# PENKO Engineering B.V.

Your Partner for Fully Engineered Factory Solutions



Manual: EU-800d



### IMPORTANT SAFETY INFORMATION READ THIS PAGE FIRST!

PENKO Engineering B.V. manufactures and tests its products to meet all applicable national and international standards. It is vital that this instrument is correctly installed, used, and maintained to ensure it continues to operate to its optimum specification.

The following instructions must be adhered to and incorporated into your safety program when installing, using, and maintaining PENKO products. Failure to follow the recommended instructions can affect the system's safety and may increase the risk of serious personal injury, property damage, damage to this instrument and may invalidate the product's warranty.

• Read the instructions fully prior to installing, operating, or servicing the product. If this Instruction Manual is not the correct manual for the PENKO product you are using, call 0031(0)318-525630 for a replacement copy. Keep this Instruction Manual in a safe place for future reference.

• If you do not fully understand these instructions, contact your PENKO representative for clarification.

• Pay careful attention to all warnings, cautions, and instructions marked on and supplied with the product.

• Inform and educate your personnel about the correct installation, operation, and maintenance procedures for this product.

• Install your equipment as specified in the installation instructions of the appropriate Instruction Manual and as per applicable local and national codes. Connect all products to the proper electrical sources.

• To ensure correct performance, use qualified personnel to install, operate, update, program, and maintain the product.

• When replacement parts are required, ensure that qualified technicians use replacement parts specified by PENKO. Unauthorized components and procedures can affect the product's performance and may affect the continued safe operation of your processes. The use of non-specified 'look-alike' substitution parts may result in the risk of fire, electrical hazards, or improper operation.

• Ensure that all equipment doors are closed and protective covers are in place, except when maintenance is being performed by qualified persons, to prevent electrical shock and personal injury.



### WARNING

#### ELECTRICAL SHOCK HAZARD

Installing cable connections and servicing this instrument require access to shock hazard level voltages which can cause death or serious injury.

Disconnect separate or external power sources to relay contacts before commencing any maintenance.

The electrical installation must be carried out in accordance with CE directions and/or any other applicable national or local codes.

Unused cable conduit entries must be securely sealed by non-flammable blanking plates or blind grommets to ensure complete enclosure integrity in compliance with personal safety and environmental protection requirements.

To ensure safety and correct performance this instrument must be connected to a properly grounded, three-wire power source.

Proper relay use and configuration is the responsibility of the user.

Do not operate this instrument without the front cover being secured. Refer any installation, operation or servicing issues to qualified personnel.

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### Introduction

The PENKO EU-800d is an IP68 Measurement Device.

#### In the box

The box contains the following items:

- 1 x PENKO EU-800d
- 1 x quick start manual

#### **Needed for use**

To use the EU-800d the following items are needed:

- Class 2 or Limited Power Source, rate 18 32 VDC, 0.4A@24VDC
- Load cell
- USB A B cable for configuration with PC software (optional)

For easy configuration, two PC applications are available as download.



#### PDI Client

PDI Client is a cross-platform freeware program for easy monitoring and configuration of PENKO devices. PDI Client is compatible with the PENKO FLEX series, FLEX2100 series, 1020 series, SGM700/800 series and RIO/RIA700 series. Only USB communication is supported. The minimum required Java Runtime Environment is version 1.8.0. Installation guide and USB drivers for Windows are included.



#### Pi Mach II

Pi Mach II is a comprehensive freeware program for monitoring and configuration of PENKO devices. Available features are firmware update manager, manage tool for all parameters, oscilloscope functionality to explore filters and programming and visualization tooling for the PENKO FLEX and FLEX2100 series. USB drivers are included in the installer.





### 1 Overview





Number	Description	
1	Front with LED display, LED indications and optical keys	
2	24VDC power supply	
3	Digital outputs (4)	
4	Digital inputs (3)	
5	Analog output	
6	RS485 connection	
7	RS485 bus termination	
8	USB connection	
9	Load cell connection	



### 2 Connections

This chapter describes the connections of the EU-800d.





### 2.1 Power supply



Power the device using a Class 2 or Limited Power Source, rate 18 – 32 VDC, 0.4A@24VDC



### 2.2 Load cell



Property	Description
Wiring	With sense
Type of sense	Passive
Excitation voltage	5 VDC
Sensitivity	0.1 μV/d
Selectable ranges	1 mV/V   1,5 mV/V   2 mV/V   2,5 mV/V   3 mV/V
Input voltage unipolar @3mV/V	-1 mV to 16 mV
Input voltage bipolar @3mV/V	-16 mV to 16 mV
A/D Conversion speed	1600/s
Max. load cell impedance	1200 Ω
Min. Load cell impedance	43,75 Ω
Max. no. of load cells 350 $\Omega$	8
Max. no. of load cells 1000 $\Omega$	22



#### 2.3 USB



Connect the device to a computer using an A - B USB cable. The USB interface is used for communication with PENKO configuration software.

Before connecting the device to a computer using USB, make sure the USB driver is installed. The driver is included in the PENKO configuration PC applications, see chapter PC applications.

Only 1 protocol is supported over USB:





Before connecting the device to a computer using USB, make sure the USB driver is installed.



The USB interface is intended for use before installation and can only be connected when the housing is open. This must only be allowed outside the explosion hazard zone.



The USB interface cannot be used for printers, memory sticks etc.



#### 2.4 Analog output



The analog output must be powered by an external power supply as shown in the above picture. The analog output can follow an indicator value and output the following range:

Range	Description
4 - 20 mA	The minimum and maximum output of the analog output

See chapter 6.3.6 for all available settings.

#### 2.5 RS485



The following protocols are supported over RS485:

Protocol	Description
Modbus-RTU	Protocol to connect to SCADA/PLC
Modbus-ASCII	Protocol to connect to SCADA/PLC
ASCII	PENKO protocol for ASCII communication
NPV Slave	PENKO Protocol used for follow displays

For best performance the RS485 must be terminated at the first and last device on the bus. This ensures proper impedance matching. Use the dipswitch to terminate the bus.

See chapter 6.3.3 for all available settings.



### 2.6 Digital outputs



The device has 4 digital outputs that can be used for an AC and DC power circuit up to 35V/0.5A.

The outputs can be programmed as setpoints with a programmable hysteresis and function like Weight, Gross, Peak etc.

See chapter 6.3.5 for all available settings.

### 2.7 Digital inputs



The device has 3 digital. The inputs can be switched PNP or NPN with 18 - 28 VDC.

The inputs can be programmed as Hold, Peak Hold, Key Lock etc.

See chapter 6.3.4 for all available settings.



### 3 Display and keypad

The display contains the following indications:



- ► 0 < ZERO Zero is active
  - NET Tare is active
  - STABLE Indicator in stable range
  - MENU Device is in menu mode
  - MM COMM Reserved
  - KEY Optical keys enabled goes momentary off while a key is active
    - LBS Active unit of measurement (LBS or KG)
    - KG Active unit of measurement (LBS or KG)
- 1

KG

Press keys simultaneously for unlocking the keyboard (step 1)

Press keys simultaneously for unlocking the keyboard (step 2)



The optical keys have the following functions:

ZERO	Press short	Weighing mode: create a new zero level Menu mode: increase value by 1 or move up in menu
ZERO	Press long	Weighing mode: reset zero level to original zero level
TARE /P	Press short	Weighing mode: set/reset tare and reset preset tare Menu mode: move cursor 1 position to the left
TARE /P	Press long	Weighing mode: set preset tare
ENTER MENU	Press short	Weighing mode: Menu mode: confirm
ENTER MENU	Press long	Weighing mode: enter configuration menu Menu mode:
ESC SETP	Press short	Weighing mode: Menu mode: escape
ESC SETP	Press long	Weighing mode: enter setpoint menu Menu mode:



#### Unlocking the keyboard

By default, the optical keys are disabled to prevent accidental operation. The **KEY** indication is off to indicate this state. The keys are enabled with an unlock code.



The optical keys can now be used. The **KEY** indication turns off when a key is operated as feedback to the user.

#### Locking the keyboard

Performing one of the two above described actions will directly lock the optical keys. The **KEY** indication turns off to indicate this state.

In menu mode, the optical keys are always enabled. In weighing mode, when no key operations are detected within five minutes, the optical keys are disabled automatically. The **KEY** indication turns off to indicate this state.



### 4 PC applications

For easy configuration and monitoring, two PC applications are available as download. PDI Client and Pi Mach II. In the following chapters, Pi Mach II is used to explain the EU-800d functionality.



### 4.1 PDI Client

PDI client is a small cross-platform application that only works with USB communication. It can run on any operating system that runs Java Runtime Environment (JRE). All device properties are shown in a tree structure and can easily be edited.





USB driver and user manual are included in the download



### 4.2 Pi Mach II

Pi Mach II is a comprehensive Windows application that works with USB communication and has more functionality compared to PDI Client. The tree structure configuration of PDI Client is available in this program. Other features are backup and restore, firmware updates and a build in oscilloscope to analyze signals for different filter settings.

$\pi^2$ IdCode: 0631, Device Version: 01.00, Build: 01, Serial: FFFFFFF, Module Version: 00.00	, Build: 00, Project: C:\PENKO Engineer	ing B.V\Pi Mach I\ 🗖 🗖 💌	
File Project Environment View Tools Help			
📗 💕 On-Line 🛛 🛞 Eirmware Update Manager 🐔 Program Builder 🧠 Flex Builder 💷 Wa	tches 🛃 E <u>x</u> it		
📙 💻 Display 🛛 🕨 Control 🌰 Tasks 🛛 🏪 1/0 🚎 Indicator & Registers 📼 Labels 🚆 I	R <u>e</u> sults 🛛 🏭 Pri <u>n</u> ter Layout 👗 Printer T	icket 🕓 Clock 🗠 Scope 🔋 Manage	
⊡- PENKO ⊟- Device root ⊟- Quick Setup	Class: PENKO.Device root.Qu Path: 1.1.1.1	uick Setup.Step 1, Weigher Paramete	
	Unit Decimal point	kg 000.000	
□ 1.1.1.1.4 Maxload = 21,000 kg ⊡ Step 2, Indicator setup ⊡ Step 3, Calibrate	Step	000.000   STEP 1	
⊕ Step 4, Communication ⊕ Done	Maxload	21,000 kg	
	Discover Import Proper	rties (CSV) Apply	
ACTIVE USB USB open			



USB driver and user manual are included in the download



### 5 First use

For first use, the following settings are important:

- Unit indication
- Decimal point position
- Step size
- Maximum load
- Calibration
- Communication

This chapter describes how to adjust these settings with the configuration software and on the device itself.

### 5.1 Using the configuration software

Make sure Pi Mach II and the USB driver are installed properly as described in the Pi Mach II user manual. Open Pi Mach II and open Manage.







i

The left screen shows the device configuration in a tree structure. The right screen shows the properties of the selected item in the left screen. For example the live weight information:



In the tree, select **EU-800d**. The properties of this tree node are shown in the right screen.

□ · PENKO □ Device root □ EU-800d	Class: PENKO.Device root.EU-800d Path: 1.1.1
- 1.1.1.1 Name = - 1.1.1.2 Start Quick setup	
- 1.1.1.3 Enable Full setup	Name
tie- Live 	Start Quick setup
B- Control B- Access	Enable Full setup

The first use settings are available under Start Quick setup





To confirm a setting press enter or click the Apply button



#### Select Step1, Weigher Parameters

Unit	kg 💌
Decimal point	000.000
Step	STEP 1
Maxload	10,009 kg

#### Unit

Set the unit of measurement. This will be shown everywhere the measured weight is displayed or printed. The corresponding **KG** or **LBS** indication on the device is on.

Available options	
lbs	
kg	

#### **Decimal point**

Select the position of the decimal point. This setting will be used everywhere the measured weight is displayed or printed.

Available options
000000
00000.0
0000.00
000.000
00.0000
0.00000



#### Step

Select the step size. This setting defines the scaled parts of the weigher value. The display value will be rounded to the nearest value with a valid step size. Available options:

Available options
1
2
5
10
20
50
100
200
500

#### $\rightarrow$ Example:

Measured value is 2317 kg.

Step size	Displayed value
1	2317
2	2318
5	2315
10	2320
20	2320
50	2300
100	2300
200	2400
500	2500

#### Maxload

Set the weight the indicator will use as maximum. If the measured weight is higher than the maximum load, the display will show ======



More weigher parameters are available in the Full setup



#### Select Step2, Indicator setup

Application	Unknown	•

#### Application

A number of predefined configurations with specific filter settings are available. These configurations don't affect the settings made in step 1. They only affect the filter settings.

Available options
Unknown
Standard indicator
Fast indicator
Silo
Platform
Belt slow
Belt fast
Filling slow
Filling fast
Checkweigher slow
Checkweigher fast

When setting up an installation, select the appropriate configurations and start fine tuning it with the options available in the Full setup.



Filter settings are explained in the Full setup chapter



#### Select Step 3, Calibrate

Live gross	0,000 kg
Live signal	0,6637 mV
Scale empty	0,000 kg
	Calibrate scale empty
Enter load on scale	0,000 kg
	Calibrate load on scale

With this step a two-point calibration can be made. The unit indication and decimal point position are a result of the settings in step 1.

#### Live gross

This shows the gross indicator value. When no calibration is available this will show cccccc

#### Live signal

This shows the voltage generated by the connected load cell.

#### Scale empty

The calibration of the "zero" point.

Make sure the load cell is not loaded and is stable.

Click Calibrate scale empty and the zero point is saved.

#### Enter load on scale

The calibration of the "gain" point.

Make sure the load cell is loaded with the reference weight and is stable.

Set the reference weight.

Click Calibrate load on scale and the gain point is saved.

The device is now calibrated.



More calibration options are available in the Full setup



#### Select Step 4, Communication

All communication options use the RS485 connection.

#### RS485

Protocol	MODBUS-RTU
Address	1
Stopbits	2
Parity	None
Baudrate	9600
Indicator	0

#### Number of data bits is fixed at 8

#### Protocol

Select the protocol for the RS485 port.

Available options
None
MODBUS-RTU
MODBUS-ASCII
ASCII
NPV Slave

**Address** Set the address of the port for identification in the network.





#### Stopbits

Set the number of stop bits needed for the selected protocol.



#### Parity

Set the parity needed for the selected protocol.

Available options
None
Odd
Even
Mark
Space

#### Baudrate

Set the baud rate needed for the selected protocol.

Available options
1200
2400
4800
9600
19200
38400
57600
115200

#### Indicator

This option is only active when ASCII is selected as protocol. The value of the selected indicator will be sent out over the communication port.





### 5.2 Using the device

The menu structure in the device has no quick setup like the configuration software. The first use items can be set along with all other settings. First the interaction with the device is explained.

#### 5.2.1 Device interaction

This chapter describes the device interaction using the optical keys.

#### How to open the Main Menu

From the main screen, press the Enter/Menu button for 5 seconds to enter the Main Menu.



The **MENU** indication lights up to indicate that the device is in menu mode.

#### How to navigate through the menu

Use the Up button to navigate through the menus. Use the Enter button to enter a menu item. Use the Escape button to step back a level.





#### Available menu items

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The following menu items are available:

Fun	Setpoint function settings
REn	Setpoint action settings
dRC	Analog output settings
485	RS485 settings
I n d	Indicator settings
rn9	Multi range/interval settings
FIL	Filter settings
dSF	Digital filter settings
PCL	Pre-calibration settings
CRL	Calibration settings
E[L	Theoretic calibration
966	Geographic calibration
[Lo	Date / time
rel	Recall

#### How to edit a menu setting

In case of changing a setting with a fixed number of options, the current option is shown. With the following keys the option can be changed.



#### Example





Change this option with the UP key, confirm with ENTER or cancel with ESC. Note: the full menu structure and available options can be found in appendix I.



#### How to edit a menu value

In case of changing a setting with a value, the current value is shown and the last digit is blinking. With the following keys the value can be changed.

Select previous digit	TARE /P	Press short
Increase selected digit	ZERO	Press short
Confirm whole value	ENTER MENU	Press short
Cancel	ESC SETP	Press short

#### Example









The last digit is blinking. Change its value with the UP key. Select another digit with the LEFT key. Confirm with ENTER or cancel with ESC. *Note: the full menu structure and available options can be found in appendix I.* 

#### 5.2.2 First use parameters

This chapter describes the weigher settings for first use.

#### Set the weigher parameters for first use

The weigher parameters from the quick setup can be set as follows:



#### Maxload

Set the weight the indicator will use as maximum. If the measured weight is higher than the maximum load, the display will show ======



After setting the max load, menu item Ind 2 is shown.



#### Step size

Select the step size. This setting defines the scaled parts of the weigher value. The display value will be rounded to the nearest value with a valid step size. Available options:

Available options
1
2
5
10
20
50
100
200
500

After setting the step size, menu item Ind 6 is shown.





To edit the **Decimal Press short** Point position



Set Decimal Point Position, see description below



#### **Decimal point**

Select the position of the decimal point. This setting will be used everywhere the measured weight is displayed or printed.

Available options
000000
00000.0
0000.00
000.000
00.0000
0.00000

#### After setting the decimal point position, menu item Ind 7 is shown.



#### Unit

Set the unit of measurement. This will be shown everywhere the measured weight is displayed or printed. The corresponding **KG** or **LBS** indication on the device is on.

Available options
lbs
kg



The full menu structure and available options can be found in appendix I





The predefined settings of step 2 in the quick setup are not available in the configuration menu of the device

#### Calibrate the device for first use

The calibration from the quick setup can be performed as follows:







After deleting the calibration points, menu item CAL 4 is shown.





#### Set communication options for first use

The communication from the quick setup can be performed as follows:



#### Protocol

Select the protocol for the RS485 port.

Available options	Description
1	None
2	MODBUS-RTU
3	MODBUS-ASCII
4	ASCII
5	NPV Slave




#### After setting the protocol, menu item 485 2 is shown.



Press short To set the address

Set address, see description below

#### Address

Set the address of the port for identification in the network.



#### After setting the address, menu item 485 3 is shown.



## Stopbits

Set the number of stop bits needed for the selected protocol.





### After setting the stop bits, menu item 485 4 is shown.



## Parity

Set the parity needed for the selected protocol.

Available options	Description
1	None
2	Odd
3	Even
4	Mark
5	Space

### After setting the parity, menu item 485 5 is shown.



**Press short** To set the baudrate



Set baudrate, see description below



#### Baudrate

Set the baud rate needed for the selected protocol.

Available options	Description
1	1200
2	2400
3	4800
4	9600
5	19200
6	38400
7	57600
8	115200

#### After setting the baudrate, menu item 485 6 is shown.



#### Indicator

This option is only active when ASCII is selected as protocol. The value of the selected indicator will be sent out over the communication port.





The full menu structure and available options can be found in appendix I



#### How to use the Setpoint Menu

The setpoint function and action can only be set via the configuration software. The value of the setpoints however, can be set in the device setpoint menu.

From the main screen, press the Escape/Setpoint button to enter the Setpoint Menu.





## 6 Full setup

The full setup is described with use of the configuration software. Most settings are also available in the device menu. A full menu structure can be found in appendix I.

In the tree, select **EU-800d**. The properties of this tree node are shown in the right screen.

E- PENKO È- Device root È- <mark>EU-800d</mark>	Class: PENKO.Device root.EU-800d Path: 1.1.1
	Name
1.1.1.3 Enable Full setup Live System	Start Quick setup
⊡- Control ⊕- Access	Enable Full setup

The full settings are available under Enable Full setup





To confirm a setting press enter or click the Apply button



## 6.1 Live

⊡. Live
⊕ Remote
⊡ Indicator
Digital inputs
Digital outputs
🗄 Analog output
Counters

Live shows various live parameters of the device.

Node	Description
Remote	Buttons to remotely control the device
Indicator	Live indicator values and indicator status
Digital inputs	Live status of the 3 digital inputs (0 = OFF, 1 = ON)
Digital outputs	Live status of the 4 digital outputs (0 = OFF, 1 = ON)
Analog output	Live output percentage of the analog output
Counters	Live counter status of the 3 digital inputs
Totals	Live status of the totals

## 6.2 System



System shows the system information.

Node	Description
Info	Hardware and software information of the device
License	License information of the device



## 6.3 System Setup

System Setup
Service
⊡ Indicator
Digital inputs
Digital outputs
Analog output

System Setup contains the full device configuration.

### 6.3.1 Service

Service is for PENKO employees only.

### 6.3.2 Indicator

Indicator contains the indicator parameters and calibration.

⊡ Indicator
Calibration

#### PARAMETERS

To enter the parameters, enter the shown TAC and confirm with Enter or the Apply button:

ТАС	[0001]
Enter TAC	1

The parameters are now shown in the tree:

⊡. Indicator
🗄 Parameters
- 1.1.1.3.2.1.1 TAC = [0001]
- 1.1.1.3.2.1.2 Enter TAC
🗄 Weigher
🗄 Stable
🗄 Zero tracking
🗄 Range/Interval
🕀 Filter



## Weigher

Weigher contains the basic weigher parameters.

Name	
Maxload	10,009 kg
Sample rate	1600/s
Step	STEP 1
Decimal point	000.000
Unit	kg 💌

#### Name

Set a name to identify the device in a multiple device setup (optional).

#### Maxload

Set the weight the indicator will use as maximum. If the measured weight is higher than the maximum load, the display will show ======

#### Sample rate

Select the sample rate for measuring.

Available options
10/s
20/s
25/s
50/s
100/s
200/s
400/s
800/s
1600/s



## Step

Select the step size. This setting defines the scaled parts of the weight value. The display value will be rounded to the nearest value with a valid step size. Available options:

Available options
1
2
5
10
20
50
100
200
500

## $\rightarrow$ Example:

Measured value is 2317 kg.

Step size	Displayed value
1	2317
2	2318
5	2315
10	2320
20	2320
50	2300
100	2300
200	2400
500	2500



#### **Decimal point**

Select the position of the decimal point. This setting will be used everywhere the measured weight is displayed or printed.

Available options
000000
00000.0
0000.00
000.000
00.0000
0.00000

### Unit

Set the unit of measurement. This will be shown everywhere the measured weight is displayed or printed. The corresponding **KG** or **LBS** indication on the device is on.

Available options
lbs
kg

#### Stable

The stable settings determine when the indicator accepts the current value as stable.

Stable range	0,002 kg
Stable time	1,00 s

#### Stable range

Set the range the indicator has to be in for the set time to give a stable signal.

#### Stable time

Set the time the weigher has to be within the range to give the stable signal.

With these values, the indicator has to be within the range of 0.002kg over the time of 1.00 second to indicate stable. When stable, the stable indication on the display will light up.



#### Zero tracking

Zero tracking is able to tune the zero point back to zero when the scale becomes dirty.

Tracking range	0,100	kg
Tracking step	0,010	kg
Tracking time	1,00	s

#### Tracking range

Set the maximum offset to tune back to zero.

#### **Tracking step**

Set the step size that will be tuned every time the weight is within the tracking range.

#### **Tracking time**

Set the time that the weight has to be within the tracking range to tune 1 step back to zero.

With these values, the indicator will step back 0.010kg towards zero every 1.00 second as soon as the measured weight gets below 0.100kg.

#### Range/Interval

Set the indicator to change its step size when the measured weight reaches a certain value.

Range	100 parts
MaxStep	STEP 50
Mode	MULTI-RANGE

#### Range

Set the number of divisions when the indicator has to display with the next step size. Auto ranging is disabled when range is set to 0.



#### MaxStep

Select the biggest allowed step size.

Available options
Step 1
Step 2
Step 5
Step 10
Step 20
Step 50
Step 100
Step 200
Step 500

#### Mode

Select the mode. In multi-range mode the step size is reset when the indicator has been lower or equal to zero. In multi-interval mode the step size is reset when the value reached the previous range.

Available options	
Multi-Range	
Multi-Interval	

 $\rightarrow$  Example:

With the shown values, the ranges are as follows:

Range No.	Displayed range	Step size
Range: 1	0 - 100	1
Range: 2	100 - 200	2
Range: 3	200 - 500	5
Range: 4	500 - 1000	10
Range: 5	1000 - 2000	20
Range: 6	2000 - 5000+	50

The number of ranges depends on the selected max step size. In this case there are 6 possible ranges.



In multi-range mode, the range will only get back to range 1 when the indicator has been lower or equal to zero. In this case, when the value goes down, range 4 will remain active until the indicator reaches zero.

In multi-interval mode, the range number will follow the table above. In this case, when the value gets lower than 500, range 3 will become active, etc.

#### Filter

Filters are used to filter vibrations present in an industrial environment.

Overall filter	0 dB
Filter type	Static
Cut Off	1,0 Hz
Moving Average	50 Hz

### **Overall filter**

Select an overall filter. This will affect all indicator signals in the device. 0dB is no filtering. -48dB gives the strongest damping.

Available options
0 dB
-6 dB
-12 dB
-18 dB
-24 dB
-30 dB
-36 dB
-42 dB
-48 dB

To prevent a loss of information or accuracy, don't set the overall filter higher than 24dB. When no accuracy is needed, a higher filter setting is allowed to enable extreme filtering.



#### Filter type

Select the type of filtering. This is a 2<sup>nd</sup> order filter. This filter affects all signals up to and including the cutoff frequency.

Available options	Description
None	No filter
Dynamic	Used when the signal is changing fast
Static	Used when the signal is changing slow

### Cut Off

Select the cutoff frequency for the selected filter type.

Available options
1,0 Hz
1,4 Hz
2,5 Hz
5,0 Hz
10 Hz
20 Hz
40Hz

### **Moving Average**

Set the moving average frequency for the selected filter.



### Display

The display filter will damp the indicator signal to the display to get a calm display view.

Rate	25/s	
Display Net/Gross:Filter range	0,000 kg	
Display Net/Gross:Filter damping	0 dB	
Display Net/Gross:Zero suppress	0,000 kg	
Indicator	WEIGHER	



#### Rate

Select the refreshment speed of the display.

Available options
1/s
2/s
3/s
5/s
10/s
25/s
50/s

### **Display Tracking: Filter range**

Set the range where the filter is active.

## **Display Tracking: Filter damping**

Select the strength of the filter. OdB is no filtering. -48dB gives the strongest damping.

0 dB -6 dB -12 dB -18 dB
-12 dB
-18 dB
10 00
-24 dB
-30 dB
-36 dB
-42 dB
-48 dB

## **Display Tracking: Zero suppress**

Set the band within the indicator will show 0.



## Indicator

Select the indicator that is shown in the display.

Available options	Description
Weigher	Filtered net weigher value that can react on multi range/interval
Fast Gross	Unfiltered gross weigher value
Fast Net	Unfiltered net weigher value
Display Gross	Filtered gross weigher value
Display Net	Filtered net weigher value
Tare	Tare value
Peak	Peak hold value - the highest measured value
Valley	Valley hold value - the lowest measured value
Hold	Hold value - stored with zero button in hold mode, or with hold input
Weigher x10	Weight with extra decimal for more accuracy
Fast Gross x10	Fast Gross with extra decimal for more accuracy
Fast Net x10	Fast Net with extra decimal for more accuracy
Display Gross x10	Display Gross with extra decimal for more accuracy
Display Net x10	Display Net with extra decimal for more accuracy
Tare x10	Tare with extra decimal for more accuracy
Peak x10	Peak with extra decimal for more accuracy
Valley x10	Valley with extra decimal for more accuracy
Hold x10	Hold with extra decimal for more accuracy
Signal	mV signal from the load cell(s)



### CALIBRATION

To enter the calibration, enter the shown CAL and confirm with Enter or the Apply button:

CAL	[0002]
Enter CAL	0

The parameters are now shown in the tree:



#### Weight calibration

Weight calibration contains the calibration settings.



→ **Display** shows the current display values.

Gross	0,804 kg
Gross x10	0,8043 kg
Signal	0,4046 mV
ADC	076607 ADC

#### Gross

The current displayed gross value.

#### Gross x 10

The current displayed gross value with extra digit for more accuracy.



### Signal

The current signal, from the load cell, in millivolts.

### ADC

The current ADC value.

 $\rightarrow$  **Points** show the stored calibration points.

Point 1	848941ADC 9,9869mV 20,000kg
Point 2	044243ADC 0,0030mV 0,000kg
Point 3	not used
Point 4	not used
Point 5	not used
Point 6	not used
Point 7	not used
Point 8	not used
Point 9	not used
Point 10	not used

Up to 10 calibration points can be stored to realize a multi-point calibration.

 $\rightarrow$  Add/Replace point is used to add a calibration point.

Add/Replace point	0,000	kg

When a point is added with a value that already exists, the existing point will be replaced. When a point is added with a new value, it will be stored as a new point.

 $\rightarrow$  **Delete point** is used to delete a calibration point.



Select the number of the calibration point (see Points) and confirm with Enter or the Apply button. The calibration point will be deleted.



 $\rightarrow$  **Deadload** can be set to pull the whole measuring line back to zero. The zero point could be different because of some modification on the scale or dirt.

Deadload	0,000	kg
----------	-------	----

Normally, the dead load is zero, but it's possible to change the line position if there's weight on the scale. To do so, edit the actual weigh value to the new known value.



#### **Transducers calibration**

Transducer calibration is used for a theoretic calibration, using the datasheet of the load cell. Up to 8 transducers can be set.

□ Transducers calibration
Transducer 5
Transducer 6
Transducer 7

For each load cell the following data can be set.

Output	0,00000 mV/V
Zero balance	0,00000 mV/V
Туре	None
Max load	10,000 kg



### Output

Set the output value as mentioned on the datasheet.

#### Zero balance

Set the zero balance value as mentioned on the datasheet.

**Type** Set a name for the load cell.

#### Max load

Set the maximum load as mentioned on the datasheet. The max load is automatically copied to all transducers because all transducers must have the same max load. The total max load is the sum of the max load of all active transducers.

#### **Geometric calibration**

After calibrating with the Transducer menu, the geometric location and height of the place where the load cells are fabricated and the recent location must be filled in.

Latitude	52,00	degrees
Elevation	0	m

Set both values for Origin (load cell origin) and Location (load cell current location).

#### Input range

Input range is used to set the range for the connected load cell.

Mode	Unipolar 🔽
Range	2 mV/V
Offset	0



### Mode

Set the polarity of the input.

Available options	Description
Unipolar	Input range between -0.2mV/V and value set at Range (default 2mV/V)
Bipolar	Input range between minus Range and Range (default -2mV/V to 2mV/V)

## Range

Select the input range.

Available options	Description
1mV/V	
1,5 mV/V	
2 mV/V	Calibrated range*
2,5 mV/V	
3 mV/V	Calibrated range*

\* When using a theoretic calibration, note that these two ranges are officially calibrated

## Offset

Set an ADC value offset. This can be used when the indicator gets out of its ADC range.



#### 6.3.3 Communication

The only communication port is the RS485 port.

⊡. Communication

#### RS485

Protocol	None
Address	0
Stopbits	1
Parity	None
Baudrate	9600 💌
Indicator	0

## Number of data bits is fixed at 8

### Protocol

Select the protocol for the serial port.

Available options
None
MODBUS-RTU
MODBUS-ASCII
ASCII
NPV Slave

### Address

Set the address of the port for identification in the network.





## Stopbits

Set the number of stop bits needed for the selected protocol.



## Parity

Set the parity needed for the selected protocol.

Available options
None
Odd
Even
Mark
Space

#### Baudrate

Set the baud rate needed for the selected protocol.

Available options	
1200	
2400	
4800	
9600	
19200	
38400	
57600	
115200	



## Indicator

This option is only active when ASCII is selected as protocol. The value of the selected indicator will be sent out over the communication port.

Available options	Description
Weigher	Filtered net weigher value that can react on multi range/interval
Fast Gross	Unfiltered gross weigher value
Fast Net	Unfiltered net weigher value
Display Gross	Filtered gross weigher value
Display Net	Filtered net weigher value
Tare	Tare value
Peak	Peak hold value - the highest measured value
Valley	Valley hold value - the lowest measured value
Hold	Hold value - stored with zero button in hold mode, or with hold input
Weigher x10	Weight with extra decimal for more accuracy
Fast Gross x10	Fast Gross with extra decimal for more accuracy
Fast Net x10	Fast Net with extra decimal for more accuracy
Display Gross x10	Display Gross with extra decimal for more accuracy
Display Net x10	Display Net with extra decimal for more accuracy
Tare x10	Tare with extra decimal for more accuracy
Peak x10	Peak with extra decimal for more accuracy
Valley x10	Valley with extra decimal for more accuracy
Hold x10	Hold with extra decimal for more accuracy
Signal	mV signal from the load cell(s)



## 6.3.4 Digital inputs

The digital inputs can execute a function.

Function 1	HOLD
Function 2	NONE
Function 3	NONE

### Function

Select a function for the input.

Available options	Description
None	No function
Zero Set	Set indicator to zero
Zero Reset	Reset indicator from zero
Tare On	Set tare
Tare Off	Reset tare
Tare Toggle	Toggle between tare and net
Preset Tare On	Tare on configured preset tare
Print (reserved)	-
Print Subtotal/Event (reserved)	-
Print Total/Alibi (reserved)	-
Print Day Total (reserved)	-
Print Batch Total (reserved)	-
Totalize	Add current weight to total
Subtotal (reserved)	-
Total Reset	Reset totals
Day Total (reserved)	-
Batch Total (reserved)	-
Peak Reset	Reset peak hold value
Valley Reset	Reset valley hold value
Hold	Store current value as hold value
Keyboard Lock	Disable the device keyboard
Start Stop (reserved)	-
Print Layout (reserved)	-



## 6.3.5 Digital outputs

The digital outputs can respond to the value of an indicator.

Digital outputs
🗄 Setpoint
Action
• Function

### Setpoint

Level 1	0,000 kg
Level 2	1,000 kg
Level 3	2,000 kg
Level 4	3,000 kg

#### Level

Set the level for each output when it has to turn on.

### Action

Hysteresis 1	0,010 kg
Hysteresis 2	0,010 kg
Hysteresis 3	0,010 kg
Hysteresis 4	0,010 kg

#### Hysteresis

Set the hysteresis for each output. The hysteresis can be positive or negative.







#### Function





#### Function

Select the indicator the output has to react on.

Available options	Description
Weigher	Filtered net weigher value that can react on multi range/interval
Fast Gross	Unfiltered gross weigher value
Fast Net	Unfiltered net weigher value
Display Gross	Filtered gross weigher value
Display Net	Filtered net weigher value
Tare	Tare value
Peak	Peak hold value - the highest measured value
Valley	Valley hold value - the lowest measured value
Hold	Hold value - stored with zero button in hold mode, or with hold input
Weigher x10	Weight with extra decimal for more accuracy
Fast Gross x10	Fast Gross with extra decimal for more accuracy
Fast Net x10	Fast Net with extra decimal for more accuracy
Display Gross x10	Display Gross with extra decimal for more accuracy
Display Net x10	Display Net with extra decimal for more accuracy
Tare x10	Tare with extra decimal for more accuracy
Peak x10	Peak with extra decimal for more accuracy
Valley x10	Valley with extra decimal for more accuracy
Hold x10	Hold with extra decimal for more accuracy
Signal	mV signal from the load cell(s)

## $\rightarrow$ Example:

Output	Setpoint	Action	Function	Description
1	1,000 kg	0,100 kg	Weight	Positive hysteresis - output will turn on at setpoint
2	1,000 kg	-0,100 kg	Weight	Negative hysteresis - output will turn off at setpoint

- Output 1 will turn on when the tracking value reaches 1,000 kg
- It will turn off again when the tracking value drops below 0,900 kg (1,000 0,100)
- Output 2 will turn off when the tracking value reaches 1,100 kg (1,000 + 0,100).
- It will turn on again when the tracking value drops below 1,000 kg



## 6.3.6 Analog output

The settings for the analog output.

Analog output
🕀 Manual
• Configuration

#### Manual

Manual output level	0,00	%
	Manual control	
	Manual 0.00%	
	Manual 100.00%	
	Manual off	

#### Manual output level

Set the percentage for the output when manual control is enabled.

### Manual control

Enable manual control of the output.

#### Manual 0.00%

Set the output to 0%

#### Manual 100.00%

Set the output to 100%

#### Manual off

Disable manual control of the output.

#### Configuration

Minimum Level	0,000	kg
Maximum Level	10,000	kg
Function	WEIGHER	•



## **Minimum level**

Set the indicator value the analog output will set as 0.00% output.

#### Maximum level

Set the indicator value the analog output will set as 100.00% output.

### Function

Select the indicator the output has to react on.

Available options	Description
Weigher	Filtered net weigher value that can react on multi range/interval
Fast Gross	Unfiltered gross weigher value
Fast Net	Unfiltered net weigher value
Display Gross	Filtered gross weigher value
Display Net	Filtered net weigher value
Tare	Tare value
Peak	Peak hold value - the highest measured value
Valley	Valley hold value - the lowest measured value
Hold	Hold value - stored with zero button in hold mode, or with hold input
Weigher x10	Weight with extra decimal for more accuracy
Fast Gross x10	Fast Gross with extra decimal for more accuracy
Fast Net x10	Fast Net with extra decimal for more accuracy
Display Gross x10	Display Gross with extra decimal for more accuracy
Display Net x10	Display Net with extra decimal for more accuracy
Tare x10	Tare with extra decimal for more accuracy
Peak x10	Peak with extra decimal for more accuracy
Valley x10	Valley with extra decimal for more accuracy
Hold x10	Hold with extra decimal for more accuracy
Signal	mV signal from the load cell(s)

The range of the analog output is fixed at 4 - 20mA



### 6.3.7 Clock

The device date and time are used for printer tickets and for storing data in the alibi memory and event log. The device is equipped with a backup battery for the real time clock.

Current Time	16:22:44
Current Date	08-08-2014
Set Time (HH:MM:SS)	16:22:40
Set Date (DD:MM:YYYY)	08-08-2014

### **Current Time**

The current device time in HH:MM:SS format.

## **Current Date**

The current device date in DD-MM-YYYY format.

### Set Time

Set the time in the indicated format to correct the device time.

### Set Date

Set the date in the indicated format to correct the device date.

An easy way to synchronize time and date is to use the Clock function in Pi Mach II.









#### 6.3.8 Factory recall

A factory recall can be performed. Also the device parameters can be backed up and restored.



#### Parameters to factory

Are you sure ? No
-------------------

Select yes to set all parameters to factory. The device reboots after this action.

Backup

Are you sure ?	No	•	

A backup of the device configuration can be made within the device. A password is required for the backup. Contact PENKO for this password. When using Pi Mach II manage to make a backup, enter this password in the service code field to enable the backup option.

#### **Restore parameters**



This option only restores the non-certified parameters.

Restore full			
Are you sure ?	No	•	

This option restores all parameters.



## 6.4 Control

⊡ · Control
⊡ Indicator

Control has various functions to control the indicator.

Node	Description
Zero Set	Set the indicator value to zero
Zero Reset	Set the indicator value back to its original value
Tare Set	Set tare
Tare Reset	Reset tare
Tare Toggle	Toggle between tare and net
Preset Tare Value	Set the preset tare value
Peak Reset	Reset the stored peak hold value
Valley Reset	Reset the stored valley hold value

## 6.5 Access

⊡ Access		
🗄 Alibi		

Access contains the Alibi Memory and Event Log.

Node	Description
Alibi	Browse or clear the Alibi Memory
Event Log	Browse the Event Log



Also see the Alibi Memory and Event Log chapter



## 7 Alibi Memory and Event Log

The Alibi and Event Log support the following features:

- Automatically store system events
- Create alibi records
- View alibi records and event logs

## 7.1 Alibi Memory

Alibi records are generated by a user action. To generate records, go to the Digital inputs settings menu and set an input action to Print.

	Class: PENKO.Device root.EU-800d.System Setup.Digital inputs Path: 1.1.1.3.4		
- 1.1.1.1 Name = - 1.1.1.2 Start Quick setup - 1.1.1.3 Enable Full setup	Function 1		
⊕- Live ⊕- System	Function 2	NONE	
⊟- System Setup ⊡- Service	Function 3	NONE	
B: Indicator  C: Communication  C: Digital inputs  D: Digital inputs  D: Digital outputs  C: Digital outputs  C: Clock  D: Clock  C: Control  C: Control  C: Access			
	Discover Import Prope	erties (CSV) Apply	

Every time the input is activated, a new alibi record is created. To see the alibi records, go to the Access menu and select Alibi.

PENKO  Device root  -EU-800d  -1.1.1.2 Start Quick setup -1.1.1.3 Start Quick setup -1.1.3 Stable Full setup  ELive System System Control  Control  Control  Devices  Device Control  Device	Class: PENKO.Device root.EU-800d.Access.Alibi Path: 1.1.1.8.2		
	Number of entries	6	
	Record Tag/Code		
	Date/Value		
	Time/Unit	Clear	
	Discover Import Proper	ties (CSV)	

### Number of entries

The total number of alibi records.



#### **Entry Number**

Enter the number of the desired record and conform with Enter or the Apply button. The record is shown.

### Record

The type of record. A record can be a **Header** or a **Data** record. A header records is the title of the record and shows a tag, date and time. A header has several data records that show the code, value and unit of the stored value.

## Tag/Code

Tag shows a tag the header record belongs to. By default this is "Alibi 001" and cannot be changed. Code shows the type of value stored in the data record.

### Date/Value

Date shows the date of the header record. Value shows the stored measurement of the data record.

## Time/Unit

Time shows the time of the header record. Unit shows the stored unit of the data record.

### UID

Every record has a Unique ID number, the UID.

### Clear

This will clear the total alibi memory.

When the inut with the print function is activated, 2 records are added to the alibi memory. This is 1 header and 1 data record. Example:

Number	Record	Tag/Code	Date/Value	Time/Unit	UID
1	Header	Alibi 001	15-03-16	09:43:20	3298435072
2	Data	Gross	0.732	kg	1755848705



## 7.2 Event Log

System events are generated automatically by the system. These events can be seen but cannot be erased. Erasing of the records can only be performed by PENKO. Events are created for logging software updates, calibration changes, parameter changes, clearing the alibi memory, etc.

To see the event log, go to the Access menu and select Event Log.

E PENKO E Device root E - EU-800d	Class: PENKO.Device root.EU-800d.Access.Event Log Path: 1.1.1.8.3		
-1.1.1.1 Name = -1.1.1.2 Start Quick setup -1.1.1.3 Enable Full setup ⊕ Live ⊕ Control ⊖ Access ⊕ Albi ⊕ Event Log	Number of entries  Futry Number  Record  Tag/Code  Date/Value  Time/Unit  UID	4 4 Header Alibi Cleared 11-03-16 14:45:26 1891893251	
	Discover Import Proper	ties (CSV) Apply	

## Number of entries

The total number of event logs.

### **Entry Number**

Enter the number of the desired record and conform with Enter or the Apply button. The record is shown.

### Record

The type of record. An event log is always a **Header** record.

## Tag/Code

This shows the stored event, like Software Update, Set Clock, etc.

## Date/Value

This shows the date of the event.

## Time/Unit

This shows the time of the event.

## UID

Every record has a Unique ID number, the UID.


### 8 Firmware update

Update the application firmware by USB connection.

Connect the EU-800d to the computer through USB. Start PI Mach II. Set communication to USB. Also see the Pi Mach II manual.



Start the Firmware Update Manager.

🧐 <u>F</u>irmware Update Manager

Click Open and select the PIP file.

避 <u>O</u>pen...

Click Search for devices and select the device with source "0".

Search for devices

Use double click or the arrow button to move the device from the Source List to the Destination List and click OK.

Two Phase Selection Dialog		×
Source List: 1	Destination List: 0	OK Cancel
0	68 255	Search





Now click Firmware Update to start the update.

🛂 Firmware update

The EU-800d will reboot automatically and the Firmware Update Manager will show Updated.

Device	Id-code	Softw Version	Status
✓ 0 ·		0631 V:0100	Updated



### 9 Backup and restore

With the EU-800d it's possible to make a backup of the software as it's installed in the device. The software will be saved as an FDI file which stands for Flex Data Image. The Backup data assures that if the device fails, a replacement device can be programmed as a copy of the original device. In case of multiple devices which have to be configured similarly, one device can be programmed, and a backup of this device can be used to program the other device.

### 9.1 Backup

To back up the device, open Pi Mach II. Go to MENU  $\rightarrow$  ENVIRONMENT  $\rightarrow$  BACKUP DEVICE.



A save dialog is shown. Choose a destination and filename, and click SAVE. The image will be created and saved to this destination.

### 9.2 Restore

To restore the device, open Pi Mach II. Go to MENU  $\rightarrow$  ENVIRONMENT  $\rightarrow$  RESTORE DEVICE.



An open dialog is shown. Select the backup file, and click OPEN. The image will be programmed into the device, and the device will restart.

### 9.3 Progress

The progress of reading and writing is shown in a progress bar. The action can fail by a loss in communication between the PC and the controller. In that case the progress bar will be stuck somewhere between 0 and 100 %. In this case, check the communication and retry.



Erasing the Flash takes a while. Do not close the application until ready.		
Restore progress 30 %		
	Abort	Close



### 10 Standard factory settings

Description	Display	Value	Your setting
Weigher	Name		
	Max Load	10.009 kg	
	Sample Rate	1600/s	
	Step	1	
	Decimal point	000.000	
	Unit label	kg	
Stable condition	Range	0.002 kg	
	Time	1.00 s	
Zero tracking	Range	0.000 kg	
	Step	0.000 kg	
	Time	0.00 s	
Range / Interval	Range	0 Parts	
	Max Step	1	
	Mode	Multi Range	
Filter	Overall Filter	0 dB	
	Filter type	Dynamic	
	Cutoff Frequency	2.5 Hz	
	Moving average	50 Hz	
Display	Display Rate	25/s	
	Filter Range	0.000 kg	
	Filter Damping	0 dB	
	Zero Suppress	0.000 kg	
	Indicator	WEIGHER	
Transducer calibration	Max load	10.000 kg	



	Output (18)	0.00000 mV/V	
	Zero balance (18)	0.00000 mV/V	
Geometric recalibration	Latitude	52.00 degrees	
	Elevation	0 m	
Input range	Mode	Unipolar	
	Range	2 mV/V	
	Offset	0	
RS485	Protocol	MODBUS-RTU	
	Address	0	
	Stopbits	1	
	Parity	None	
	Baudrate	9600	
	Indicator	0	
Digital inputs	Function (13)	None	
Digital outputs	Level 1	0.000 kg	
	Level 2	1.000 kg	
	Level 3	2.000 kg	
	Level 4	3.000 kg	
	Hysteresis (18)	0.010 kg	
	Function (18)	Weigher	
Analog output	Minimum level	0.000 kg	
	Maximum level	10.000 kg	
	Function	Weigher	



### **11 Error codes**

Error code	Description	Solution
2001	Parameter error	Invalid entry, choose valid value
2005	Input value is not valid	Invalid entry, choose value within range
2101	Weigher not stable	Wait for stable and try again
2102	Parameter exceeds maxload	Remove load / edit max load setting
2103	Parameter below zero	Check if scale is blocked
2104	Not in zero range	Remove load
2105	Arithmetic overflow occurred	Change calibration levels
2106	A/D reads all 1's	Check load cell connection
2107	A/D reads all 0's	Check load cell connection
2108	Gain ref. < zero ref.	Change calibration levels
2109	Gain > 0.99984741211	Change calibration levels
2110	Save error	Contact PENKO
2111	Flash ROM exhausted	Contact PENKO
2112	Error on header creation	Contact PENKO
2113	Error on date write	Contact PENKO
2114	Header validation failed	Contact PENKO
2115	De-active old data fail	Contact PENKO
2116	Load errors	Contact PENKO
2117	Item not found in store	Contact PENKO
2118	Error in stored data	Contact PENKO
2119	Bad calibration	Change calibration levels
2120	Action not enabled	-
2121	Multi-point not found	Add multi-point calibration
2122	Calibration table full	Remove calibration points
2123	Not allowed, tare active	Deactivate tare
2124	Action not allowed	-
2125	ADC no power	Check power supply
CCCCCC	No proper calibration available	Check calibration setting
υυυυυυ	Underflow	Check load cell
		Check platform construction
000000		
000000	Overflow	Check load cell Check platform construction
		Check platform construction
	Display overflow; Exceed	Reduce load on platform
	maximum display value (max. load)	



### **12 Specifications**

Туре	Description
Wiring	With sense
Type of sense	Passive
Power supply	18-32 VDC; 4 W max.
Excitation voltage	5 VDC
Sensitivity	0.1 μV/d
Selectable ranges	1 mV/V   1,5 mV/V   2 mV/V   2,5 mV/V   3 mV/V
Input voltage @3mV/V	-16 mV to 16 mV
A/D Conversion speed	1600/s
Max. load cell impedance	1200 Ω
Min. Load cell impedance	43,75 Ω
Max. no. of load cells 350 $\boldsymbol{\Omega}$	8
Max. no. of load cells 1.000 $\Omega$	22
Max. number of d	10.000
Display resolution	100.000
Internal resolution	24 bits
Display steps	1,2,5,10,20,50,100,200
Display size	6 x 7 segments red LED 0.4 inch (10.2 mm)
Digital inputs (3)	18 - 28 VDC, PNP or NPN
Digital outputs (4)	Max. 35V/0.5A, PNP or NPN
Analog output	4 - 20 mA, 10.000 d
Operating temperature	-10°C to +40°C
Storage temperature	-20°C to +70°C
Relative Humidity	Max. 85 % non-condensing
Protection class	See table below
Weight	2150 g



Side view





Top view



### **Protection degree**

IP	D <sub>3</sub>	<b>D</b> <sub>2</sub>	D <sub>1</sub>	
5.4	plugged – IP 68	plugged – IP 68	sensor connection – thread without sealing – IP 54	
54	ATEX cable gland IP66	ATEX cable gland IP66		
	closed – IP 68	closed – IP 68	sensor connection	
68	ATEX cable gland IP68	ATEX cable gland IP68	– sealed thread – IP 68	



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### Appendix I - Menu structure

Main menu	Setpoint function (FUN)	14	Setpoint 14 function	indicator 119
	Setpoint action (ACN)	14	Setpoint 14 hysteresis	value
	Analog output (DAC)		Manual control 0%	set
		2	Manual control 100%	set
		3	Manual control level	0100%
		4	Analog output function	- indicator 119
		5 -	Minimum level	value
		6	Maximum level	value
	RS485	- 1 -	Protocol	none/mb-rtu/mb-as ascii/npv-slave
		2 -	Address	0255
		3	Stopbits	- 1/2
		4	Parity	none/odd/even/
		5		mark/space
			Baudrate	— 1200115k2
		6	Indicator	— <u>130</u>
	Indiactor (IND)	_ 1 _	Maxlood	uchus
	Indicator (IND)		Maxload	value
		2 -	Stable range	value
		3	Stable time	seconds
		4	Digital overal filter	option 08
		5	Step size	size 1500
		6	Decimal point	option 05
		7	Display rate	150/s
		8	Unit	lbs/kg
		9	Sample rate	101600/s
		0	Gampie late	101000/3
	Range (RNG)	- 1 -	Range	value
		2	Max step	size 1500
		3		
		3	Multi interval	on/off
	Filter (FIL)	- 1 -	Display filter range	value
		2	Display filter damping	option 08
				_
	<b>_</b>	3 -	Display zero suppress	- value
	V	4	Indicator to display	- indicator 119

Digital filter (DSF)	1 2 1 3	Filter type Cut off frequency	
Pre calibration (PCL)	1	Cut off frequency	off or 140Hz
Pre calibration (PCL)	3 -		
Pre calibration (PCL)		Display zero suppress	value
	1 -	Input mode	unipolar/bipolar
	2 –	Input range	13mV/V
	3 -	Offset	value
	4 -	Recall	set
Calibration (CAL) -	1 -	Add collision point	value
Calibration (CAL)	1	Add calibration point	
	2	Weigher information	info
	3 -	Show calibration points	info
	4 -	Deadload	value
	5 -	Show CAL code	info
Theoretic calibration (TCL)	1	Maxload	value
	2	Output transducer 1	mV/V
	3 -	Output transducer 2	mV/V
	4 -	Output transducer 3	mV/V
	5	Output transducer 4	mV/V
Geo calibration (GCL)	1 -	Origin latitude	degrees
	2	Origin elevation	meters
	3 -	Location latitude	degees
	4	Location elevation	meters
Date/time (CLO)	1 -	Date	DD.MM.YY
	2 -	Time	HH.MM.SS
			-
Recall (RCL)	1 -	Reset device	set
	2	Restore parameters	set
-			
	3	Restore all	set



### **Appendix II - Communication protocols**

The following communication protocols are available:

Protocol	Available on port	Description
Modbus ASCII/RTU	RS485	Modbus protocol over RS485 used to
		connect to PLC.
PENKO ASCII	RS485	PENKO protocol over RS485.
	USB	PENKO protocol over USB connection used
PENKO TP / PDI		for communication between the device
		and the configuration software.

Protocol descriptions and needed files can be downloaded from the PENKO website.



www.penko.com





Remarks:





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