
				Width x Height x Depth (W x H x D)		Width x Height x Depth (W x H x D)					
	w	mm	in.	mm	in.	mm	in.	kg	lb	kg	lb
BCH2MBA53•C•5C	50	40	1.57	40 x 58.5 x 82	1.57 x 2.30 x 3.23	40 x 58.5 x 112	1.57 x 2.30 x 4.41	0.400	0.88	0.600	1.32
BCH2MB013eCe5C	100	40	1.57	40 x 58.5 x 100	1.57 x 2.30 x 3.94	40 x 58.5 x 130	1.57 x 2.30 x 5.12	0.560	1.23	0.770	1.70
BCH2LD023eCe5C	200	60	2.36	60 x 78.5 x 104	2.36 x 3.09 x 4.09	60 x 78.5 x 140	2.36 x 3.09 x 5.51	1.020	2.25	1.500	3.31
BCH2LD043eCe5C	400	60	2.36	60 x 78.5 x 129	2.36 x 3.09 x 5.08	60 x 78.5 x 165	2.36 x 3.09 x 6.50	1.450	3.20	2.000	4.41
BCH2LF043•C•5C	400	80	3.15	80 x 98.5 x 112	3.15 x 3.88 x 4.41	80 x 98.5 x 152	3.15 x 3.88 x 4.41	2.000	4.41	2.800	6.17
BCH2HF073eCe5C	750	80	3.15	80 x 98.5 x 138	3.15 x 3.88 x 5.43	80 x 98.5 x 178	3.15 x 3.88 x 7.01	2.900	6.39	3.700	8.16
BCH2LF073•C•5C	750	80	3.15	80 x 98.5 x 138	3.15 x 3.88 x 5.43	80 x 98.5 x 178	3.15 x 3.88 x 7.01	2.800	6.17	3.600	7.94
BCH2LH103eCe6C	1000	100	3.94	100 x 145.6 x 153.5	3.94 x 5.73 x 6.04	100 x 145.6 x 180.5	3.94 x 5.73 x 7.11	4.600	10.14	5.100	11.24
BCH2LH203eCe6C	2000	100	3.94	100 x 145.6 x 198.5	3.94 x 5.73 x 7.81	100 x 145.6 x 225.5	3.94 x 5.73 x 8.88	6.700	14.77	7.200	15.87
BCH2MM031eCe6C	300	130	5.12	130 x 175.6 x 147	5.12 x 6.91 x 5.79	130 x 175.6 x 183	5.12 x 6.91 x 7.20	7.000	15.43	8.200	18.08
BCH2MM052eCe6C	500	130	5.12	130 x 175.6 x 147	5.12 x 6.91 x 5.79	130 x 175.6 x 183	5.12 x 6.91 x 7.20	7.000	15.43	8.200	18.08
BCH2MM061eCe6C	600	130	5.12	130 x 175.6 x 147	5.12 x 6.91 x 5.79	130 x 175.6 x 183	5.12 x 6.91 x 7.20	7.000	15.43	8.200	18.08
BCH2MM081eCe6C	850	130	5.12	130 x 175.6 x 187	5.12 x 6.91 x 7.36	130 x 175.6 x 216	5.12 x 6.91 x 8.50	9.600	21.16	10.900	24.03
BCH2MM091eCe6C	900	130	5.12	130 x 175.6 x 163	5.12 x 6.91 x 6.42	130 x 175.6 x 198	5.12 x 6.91 x 7.80	7.600	16.76	8.800	19.40
BCH2MM102eCe6C	1000	130	5.12	130 x 175.6 x 147	5.12 x 6.91 x 5.79	130 x 175.6 x 183	5.12 x 6.91 x 7.20	7.000	15.43	8.200	18.08
BCH2MM152eCe6C	1500	130	5.12	130 x 175.6 x 167	5.12 x 6.91 x 6.57	130 x 175.6 x 202	5.12 x 6.91 x 7.95	7.600	16.76	8.800	19.40
BCH2MM202eCe6C	2000	130	5.12	130 x 175.6 x 187	5.12 x 6.91 x 7.36	130 x 175.6 x 216	5.12 x 6.91 x 8.50	9.700	21.38	11.000	24.25
BCH2MR202•C•6C	2000	180	7.09	180 x 245.1 x 169	7.09 x 9.65 x 6.65	180 x 245.1 x 203	7.09 x 9.65 x 7.99	13.000	28.66	18.000	39.68
BCH2MR301+C+6C	3000	180	7.09	180 x 245.1 x 202	7.09 x 9.65 x 7.95	180 x 245.1 x 235	7.09 x 9.65 x 9.25	18.500	40.79	23.000	50.71
BCH2MR302•C•6C	3000	180	7.09	180 x 245.1 x 202	7.09 x 9.65 x 7.95	180 x 245.1 x 235	7.09 x 9.65 x 9.25	18.500	40.79	23.000	50.71
BCH2MR352eCe6C	3500	180	7.09	180 x 245.1 x 202	7.09 x 9.65 x 7.95	180 x 245.1 x 235	7.09 x 9.65 x 9.25	18.500	40.79	23.000	50.71
BCH2MR451•C•6C	4500	180	7.09	180 x 245.1 x 235	7.09 x 9.65 x 9.25	180 x 245.1 x 279	7.09 x 9.65 x 10.98	23.640	52.12	28.000	61.73

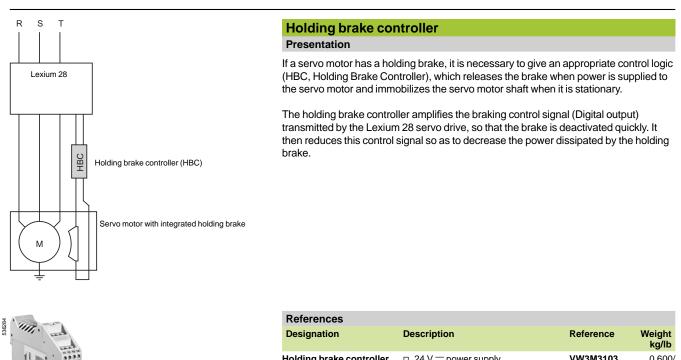


### Presentation, references

## Lexium 28 motion control

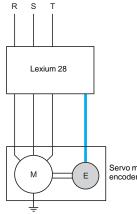
**BCH2** servo motors

Options: Integrated holding brake, Integrated encoder





VW3M3103



 □ 24 V ---- power supply
 □ Max. power 50 W (0.06 hp)
 □ IP 20 Holding brake controller VW3M3103 0.600/ 1.323 □ for mounting on 55 mm (2.17 in) ⊥r rail

#### Integrated encoder in BCH2 servo motors Presentation

The standard measurement device is a 20-bit single-turn absolute encoder integrated in BCH2 servo motors. This measurement device is particularly suited to the Lexium 28 range of servo drives.

- Use of this interface enables:
- Automatic identification of BCH2 servo motor data by the servo drive Automatic initialization of the servo drive control loops, thus simplifying
- installation and drive commissionning at the machine

Servo motor with 20-bit single-turn absolute

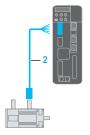


BCH2 servo motors Connection components:

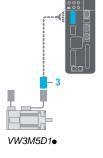
Motor power cordsets, connector kits

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	-1	

VW3M5D1●R●●



*VW3M5D2*● R●● *VW3M5D4*● R●● *VW3M5D6*● R●●



<u>–</u> 4	
VW3M5D2	

<b>Connection compor</b>	nents for BCH2	servo motors			
Power cable type					
Connector	AWG	mm²	Length m/ <i>ft</i>	Reference	Weight kg/lb
Shielded power cordsets	for BCH2 motors	without brake			
Equipped with one quick connector (servo motor	AWG18	4x 0.821.0	1.5 / 4.92	VW3M5D1AR15	0.200/ <i>0.441</i>
side), and open end (servo drive side) (item 1)			3/9.84	VW3M5D1AR30	0.300/ <i>0.661</i>
			5 / 16.40	VW3M5D1AR50	0.450/ <i>0.99</i> 2
Equipped with one MIL connector (servo motor	AWG16	4x 1.31.5	3/9.84	VW3M5D2AR30	0.450/ <i>0.99</i> 2
side), and open end (servo drive side) (item 2)			5/16.40	VW3M5D2AR50	0.700/ 1.543
	AWG12	4x 3.34.0	3/9.84	VW3M5D4AR30	0.750/ 1.653
			5/16.40	VW3M5D4AR50	1.250/ 2.756
	AWG10	4x 6.0	3/9.84	VW3M5D6AR30	2.100/ <i>4.630</i>
			5/16.40	VW3M5D6AR50	3.400/ <i>7.49</i> 6
Shielded power cordsets	for BCH2 motors	with brake			
Equipped with one quick connector (servo motor	AWG18	6x 0.821.0	3/9.84	VW3M5D1FR30	0.300/ <i>0.661</i>
side), and open end (servo drive side) (item 1)			5/16.40	VW3M5D1FR50	0.450/ <i>0.99</i> 2
Equipped with one MIL connector (servo motor	AWG16	6x 1.31.5	3/9.84	VW3M5D2FR30	0.650/ 1.433
side), and a free lead (servo drive side)			5/16.40	VW3M5D2FR50	0.900/ 1.984
(item 2)	AWG12	6x 3.34.0	3/9.84	VW3M5D4FR30	0.950/ 2.094
			5/16.40	VW3M5D4FR50	1.450/ 3.197
	AWG10	6x 6.0	3/9.84	VW3M5D6FR30	3.000/ 6.614
			5/16.40	VW3M5D6FR50	5.000/ 11.023

Motor power connectors	kits		
Description	Use	Unit reference	Weight kg/lb
Motor power connector kits (sold in lots of 3) (item 3)	BCH2•B/•D/•F motors (flange size: 40/60/80 mm) with free leads connection, without brake	VW3M5D1A	0.150/ <i>0.331</i>
	BCH2eB/eD/eF motors (flange size: 40/60/80 mm) with free leads connection, with brake	VW3M5D1F	0.150/ 0.331

Power MIL connector kits VW3M5D2A 0.300/ BCH2•H/•M motors (flange size: 100/130 mm) with or without brake 0.661 (item 4) BCH2•R motors (flange size:180mm) VW3M5D2B 0.300/ with or without brake 0.661

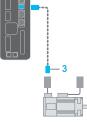
### References (continued), selection

## Lexium 28 motion control

BCH2 servo motors Connection components: Encoder cordsets, connector kits,

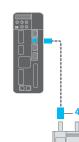
		components fo				
	Description	Use	Composition	Length m/ft	Reference	Weight kg/lb
_2	Shielded encod	ler cordsets				
		For BCH2•B/•D/•F motors,	10x 0.13 mm <sup>2</sup>	1.5 / <i>4.9</i> 2	VW3M8D1AR15	0.500/ 1.102
	ends (item 1)	for connection on CN2 interface		3 / 9.84	VW3M8D1AR30	1.000/ <i>2.205</i>
				5/ 16.40	VW3M8D1AR50	1.200/ <i>2.64</i> 6
•	MIL connector	For BCH2•H/•M/•R, for connection on CN2	10x 0.13 mm <sup>2</sup>	3 / 9.84	VW3M8D2AR30	1.300/ 2.866
	(servo motor side), and a firewire connector (servo drive side) (item 2)	interface		5 / 16.40	VW3M8D2AR50	1.500/ 3.307
	Encoder conne	ctor kits				
	Encoder connector kits	For BCH2•B/•D/•F mod (flange: 40/60/80 mm) with free leads connect (item 3) (sold in lots of	ion		VW3M8D1A	0.150/ <i>0.331</i>
		For BCH2•H/•M/•R m (flange: 100/130/180 m with MIL connector (item 4) (sold in lots o	ım)		VW3M8D2A	0.150/ <i>0.331</i>

<b>Selection of motor</b>	connector k	it, or enco	der connec	tor kit, accor	ding to BCH2	2 motor type	
Motor	Motor power connector k		Encoder connector	Motor power ca	Motor power cable		
	Without brake	With brake	kit	Without brake	With brake		
BCH2MBA53•C•5C							
BCH2MB013•C•5C							
BCH2LD023•C•5C							
BCH2LD043•C•5C	VW3M5D1A	VW3M5D1F	VW3M8D1A	VW3M5D1ARee	VW3M5D1FRee	VW3M8D1ARee	
BCH2LF043•C•5C							
BCH2HF073•C•5C							
BCH2LF073•C•5C							
BCH2LH103•C•6C					VW3M5D2FR●●		
BCH2LH203•C•6C							
BCH2MM081eCe6C							
BCH2MM031eCe6C							
BCH2MM052eCe6C	VW3M5D2A	VW3M5D2A					
BCH2MM061eCe6C	V W SINDDZA	VVV3IVI3DZA		V VV SIVISDZAROO			
BCH2MM102eCe6C							
BCH2MM091•C•6C			VW3M8D2A			VW3M8D2ARee	
BCH2MM152eCe6C							
BCH2MM202eCe6C							
BCH2MR202•C•6C				VW3M5D4AR.	VW3M5D4FRee		
BCH2MR301eCe6C							
BCH2MR302eCe6C	VW3M5D2B	VW3M5D2B			MANEDOED		
BCH2MR352•C•6C				VW3M5D6ARee	VW3M5D6FR●●		
BCH2MR451eCe6C							



VW3M8D1AR.

VW3M8D1A



VW3M8D2A

# Presentation, references

### Lexium 28 motion control BCH2 servo motors

Option: GBX •••••K planetary gearboxes



GBX •••••K planetary gearbox



GBK •••••C adapter kit

#### GBX•••••K planetary gearboxes

#### Presentation

Schneider Electric proposes the use of **GBX** planetary gearboxes with the BCH2 range of servo motors.

Motion control typically requires the use of planetary gearboxes to adapt speeds and torques, while providing the precision demanded by the application.

■ The combination of **BCH2** servo motors with the most suitable **GBX**. planetary gearboxes makes them very easy to mount and set up.

The planetary gearboxes are designed for applications that are not susceptible to mechanical backlash. They have a keyed shaft, are lubricated for life, and conform to IP 54 degree of protection.

- Planetary gearboxes offer is available:
  - in four sizes (40 mm (1.58 in), 60 mm (2.36 in), 80 mm (3.15 in.), and 120 mm (4.72 in.)),
  - offered with ten reduction ratios (3:1, 5:1, 8:1, 10:1, 12:1, 15:1, 20:1, 25:1, 32:1, and 40:1).

The tables on next page shows the most suitable combinations of servo motor and **GBX**••••••K planetary gearbox.

For other combinations or any additional information about planetary gearbox characteristics, refer to the servo motor data sheets or visit our web site: www.schneider-electric.com.

A **GBK**•••••C adapter kit is available for mounting the BCH2 servo motors with GBX040•••K to GBX120•••K planetary gearboxes (see page 62323/23). The adapter kit comprises:

- an adapter plate
- a shaft end adapter, depending on the model (depends on the servo motor/ planetary gearbox combination)
- accessories for mounting the plate on the planetary gearbox
- accessories for mounting the servo motor

Reference	ces		
Size	Reduction ratio	Reference	Weight kg/ <i>lb</i>
GBX040	3:1, 5:1 and 8:1	GBX040●●●K	0.900/ 1.984
GBX60	3:1, 5:1, 8:1 and 10:1	GBX060●●●K	2.100/ <i>4.630</i>
	12:1, 15:1, 20:1, 25:1, 32:1 and 40:1	GBX060●●●K	2.600/ 5.732
GBX80	3:1, 5:1, 8:1 and 10:1	GBX080●●●K	6.000/ 13.228
	12:1, 15:1, 20:1, 25:1, 32:1 and 40:1	GBX080●●●K	8.000/ 17.637
GBX120	3:1, 5:1, 8:1 and 10:1	GBX120●●●K	18.000/ <i>39.6</i> 83
	12:1, 15:1, 20:1, 25:1, 32:1 and 40:1	GBX120●●●K	22.000/ 48.502

### Lexium 28 motion control BCH2 servo motors

Option: GBX •••••K planetary gearboxes

References										
To order a GBX040	•••KGBX120•	●●K plane	etary gear	box, com	olete eacl	n referenc	e as follo	ws:		
					GB	х	•••	•••		κ
Gearbox size	Casing diameter	ameter	40 mi	m ( <i>1.58 in</i> .	)		040			
			60 mi	m (2.36 in.	)		060			
			80 mi	m ( <i>3.15 in</i> .	)		080			
				nm ( <i>4.72 ir</i>	n.)		120			
Reduction ratio			3:1					003		
			5:1					005		
			8:1					800		
			10:1					010		
	12:1					012				
		15:1					015			
		20:1					020			
		25:1					025			
		32:1					032			
	40:1	40:1								
Mounting with GBK adaptation kit (see table below)								κ		
BCH2 servo moto	or and GBX gea	arbox co	mbinatio	ns						
Reduction ratio from	-									
Servo motor	Reductio	Reduction ratio								
	3:1	5:1	8:1	10:1	12:1	15:1	20:1	25:1	32:1	40
BCH2MBA53eCe5C	GBX	GBX	GBX							

	3:1	5:1	8:1	10:1	12:1	15:1	20:1	25:1	32:1	40:1
BCH2MBA53•C•5C BCH2MB013•C•5C	GBX 040	GBX 040	GBX 040	-	-	-	-	-	-	-
BCH2LD023•C•5C	GBX 060	-								
BCH2LD043•C•5C	GBX 060	GBX 060	GBX 060	-	GBX 060	GBX 060	-	GBX 060	GBX 060	-
BCH2LF043•C•5C	GBX 080									
BCH2LF073•C•5C	GBX 080	GBX 080	GBX 080	-	GBX 080	GBX 080	GBX 080	GBX 080	-	-
BCH2LH103•C•6C	GBX 120									
BCH2LH203•C•6C	GBX 120	GBX 120	GBX 120	-	GBX 120	GBX 120	GBX 120	-	-	-
BCH2MM031•C•6C BCH2MM052•C•6C	GBX 120									
BCH2MM061•C•6C BCH2MM081•C•6C BCH2MM102•C•6C	GBX 120	-	-							
BCH2MM091•C•6C BCH2MM152•C•6C	GBX 120	GBX 120	GBX 120	-	GBX 120	GBX 120	-	-	-	-
BCH2MM202•C•6C	GBX 120	GBX 120	GBX 120	-	GBX 120	GBX 120	-	-	-	-

For mounting a GB	( eeeeeK planetary gearbox o	n a BCH2 s	arvo motors	an adaptor ki	t GBKaaaaa C is ro	quired
Gearbox size	For servo motor	Gearbox external diameter (mm / in.)	Motor flange size (mm / in.)	Number of motor stacks	Reference	Weight kg/lb
Size 40	BCH2MB	40/1.58	40 / 1.58	1 and 2	GBK0400400C	0.140/0.31
Size 60	BCH2LD ••••••	60/2.36	60/2.36	1 and 2	GBK0600600C	0.240/0.53
Size 80	BCH2LF04	80/3.15	80 / 3.15	1	GBK0800801C	0.460 / 1.01
	BCH2LF07	80/3.15	80 / 3.15	2 and 3	GBK0800803C	0.440/0.97
Size 120	BCH2LH.	120/4.72	100/3.94	1 and 2	GBK1201000C	0.900 / 1.98
	BCH2MM031 BCH2MM052 BCH2MM061 BCH2MM091 BCH2MM102 BCH2MM152 BCH2MM152	120 / 4.72	130 / <i>5.1</i> 2	14	GBK1201300C	1.350/2.98
	BCH2MM081	120/4.72	130 / 5.12	1 (850 W)	GBK1201308C	350/2.98