

Superior Clamping and Gripping



# **Product Information**

Random orbit sander AOV

# Compliant. Compact. Flexible. Pneumatic random orbit sander

Pneumatic random orbit sander with axial compensation for grinding and polishing of workpiece surfaces

## Field of application

Automated grinding and polishing of workpiece surfaces with a constant, adjustable contact pressure for reproducible quality.



## **Advantages - Your benefits**

**Flexibility in axial direction** for a simplified robot programming

**Use of proven, adhesive grinding and polishing wheels** for simplified automation of manual grinding and polishing tasks

**Optional media change system** for automated exchange of grinding or polishing wheels

**Optional connection for suction** for reduced contamination and susceptibility to faults

Compensation can be adjusted by means of a doubleaction pneumatic cylinder for a constant contact pressure independent of the orientation of the tool

**Simple exchange of wear parts** for maximum system availability and minimum spare parts requirements







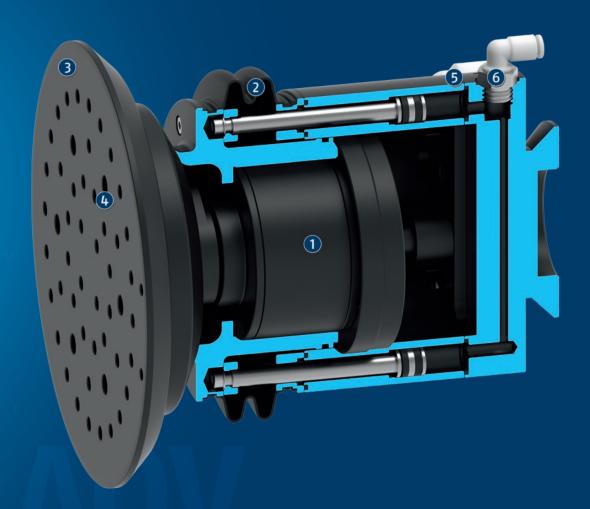




# **Functional description**

The random orbit sander is driven by a vane-type air motor. The motor is driven by filtered and oiled air. The motor is axially and flexibly mounted to compensate for tolerances on the workpiece surface and to ensure a constant contact force during the grinding or polishing process. The contact force can be controlled separately in

two directions (retracting and extending) via two air connections, so that a variable contact pressure can be achieved. The random orbit sander can be used with two different sanding pad diameters and can be optionally equipped with a connection for an extraction system.



- Rotating piston air engine
   for a high torque and a short stopping time
- ② **Dust cover** protects the bearing against contamination
- ③ Grinding pad for adhesive grinding or polishing wheels

- Bore holes for extraction of grinding and polishing dust
- S Air connection for the supply of the motor
- 6 Air connection for adjusting the contact pressure to the workpiece

3

## General notes about the series

Mounting: on the robot arm or as a stationary unit

Actuation: pneumatic, via filtered (<5  $\mu$ m, dry) and oiled compressed air (2–3 drops per hour)

Warranty: 24 months

**Ambient conditions:** Please note that the unit is notsuitable for use in an area where coolants or cutting fluids are present.



# **Application example**

Robot-guided surface treatment of sheet metal with automatic abrasive changer consisting of disk magazine, presence detector and remover.

- Orbital Sander Tool AOV
- 2 Deburring tool CDB
- Workpiece
- Magnetic gripper EMH
- Quick-change system SWS
- **6** Quick-change adapter SWA
- Tool stand module CDB
- 8 Mounting module pin and bushing
- Washer rack
- Washer presence detector
- Washer remover

# SCHUNK offers more ...

The following components make the product AOV even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.











Quick change system

Manual change system

Force/torque sensor

Clamping force block

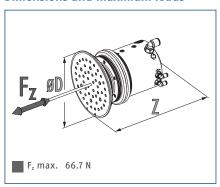


Quick-change Pallet System

① For more information on these products can be found on the following product pages or at schunk.com. Please contact us: SCHUNK technical hotline +49-7133-103-2696



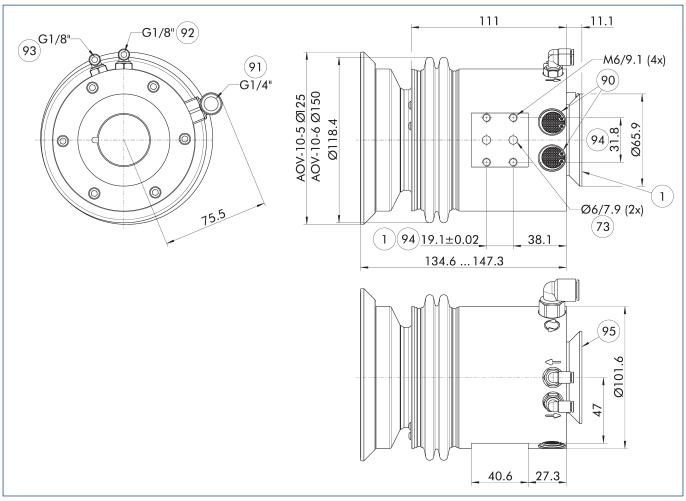
## **Dimensions and maximum loads**



## Technical data

Description		A0V-10-5	A0V-10-6
ID		1434817	1435146
Grinding disk size		125 mm (5'')	150 mm (6'')
Compensation Z	[mm]	12.7	12.7
Recommended compensation path	[mm]	±5	±5
Min./max. extension compensation force	[N]	13.3/66.7	13.3/66.7
Min./max. retraction compensation force	[N]	6.7/33.3	6.7/33.3
Min./max. compensation pressure	[bar]	1/4.1	1/4.1
Grinding stroke	[mm]	5	5
Idle speed	[1/min]	10000	10000
Operating pressure	[bar]	6.2	6.2
Noise emission	[dB(A)]	<85	<85
maximum air consumption	[I/s]	9.5	9.5
Air connection motor		10 mm	10 mm
Compensation air connection		10 mm	10 mm
Weight	[kg]	2.68	2.68
Min./max. ambient temperature	[°C]	5/35	5/35
Dimensions Ø D x Z	[mm]	125 x 148	150 x 148
Options and their characteristics			
Description		A0V-10-5-V	A0V-10-6-V
with optional connection for suction		1434818	1435148

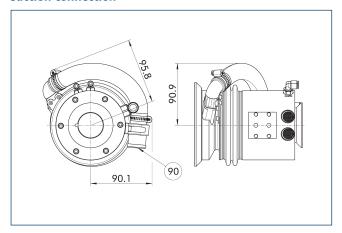
#### Main view



The drawing shows the unit in the basic version.

- 1 Robot-side connection
- 73 Fit for centering pins
- 90 Ventilation opening
- (91) Air connection motor, hose screw connection for 10 mm hose
- ©2) Extend air connection compensation, hose screw connection for 4 mm hose
- Retract air connection compensation, hose screw connection for 4 mm hose
- 94 radial mounting option
- 95) axial mounting option

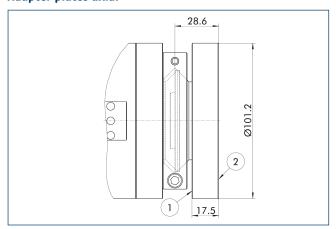
#### **Suction connection**



90 Vacuum connection Ø 25.4 mm

The drawing shows the unit with the optional connection for a suction unit.

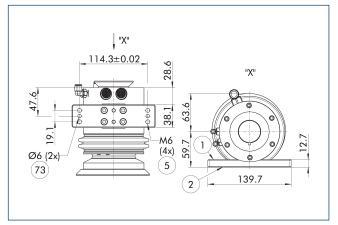
### Adapter plates axial



- (1) Robot-side connection
- (2) Tool-side connection

Description	ID
Adapter plate	
A-AOV-Axial-ISO-A50	1453540
A-FDB-660-1040/RCF-710/A0V-Axial	0322211

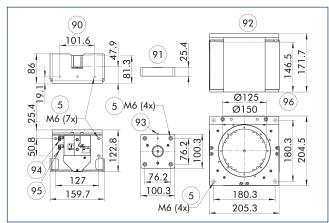
#### Adapter plates, radial



- 1 Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (73) Fit for centering pins

Description	ID	ID	
Adapter plate			
A-AOV/CRT/RCV-250/490/RCE-radial	1420116		

#### Automated media changer



- (5) Through hole for connection with screws
- 90 Washer remover
- (91) Washer presence detector
- (92) Washer rack
- (93) Cable outlet, proximity switch
- (94) Retract air connection needles
- 95 Extend air connection needles
- 96 max. media storage capacity

The drawing shows the three necessary components of the media changer.

Description	ID	Disk diameter				
Automated media changer						
AOV-MCH	1460790					
AOV-MF5	1460781	125 mm (5'')				
AOV-MF6	1460783	150 mm (6'')				
AOV-MRA	1460797					

All three components are necessary in order to use the media changer.
 These can be ordered separately and positioned individually.

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