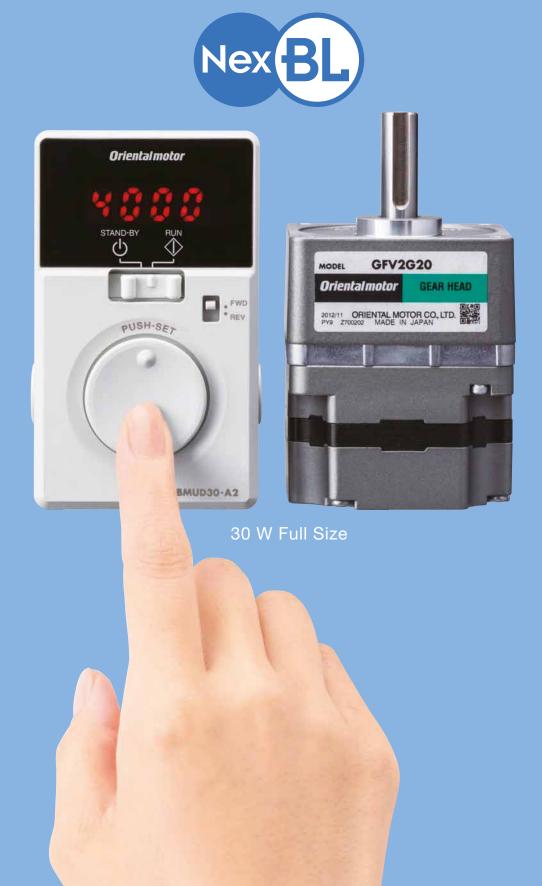
**Oriental motor** 

Brushless Motor and Driver Packages



### Easy Speed Control with Spin and Push



### Easy Speed Control with Spin and Push

A settings dial designed for easy speed control.

Once the motor and the driver are connected, all you do for this simple wiring is turn on the switch Introducing the **BMU** Series, which is committed to your ease of use of the product. The new brushless motor NexBL is a compact, high-power, and high-efficiency motor. It offers the highest standards of speed control now at an affordable price.



Brushless Motor and Driver Packages







NexBL is a new brushless motor from Oriental Motor The entire structure has been innovated in pursuit of the optimal performance from a motor. It realizes a first-ever compactness, high power and high efficiency for a motor.

 Spin and push. Easy speed control.
 Easy wiring. Quick start.
 Opening the panel reveals extensive functions.
 New Brushless Motor–NexBL.





# Spin and push. Easy speed control.



### Turn the dial, and set the speed to your desired speed.

Turning the settings dial has a similar feeling as with clicking. Turning the dial clockwise increases the speed, while turning it counterclockwise reduces the speed.



#### Pushing the dial sets the speed.

Once the desired value for speed is set. When power is re-supplied after setting the speed, the motor operates according to the set speed.



### Turning the dial slowly changes the speed by 1 r/min.

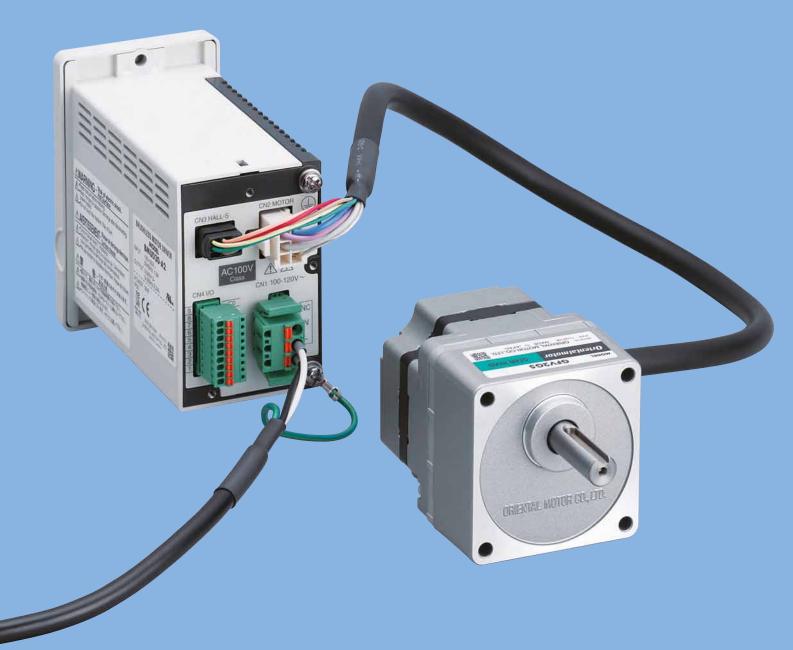
While observing the indication, turn the dial slowly to the right, and notice that speed increases by 1 r/min. While turning it slowly to the left, notice that the speed decreases by 1 r/min.



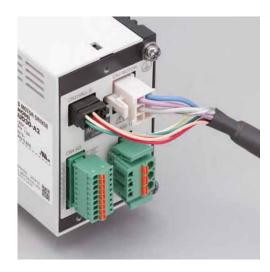
#### The dial operation can be locked.

After the speed has been set, it can be changed by operating the dial. The dial can be locked to prevent changes in speed with the dial operation.  $\rightarrow$ Page 9

### Nex BL BMU Series Connection and Activation



# (2) Easy wiring.Quick start.



### The motor and driver can be easily connected.

The motor connector is compact, and it easily passes through the flexible conduit and the cable gland..



### The power and I/O connectors are of the screwless type.

There is no need for welding or special crimp tools when connecting the power connector and the I/O connector. While pushing the orange button, just insert the lead wire.



### With only one switch, the motor can be started immediately.

The motor starts when the switch is set to the "RUN" position.

If set to the "STAND-BY" position, the motor decelerates to a stop.

The motor can be easily operated with the operating switch on the front side.



# The rotation direction of the motor can be changed with easy operation.

Switching the rotation direction is possible with the rotation direction switch. It is possible even when the motor is in operation.







## ③ Opening the panel reveals the extensive functions.

### Various functions can be set on the driver.

#### (Typical functions that can be set while the front panel is opened)

- Motor Startup/Stop\*
- Adjustment of operating speed\*
- Setting the operating speed\*
- Selecting the rotation direction\*
- Changing the indication
- Operating speed indication when the speed reduction/speed increasing ratio is set
- Setting the acceleration/deceleration time
- Dial operation lock
- Speed Setting for the 4-Speed Operation
- Speed limits setting.
- Validating the external operating signals
- External input/output signal allocation
- Setting the overload alarm detection time except during axial lock

Easy holding function for Output shaft.

\*Setting is possible even if the front panel is attached



#### Load factor can be shown.

With the rated torque of the motor at 100%, the load factor can be expressed in percentage (40-200%). The load condition during the start-up, as well as the load condition due to the aging deterioration of the equipment can be confirmed.



Indication at a load factor of 50%

#### Lock the dial operation.

This prevents the undesired changes in the speed and the changes or deletion of data with the operation of the dial.

#### Setting the Lock Function

At the main screen for each operating mode, press the "MODE" key for 5 seconds or more. When "Lk" appears, the lock function is activated.



Cancelling the lock function

Return to the main screen, and press the "MODE" key for 5 seconds or more. When "UnLk" is indicated, the lock function has been cancelled.

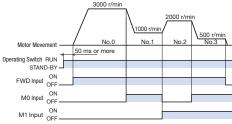


#### You can set to "Front Panel Operation Invalid"

When operating using external signals, the front panel switch operation can be set to "Invalid".

#### 4-Speed Setting.

Operation in 4 speeds is possible by setting the data to operating data No.0, No.1, No.2, or No.3, and switching the input of the M0 terminal.



Note: When operating in 4-speed settings, the rotation direction of the motor using external input signals cannot be changed.

### Indicates the transport speed of the conveyor.

The conveyor gear ratio is computed and set into the "gear ratio" parameters, and the conveyor transport speed can be indicated. As the conveyor transport speed can be checked directly, it is convenient for frequent changing of setup and other processes involved in the manufacturing process.

### Sets the acceleration time and deceleration time.

The acceleration time and deceleration time can be digitally set, in addition to adjusting them with an acceleration/deceleration time potentiometer.

• Setting Range:  $0.0 \sim 15.0 \sec($  linitial value:  $0.5 \sec)$ For the digital setting, the acceleration time and deceleration time are each set independently. Therefore, the time can be freely set according to the desired tact time of the equipment.

### Set the upper and lower rotation speed limits.

The upper and lower limits for the speed control range can be set. The speed limits can be set with the monitor mode or data mode.

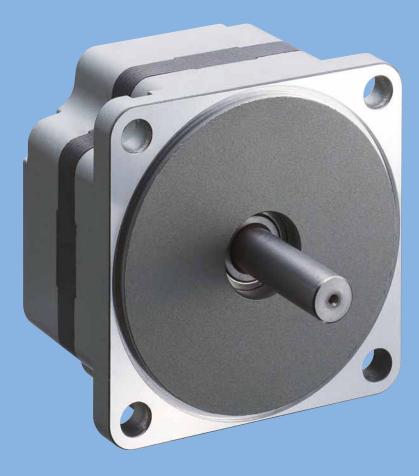
#### Output shaft is held when stopped.

When the motor is stopped, the load can be electrically held. (Holding force is up to 50% of the rated torque.)

Note

If the electrical power supply to the driver is turned OFF, the holding force dissipates. This cannot be used to prevent a fall during a power outage

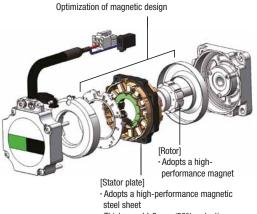




# (4) New Brushless Motor NexBL

### NexBL designed for compactness, high power and high efficiency

An optimal magnetic design and high-performance material enable a NexBL stator plate thickness of just 11.2 mm. This slimness realizes a highly efficient power unit that outputs 120 W. Compared with the conventional brushless motor of the same output power, the stator plate thickness is only half of the conventional one (For motors with a frame size of 90 mm). Moreover, the use of high-performance material reduces the amount of material used, therefore reducing costs.

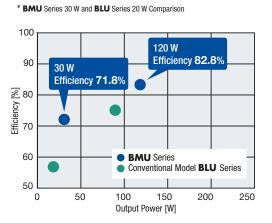


Thickness 11.2 mm (50% reduction compared with the conventional model)

# Substantial improvement in the efficiency of the motor and driver package

**BMU** Series enabled a substantial improvement in the efficiency of the motor and driver package.

A maximum of 15% improvement of the efficiency of the package\*

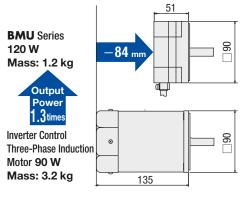


#### NexBL and Three-Phase Motor Comparison

Weight reduction and slim body are realized with the high-power NexBL. For example, compared with the three-phase induction motor of frame size 90 mm, NexBL has the following advantages:

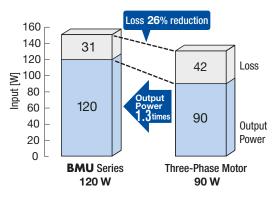
#### Downsizing of the Equipment

Motor mass of 2.0 kg (Approx. 63%) reduction, and overall length is 84.6 mm (Approx. 63%) shorter. On the other hand, motor output power increases by 1.3 times. A lightweight, slim, high-power motor enables downsizing of the equipment.



#### Energy Savings of the Equipment

Motor output power is increased by 1.3 times, while motor loss is reduced by 26%. This motor is effective for energy savings of the equipment.



### The highest standards of speed control now available at an affordable price.

#### Highest standards of speed control.

#### Maximum Speed of 4000 r/min

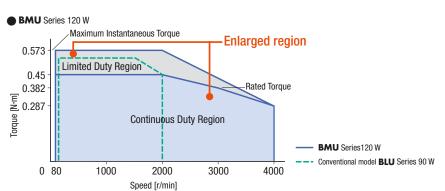
Speed ratio 1:50 (2.5 times of the conventional ratio) BMU Series has a maximum speed of 4000 r/min. Speed ratio of 1:50 (80 to 4000 r/min) is realized. Speed regulation has been greatly improved from  $\pm$  0.5% to  $\pm$  0.2%. With the highest standards of speed control, we respond to our customers' demands.

#### User-friendly features and extensive functions, all available at an affordable price.

For example, the set price for **BMU** Series of frame size 60 mm is much cheaper compared with an equivalent conventional model

#### New gearhead combination type.

With the gearhead's boss section and cut on the installation surface, the installation accuracy with the equipment has been improved. It also achieved lower noise, compared with the conventional model. Since the motor and gearhead comes in a preassembled combination type, it can easily be attached to the equipment. The motor, driver, and gearhead comes together, saving time and effort for procurement.



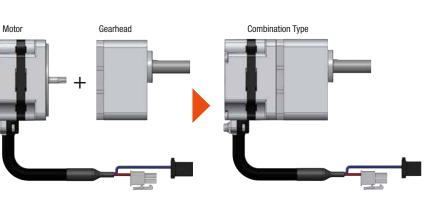


**Conventional Model BLU** Series Output Power: 20 W Gearhead gear ratio: 5 Permissible torque: 0.45 N·m
 Speed range: 20~400 r/min



**BMU** Series Output Power: 30 W Gearhead gear ratio: 5 Permissible torque: 0.45 N·m Speed range: 16~800 r/min

For price and lead time please contact the nearest Oriental Motor office, or sit our website



#### Lineup

			Package			
Motor	Frame Size	Output Power	Туре	Driver	Power Supply Voltage	Connection Cable
1	60 mm	30 W				
Combination Type	Combination Type 80 mm Round Shaft Type 60 mm	60 W	Standard (IP40) or IP65	0	Single-Phase 100-120 VAC Single-Phase 200-240 VAC Three-Phase 200-240 VAC	1 m, 2 m, 3 m or not included
Round Shaft Type*	90 mm	120 W				

For some round shaft types, the shaft is processed with a shaft flat.
 A separate catalogue, exclusive to the 200 W output type, is available. For details, contact the nearest branch office, business office or customer support center.

## Brushless motors, which are suitable for speed control, has the following features:

In a brushless motor, there are no brushes, and thus no physical contact that could lead to frictional energy losses. While DC motors use a brush and commutator to rotate and require regular maintenance, brushless motors rotate by the ON/OFF operation of the drive circuit transistor based on the signals detected by the hall effect IC (magnetic sensor).

Brushless motors are more expensive to design and manufacture, but they are typically more efficient than brushed motors.

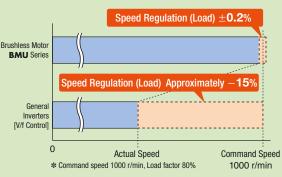
This leads to:

- Less maintenance and longer life
- More power
- Longer runtime

#### Stable speed control

Brushless motors compare the setting speed with the speed feedback signals from the motor at all times, and adjusts the motor's applied voltage. For this reason, even if the load changes, stable rotation is performed from low speed to high speed. Inverter-controlled (V/f control) three-phase induction motors do not perform, so the speed will drop significantly when the load increases. Brushless motors are recommended for applications that require speed stability.

Speed change comparison at a load factor of 80% (Reference values)\*



#### Wide Speed Control Range

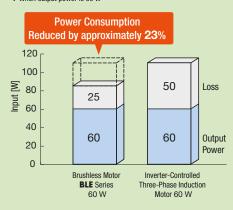
The brushless motor has a broader speed control range compared to AC speed control motors and inverters. Unlike AC speed control motors, the torque at low speed is not limited, so brushless motors are suited to applications that require a constant torque from low speed to high speed.

Product Group	Speed Control Range*	Speed Ratio
Brushless Motor BMU Series	80~4000 r/min	1:50
Inverter-Controlled Three-Phase Induction Motor	200~2400 r/min	1:12
AC Speed Control Motor	50 Hz : 90~1400 r/min 60 Hz : 90~1600 r/min	1:15 1:17

\* The speed control range varies depending on the model.

#### Contributes to Energy Savings

Brushless motors, which incorporate permanent magnets in the rotor, generate little secondary loss from the rotor. This allows for power consumption to be reduced by approximately 23% compared with inverter-controlled three-phase induction motors.\* This contributes to energy savings with the equipment. \* When output power is 60 W



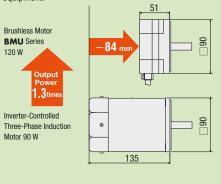
### Equipped with protective functions that output an alarm

Various protective functions such as overload protective function and overvoltage protective function are equipped. An alarm is output when a protective function activates.

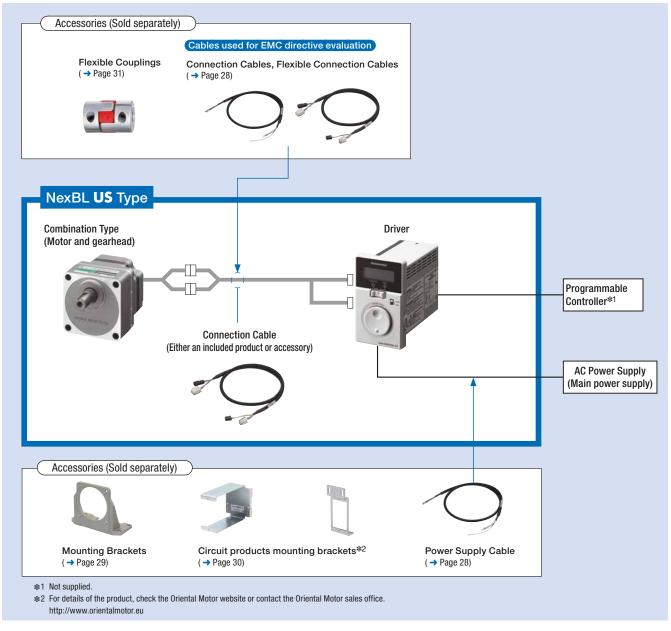


#### Compact and Powerful

Brushless motors have slim body and provide high power due to permanent magnets being used in the rotor. For example, the overall length is 84 mm shorter and the output power is 1.3 times higher than that of threephase induction motors with a frame size of 90 mm. Using brushless motors can contribute to downsizing of equipment.



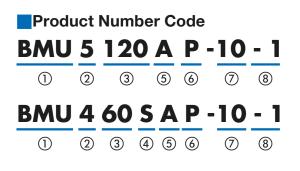
#### System Configuration



#### System Configuration

<b>BAALL</b> Cavias		Sold Separately				
<b>BMU</b> Series Combination Type - Parallel Shaft	+	Connection Cable (7 m)	Mounting Bracket	Flexible Coupling	Circuit Products Mounting Brackets	
BMU5120A-10-3		CC07BL2	SOL5M8F	MCL551818	MAFP05V	

The system configuration shown above is an example. Other combinations are available.



D	Туре	BMU: BMU Series
2)	Frame Size	2: 60 mm 4: 80 mm 5: 90 mm
)	Output Power (W)	30: 30 W 60: 60 W 120: 120 W
)	Identification number	S
)	Power Supply Voltage	A: Single-Phase 100-120 VAC C: Single-Phase, Three-Phase 200-240 VAC
)	Motor Degree of Protection	None: Standard type (IP40 specification) <b>P</b> : IP65 Specification
)	Gear Ratio/Shaft Configuration	Number: Gear Ratio for Combination Types <b>A</b> : Round Shaft Type <b>AC</b> : Round Shaft Type (Shaft flat processed)
)	Connection Cable Length (Included)	Number: Included Connection Cable Length -1: 1 m -2: 2 m -3: 3 m None: Connection cable not included

■ Examples of product names that indicate connection cable availability and length Includes a 3 m connection cable → BMU5120A-10-3 No connection cable → BMU5120A-10

#### Product Line

Combination Type The combination type comes with the motor and its dedicated gearhead pre-assembled. This simplifies mounting in equipment. Motors and gearheads are also available separately to facilitate changes in motor and gearhead combinations and if spare gearheads are required.

You may purchase the motor unit with connection cable (1 m, 2 m, 3 m). For price and lead time please contact the nearest Oriental Motor office, or visit our website.

#### Combination Type – Parallel Shaft Gearhead

♦ Standard Type (IP40 specification)

Output Power	Power Supply Voltage	Product Name	Gear Ratio
30 W	Single-Phase 100-120 VAC BMU230A-		5, 10, 15, 20 30, 50, 100 200
30 W	Single-Phase, Three-Phase 200-240 VAC BMU230C-		5, 10, 15, 20 30, 50, 100 200
60 W	Single-Phase 100-120 VAC	BMU460SA-⊡⊘	5, 10, 15, 20 30, 50, 100 200
	Single-Phase, Three-Phase 200-240 VAC	BMU460SC-⊡◇	5, 10, 15, 20 30, 50, 100 200
120 W	Single-Phase 100-120 VAC	BMU5120A-□◇	5, 10, 15, 20 30, 50, 100 200
	Single-Phase, Three-Phase 200-240 VAC	BMU5120C-□◇	5, 10, 15, 20 30, 50, 100 200

#### ◇IP65 Specification

Output Power	Power Supply Voltage	Product Name	Gear Ratio
30 W	Single-Phase 100-120 VAC	BMU230AP-□◇	5, 10, 15, 20 30, 50, 100 200
30 W	Single-Phase, Three-Phase 200-240 VAC	BMU230CP-□◇	5, 10, 15, 20 30, 50, 100 200
co.w	Single-Phase 100-120 VAC	BMU460SAP-□◇	5, 10, 15, 20 30, 50, 100 200
60 W	Single-Phase, Three-Phase 200-240 VAC	BMU460SCP-□◇	5, 10, 15, 20 30, 50, 100 200
120 W	Single-Phase 100-120 VAC	BMU5120AP-□◇	5, 10, 15, 20 30, 50, 100 200
	Single-Phase, Three-Phase 200-240 VAC	BMU5120CP-□◇	5, 10, 15, 20 30, 50, 100 200

- The following items are included in each product.

Motor, driver, gearhead\*1, connection cable\*2, CN1 connector, CN4 connector, installation screws\*1, machine key\*1, operating manual, start up guide

\*1 Combination type only

 $\ensuremath{\ast} 2$  Only with types supplied with a connection cable

lacksquare A number indicating the gear ratio is specified in the box  $\Box$  in the product name.

When the accessory connection cable is supplied, a number indicating the length of the cable, -1 (1 m), -2 (2 m), or -3 (3 m), is specified in the box  $\bigcirc$  in the product name. For motors with a degree of protection of IP65 specification, **P** is specified where the box  $\blacksquare$  appears in the product name.

#### Round Shaft Type

♦ Standard Type (IP40 specification)

Output Power	Power Supply Voltage	Product Name
30 W	Single-Phase 100-120 VAC	BMU230A-A🔷
30 W	Single-Phase, Three-Phase 200-240 VAC	BMU230C-A🛇
60 W	Single-Phase 100-120 VAC	BMU260A-A🛇
60 W	Single-Phase, Three-Phase 200-240 VAC	BMU260C-A
120 W	Single-Phase 100-120 VAC	BMU5120A-A🛇
120 W	Single-Phase, Three-Phase 200-240 VAC	BMU5120C-A🛇

#### $\bigcirc$ IP65 Specification

Output Power	Power Supply Voltage	Product Name
30 W	Single-Phase 100-120 VAC	BMU230AP-A🛇
50 W	Single-Phase, Three-Phase 200-240 VAC	вми230ср-а🛇
60 W	Single-Phase 100-120 VAC	BMU260AP-A🛇
OU W	Single-Phase, Three-Phase 200-240 VAC	ВМU260СР-А🛇
100 W	Single-Phase 100-120 VAC	BMU5120AP-A🛇
120 W	Single-Phase, Three-Phase 200-240 VAC	BMU5120CP-A

The following items are included in each product.

Motor, driver, gearhead\*1, connection cable\*2, CN1 connector, CN4 connector,

installation screws\*1, machine key\*1, operating manual, start up guide

\*1 Combination type only

\*2 Only with types supplied with a connection cable

#### Lineup of Other Products

Round Shaft Type

Shaft Flat Cutout on Output Shaft

For details of the products processed with a shaft flat cutout, check the Oriental Motor website or contact the Oriental Motor sales office.

#### Motor and Driver Combinations

#### Combination Type – Parallel Shaft Gearhead

Output Power	Power Supply Voltage	Product Name	Combination Motor Product Name*	Motor Product Name	Gearhead Product Name	Driver Product Name
30 W	Single-Phase 100-120 VAC	BMU230A <b>□</b> -□◇	BLM230	BLM230 -GFV2	GFV2G	BMUD30-A2
30 W	Single-Phase, Three-Phase 200-240 VAC	BMU230C <b>□</b> -□◇		BLWZ30E-GFVZ		BMUD30-C2
60 W	Single-Phase 100-120 VAC	BMU460SA <b>□</b> -□◇	BLM46052	BLM460S -GFV2	GFV4G□	BMUD60-A2
60 W	Single-Phase, Three-Phase 200-240 VAC	BMU460SC <b>□</b> -□◇	DL/140032	DLW40U3EFGFV2	Grv4GL	BMUD60-C2
100 W	Single-Phase 100-120 VAC	BMU5120A■-□◇	BLM5120 -□2	BLM5120 -GFV2	GFV5G□	BMUD120-A2
120 W -	Single-Phase, Three-Phase 200-240 VAC	BMU5120C <b>□</b> -□◇		DLWG120E-GFV2	GEVOGL	BMUD120-C2

\*For combination motors, the product name applies to the motor and gearhead combination.

#### Round Shaft Type

Output Power	Power Supply Voltage	Product Name	Motor Product Name	Driver Product Name
30 W	Single-Phase 100-120 VAC	BMU230A <b>□</b> -A◇	BLM230-A2	BMUD30-A2
30 W Single-Phase, Three-Phase 200-240 VA		BMU230C <b>□</b> -A◇	BLW230E-AZ	BMUD30-C2
60 W	Single-Phase 100-120 VAC	BMU260A <b>-</b> A	BLM260-A2	BMUD60-A2
	Single-Phase, Three-Phase 200-240 VAC	BMU260C <b>□</b> -A◇	BLW200E-AZ	BMUD60-C2
120 W	Single-Phase 100-120 VAC	BMU5120A <b>□</b> -A◇	BLM5120-A2	BMUD120-A2
120 W -	Single-Phase, Three-Phase 200-240 VAC	BMU5120C <b>□</b> -A◇	DLMIJIZU -AZ	BMUD120-C2

 $<sup>\</sup>blacksquare$  A number indicating the gear ratio is specified in the box  $\Box$  in the product name.

When the accessory connection cable is supplied, a number indicating the length of the cable, -1 (1 m), -2 (2 m), or -3 (3 m), is specified in the box  $\bigcirc$  in the product name. For motors with a degree of protection of IP65 specification, **P** is specified where the box  $\blacksquare$  appears in the product name.

#### Specifications

#### O30 W RoHS

Product	Combination Type – Para	llel Shaft Gearhead	BMU230A□-□�	BMU230C□-□◇	
Name	Round Shaft Type		BMU230A🗆-A🛇	BMU230C□-A◇	
Rated Output Power (Continuous) W		W	3	0	
Rated Speed		r/min	30	00	
Rated Torque		N∙m	0.0	96	
Maximum Insta	ntaneous Torque	N∙m	0.1	44	
Rotor Inertia		J: ×10 <sup>-4</sup> kg•m²	0.0	042	
Round Shaft Ty	pe Permissible Inertia	J: ×10 <sup>-4</sup> kg∙m²	1.8		
Speed Control I	Range		80~4000 r/min (Speed ratio 1:50)		
		Load	$\pm$ 0.2% or less: Conditions 0 $\sim$ rated torque, rated speed, rated voltage, normal temperature		
Speed Regulati	on	Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15{\sim}+10\%$ , rated speed, no load, normal temperature		
		Temperature	$\pm$ 0.2% or less: Conditions Operating ambient temperature from 0~+40°C, rated speed, no load, rated voltag		
	Rated Voltage	VAC	Single-Phase 100-120	Single-phase 200-240/Three-phase 200-240	
	Permissible Voltage Range		-15~	+10%	
Power Supply Input	Frequency	Hz	50/	/60	
	Permissible Frequency Range		±{	5%	
	Rated Input Current	A	1.2	Single-phase: 0.7/ Three-phase: 0.38	
	Maximum Input Current	A	2.0	Single-phase: 1.2/ Three-phase: 0.75	

<b>60 W</b>	/ (RoHS)
-------------	----------

●60 W (Ro	нѕ			(		
Product	Combination Type – Para	llel Shaft Gearhead	BMU460SA□-□◇	BMU460SC□-□◇		
Name	Round Shaft Type		BMU260A🗆-A🔷	BMU260C <b>□</b> -A◇		
Rated Output P	ower (Continuous)	W	6	0		
Rated Speed		r/min	30	00		
Rated Torque		N∙m	0.1	91		
Maximum Insta	intaneous Torque	N∙m	0.2	287		
Rotor Inertia		J: ×10 <sup>-4</sup> kg·m <sup>2</sup>	0.0	0.082		
Round Shaft Ty	pe Permissible Inertia	J: ×10 <sup>-4</sup> kg·m <sup>2</sup>	3.75			
Speed Control	Range		80~4000 r/min (Speed ratio 1:50)			
		Load	$\pm$ 0.2% or less: Conditions 0 $\sim$ rated torque, rated speed, rated voltage, normal temperature			
Speed Regulati	on	Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15 \sim +10\%$ , rated speed, no load, normal temperature			
		Temperature	$\pm 0.2\%$ or less: Conditions Operating ambient temperature from 0 $\sim$ +40°C, rated speed, no load, rated v			
	Rated Voltage	VAC	Single-Phase 100-120	Single-phase 200-240/Three-phase 200-240		
	Permissible Voltage Range		-15~	+10%		
Power Supply Frequency		Hz	50/60			
Input	Permissible Frequency Range		±5%			
	Rated Input Current	A	1.7	Single-phase: 1.0/ Three-phase: 0.52		
	Maximum Input Current	A	3.3	Single-phase: 1.9/ Three-phase: 1.1		

#### ●120 W RoHS

<b>1</b> 20 W 🖲	oHS					
Product	Combination Type – Para	llel Shaft Gearhead	BMU5120A□-□◇	BMU5120C□-□◇		
Name	Round Shaft Type		BMU5120A□-A◇	BMU5120C□-A◇		
Rated Output P	ower (Continuous)	W	12	20		
Rated Speed		r/min	30	00		
Rated Torque		N∙m	0.3	882		
Maximum Insta	ntaneous Torque	N∙m	0.5	573		
Rotor Inertia		J: ×10 <sup>-4</sup> kg•m <sup>2</sup>	0.	0.23		
Round Shaft Ty	pe Permissible Inertia	J: ×10 <sup>-4</sup> kg∙m²	5.6			
Speed Control I	Range		80~4000 r/min (Speed ratio 1:50)			
		Load	$\pm$ 0.2% or less: Conditions 0 $\sim$ rated torque, rated speed, rated voltage, normal temperature			
Speed Regulati	on	Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15{\sim}+10\%$ , rated speed, no load, normal temperature			
		Temperature	$\pm$ 0.2% or less: Conditions Operating ambient temperature from 0 $\sim$ +40°C, rated speed, no load, rated volta			
	Rated Voltage	VAC	Single-Phase 100-120	Single-phase 200-240/Three-phase 200-240		
Permissible Voltage Range			-15~+10%			
Power Supply	Frequency	Hz	50/60			
Input	Permissible Frequency Range		±5%			
	Rated Input Current	A	3.3	Single-phase: 2.0/ Three-phase: 1.1		
	Maximum Input Current	A	6.8	Single-phase: 4.1/ Three-phase: 2.0		

The values correspond to each specification and characteristic of a stand-alone motor. The speed-torque characteristics show the values when rated voltage is applied.  $\blacksquare$  A number indicating the gear ratio is specified in the box  $\square$  in the product name.

If the degree of protection of the motor is IP65 specification, **P** is entered where the box 🗌 is located within the product name.

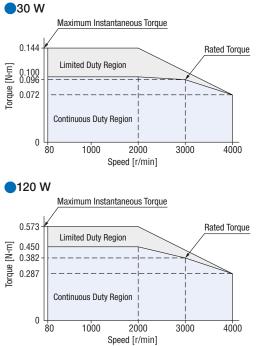
When the accessory connection cable is supplied, a number indicating the length of the cable, -1 (1 m), -2 (2 m), or -3 (3 m), is specified in the box 🗇 in the product name.

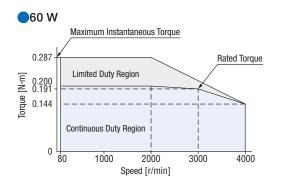
17

CE

#### Speed – Torque Characteristics

Continuous Duty Region : Continuous operation is possible in this region. Limited Duty Region : This region is used primarily when accelerating.





The values correspond to each specification and characteristic of a stand-alone motor. The speed-torque characteristics show the values when rated voltage is applied.

#### Common Specifications

Item	Specifications				
Speed Setting Methods	Digital setting using the dial 4 speed settings possible				
Acceleration/Deceleration Time	Analog setting: 0.1~15.0 s (Time setting from stopped state until reaching the rated speed) Common settings for acceleration/deceleration time with the use of acceleration/deceleration time potentiometer* Digital setting: 0.0~15.0 s (Time setting from current speed to the setting speed) Individual settings for acceleration time/deceleration time for each operating data* *Acceleration time/deceleration time varies with the load condition of the motor.				
Input Signals	Photocoupler Input Input Resistance: 5.7 k $\Omega$ Operation due to internal power supply: 5 VDC Connectable External DC Power Supply: 24 VDC $-15 \sim +20\%$ Current 100 mA or more Sink input/Source input Supplied through external wiring				
	Arbitrary signal assignment to X0~X2 input (3 points) is possible []: Initial Setting [FWD], [REV], [M0], ALARM-RESET, EXT-ERROR, H-FREE				
Output Signals	Photocoupler and Open-Collector Output External Power Supply: 4.5~30 VDC Current 100 mA or less Sink output/Source output Supplied through external wiring				
	Arbitrary signal assignment to Y0, Y1 (2 points) is possible [ ]: Initial Setting [ALARM-OUT1], [SPEED-OUT], ALARM-OUT2, MOVE, VA, WNG				
Protective Function	When the following protective functions are activated, ALARM-OUT1 output turns OFF and the motor will undergo a coasting stop. At the same time, the alarm code will be displayed. (Instantaneous stop for external stop only) Overcurrent, Main circuit overheating, Overvoltage, Undervoltage, Sensor error, Overload, Overspeed, EEPROM error, Initial sensor error, Initial operation inhibition, External stop				
Maximum Extension Distance	Motor and Driver Distance: 10.5 m (Accessory connection cable used)				
Time Rating	Continuous				
— Overload Alarm Detection Tim	le				
The overload alarm is generated	if the operation goes beyond the continuous duty region.				
0	bad alarm can be set from 0.1~60.0 seconds. (Initial setting: 30.0 seconds)				
, 0	d within 5 seconds in the following cases:				
<ul> <li>If an applied load goes beyond</li> </ul>	the limited duty region				
<ul> <li>If the output shaft is locked</li> </ul>					

 $\cdot\,$  If the output shaft is locked

#### General Specifications

	Item	Motor	Driver			
Insulation Resistance		100 $M\Omega$ or more when 500 VDC megger is applied between the windings and the case after continuous operation under normal ambient temperature and humidity.	100 M $\Omega$ or more when 500 VDC megger is applied between the power supply terminal and the protective earth terminal, and between the power supply terminal and the I/O signal terminal after continuous operation under normal ambient temperature and humidity.			
Dielectric Strength		Sufficient to withstand 1.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.	No abnormality is judged even with application of 1.5 kVAC at 50 Hz between the power supply terminal and the protective earth terminal, and with application of 1.5 kVAC at 50 Hz between the power supply terminal and the I/O signal terminal, for 1 minute after continuous operation under normal ambient temperature and humidity.			
Temperature Rise		The maximum temperature rise of the windings is $50^{\circ}$ C and that of the case is $40^{\circ}$ C* <sup>1</sup> when measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity. Temperature rise of the heat sink is $50^{\circ}$ C or less measured thermocouple method after rated continuous operation under normal ambient temperature and humidity.				
	Ambient Temperature	$0 \sim +40^{\circ}$ C (Non-freezing)				
	Ambient Humidity	85% or less (non-condensing)				
Operating	Altitude	Up to 1000 m above sea level				
Environment	Atmosphere	No corrosive gases or dust. Cannot be used in a radioactive area, magnetic field, vacuum, or other special environments.				
Vibration		Not subject to continuous vibration or excessive shock Conforms to JIS C 60068-2-6 "Sine-wave vibration test method" Frequency range: 10~55 Hz Pulsating amplitude: 0.15 mm Sweep direction: 3 directions (X, Y, Z) Number of sweeps: 20 times				
Ctorogo	Ambient Temperature	$-20 \sim +70^{\circ}$ C (non-freezing)	-25~+70°C (non-freezing)			
Storage Conditions*2 Ambient Humidity Altitude		85% or less (no	on-condensing)			
		Up to 3000 m a	above sea level			
Insulation Class	S	EN standard: 120 (E)	_			
Degree of Protection		Standard type: IP40 IP65 Specification: IP65 (Excluding the mounting surface of the round shaft type and connectors)	IP20			

\*1 For round shaft types, attach to a heat sink (material: aluminum) of one of the following sizes to keep the motor case surface temperature from exceeding 90°C.

30 W Type: 115  $\times$ 115 mm Thickness 5 mm, 120 W Type: 165  $\times$ 165 mm Thickness: 5 mm

\*2 The storage condition applies to a short period such as a period during transportation.

Note

Do not measure insulation resistance or perform a dielectric strength test while the motor and driver are connected.

#### Permissible Torque of Combination Type

#### Combination Type – Parallel Shaft Gearhead

Combi	nation Typ	e – Parallel Shaft (	Gearhead							Unit: N•m
		Gear Ratio	5	10	15	20	30	50	100	200
Dueduet		80 r/min	16	8	5.3	4	2.7	1.6	0.8	0.4
Product Name	Motor Speed	2000 r/min	400	200	133	100	66.7	40	20	10
Name	[r/min]	3000 r/min	600	300	200	150	100	60	30	15
		4000 r/min	800	400	267	200	133	80	40	20
		At 80~2000 r/min	0.45	0.9	1.4	1.8	2.6	4.3	6	6
BMU230		At 3000 r/min	0.43	0.86	1.3	1.7	2.5	4.1	6	6
		At 4000 r/min	0.32	0.65	0.97	1.3	1.9	3.1	5.4	5.4
		At 80~2000 r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
BMU460		At 3000 r/min	0.86	1.7	2.6	3.4	4.9	8.2	16	16
		At 4000 r/min	0.65	1.3	1.9	2.6	3.7	6.2	12.4	14
		At 80~2000 r/min	2	4.1	6.1	8.1	11.6	19.4	30	30
BMU5120	)	At 3000 r/min	1.7	3.4	5.2	6.9	9.9	16.4	30	30
		At 4000 r/min	1.3	2.6	3.9	5.2	7.4	12.3	24.7	27

A colored background indicates gear shaft rotation in the same direction as the motor shaft. Others rotate in the opposite direction.

#### Permissible Radial Load/Permissible Axial Load

#### Combination Type – Parallel Shaft Gearhead

	Gear Ratio		Permissible	Radial Load	Permissible Axial Load
Product Name			10 mm from output shaft end N	20 mm from output shaft end N	N
		At 80~3000 r/min	100	150	
	5	At 4000 r/min	90	110	
BMU230	10, 15, 20	At 80~3000 r/min	150	200	40
BM0230	10, 15, 20	At 4000 r/min	130	170	40
	20 50 100 200	At 80~3000 r/min	200	300	
	30, 50, 100, 200	At 4000 r/min	180	230	
	5	At 80~3000 r/min	200	250	
		At 4000 r/min	180	220	
DALLA CO	10, 15, 20	At 80~3000 r/min	300	350	100
BMU460		At 4000 r/min	270	330	100
	30, 50, 100, 200	At 80~3000 r/min	450	550	
		At 4000 r/min	420	500	
	5	At 80~3000 r/min	300	400	
	5	At 4000 r/min	230	300	
BALLE100	10.15.00	At 80~3000 r/min	400	500	150
BMU5120	10, 15, 20	At 4000 r/min	370	430	150
	20 50 100 200	At 80~3000 r/min	500	650	7
	30, 50, 100, 200	At 4000 r/min	450	550	

#### Round Shaft Type

	Permissible		
Product Name	10 mm from output shaft end N	20 mm from output shaft end N	Permissible Axial Load
BMU230	80	100	
BMU260	80	100	Half of motor mass or less
BMU5120	150	170	

#### Permissible Load Inertia J of Combination Types

#### Combination Type – Parallel Shaft Gearhead

Unit: ×10<sup>-4</sup> kg·m<sup>2</sup> Gear Ratio Product Name **BMU230** When instantaneous stop or instantaneous bi-directional 1.55 6.2 24.8 55.8 operation is performed\* **BMU460** When instantaneous stop or instantaneous bi-directional 5.5 49.5 operation is performed\* BMU5120 When instantaneous stop or instantaneous bi-directional operation is performed\*

\*It is also applicable when digitally setting the deceleration time to below 0.1 second.

#### Dimensions (Unit mm)

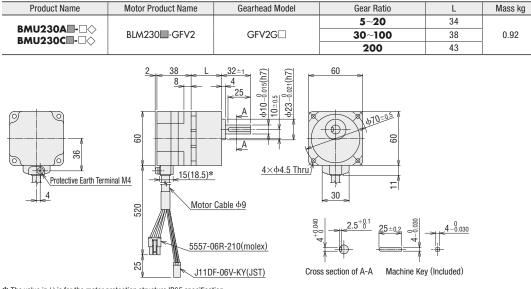
● "Mounting screws" are included with the combination type. Dimensions of installation screws → Page 24

 $\blacksquare$  A number indicating the gear ratio is specified in the box  $\square$  in the product name.

For motors with a degree of protection of IP65 specification, **P** is specified where the box **m** appears in the product name. When the accessory connection cable is supplied, a number indicating the length of the cable, **-1** (1 m), **-2** (2 m), or **-3** (3 m), is specified in the box  $\bigcirc$  in the product name.

#### **3**0 W

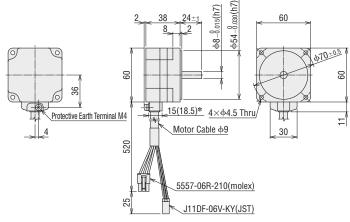
#### ♦ Motor/Parallel Shaft Gearhead



\* The value in ( ) is for the motor protection structure IP65 specification.

#### ◇Round Shaft Type BMU230AII-A◇, BMU230CII-A◇ Motor: BLM230I-A

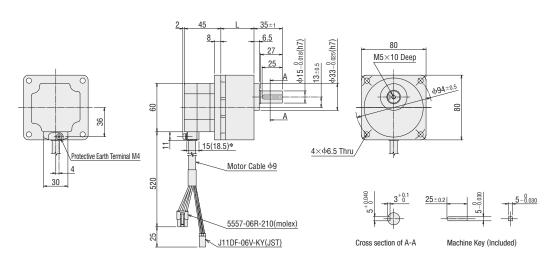
Mass: 0.42 kg



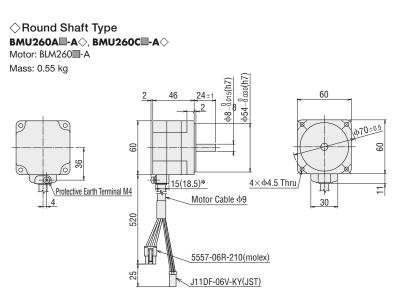
\* The value in ( ) is for the motor protection structure IP65 specification.

#### ●60 W ◇Motor/Parallel Shaft Gearhead

*					
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
			5~20	41	
BMU460SA <b>□-</b> □◇ BMU460SC <b>□-</b> □◇	BLM460S GFV2	GFV4G□	30~100	46	1.6
BM04003CB-LV			200	51	1

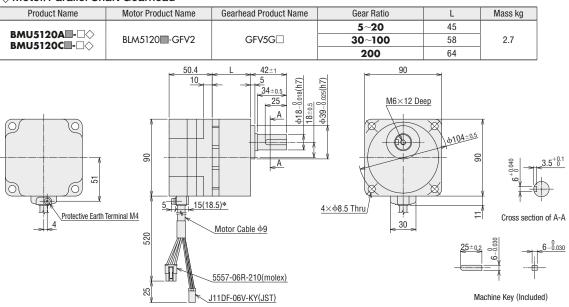


 $\ensuremath{\boldsymbol{\ast}}$  The value in ( ) is for the motor protection structure IP65 specification.

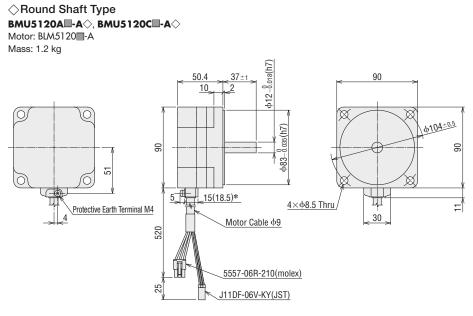


\* The value in ( ) is for the motor protection structure IP65 specification.

#### ●120 W ◇Motor/Parallel Shaft Gearhead



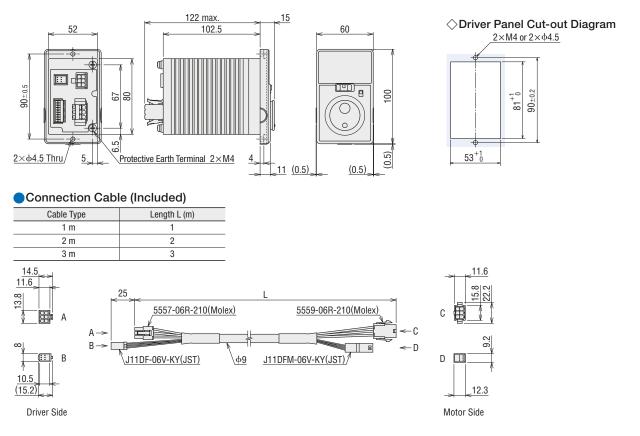
\* The value in ( ) is for the motor protection structure IP65 specification.



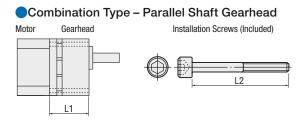
 $\boldsymbol{\ast}$  The value in ( ) is for the motor protection structure IP65 specification.

#### Driver

BMUD30-A2, BMUD30-C2, BMUD60-A2, BMUD60-C2, BMUD120-A2, BMUD120-C2 Mass: 0.4 kg



#### Dimensions of Installation Screw



L1		l	.2
Gearhead Product Name	Length (mm)	Length (mm)	Screw Size
GFV2G5~20	42	50	
GFV2G30~100	46	55	M4 P0.7
GFV2G200	51	60	
GFV4G5~20	49	60	
GFV4G30~100	54	65	M6 P1.0
GFV4G200	59	70	
GFV5G5~20	55	70	
GFV5G30~100	68	85	M8 P1.25
GFV5G200	74	90	

Installation screw: Includes 4 plain washers and 4 spring washers each
 The installation screw material is stainless steel.

#### Connection and Operation

#### Names and Functions of Driver Parts

MODE Key

mode.

Changes the operating

Indication	Orientalmotor
Displays the monitor	
contents, alarm, etc.	A.0.0.0
	THAD BY THE
	Y
Dial	PUSH-SET
Changes the speed and	
parameters.	
The value is set when the dial	
is pressed after changes are	
made.	
	MOREL BMUD30-A2

**Operating Switch** The motor is started by setting it to the "RUN" position. Setting it to the "STAND-BY" position stops the motor.

Rotation direction switch Changes the rotation direction of the motor.

Front Panel

Sensor Connector (CN3) Connects to the sensor connector (black) of the motor.

I/O Signal Connector (CN4) Connects with the I/O signals



Motor Connector (CN2) Connects to the motor connector (white) of the motor.

Main power connector

(CN1) Connects to the main power supply.

Protective Earth Terminals (2 locations)

Ground either one of the protective earth terminals.

<Back side of the driver>

#### Extended Functions

Remove the front panel to be able to perform various settings by operating the

	×0.0.0	
. 10		
		100
	$( \circ )$	MIS
0		

<Front side of the driver>

0.01.0

FUNCTION Key Changes the indication and functions for the operating mode.

Acceleration/deceleration time potentiometer Sets the acceleration time for starting the motor and deceleration time for motor standstill. Setting range: 0.1 s  $\sim$  15.0 s

Installation holes (2 places)

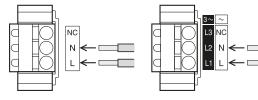
Operating mode	Details
Monitoring	Speed, load factor, operating data number, alarm, warning, I/O monitor
Data	Data No. 0, No. 1 (2 points) Operating speed, acceleration time, deceleration time, reset
Parameters	Gear ratio, speed increasing ratio, initial panel indication, initial operation inhibition alarm, analog acceleration/deceleration, external operating signal input, input function selection, output function selectior overload alarm detection time except during axial lock, overload warning level, speed attainment width, speed upper limit and lower limit function, slight position - keeping function, parameter mode reset

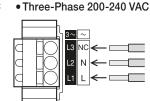
#### ◇Main power connector (CN1)

♦ When Front Panel is Removed

Connects to the main power supply. Connect a power supply that matches with the power supply voltage to be used.

#### • Single-Phase 100-120 VAC • Single-Phase 200-240 VAC





Applicable Lead Wire Size

AWG18~14 (0.75~2.0 mm<sup>2</sup>)

#### • Applicable Crimp Terminals

Use the following terminals for connection using crimp terminals. Please note that the applicable crimp terminal varies depending on the size of the lead wire

Manufacturer	PHOENIX CONTACT	
Product No.	AI 0.75-10 AI 1-10 AI 1.5-10 AI 2.5-10	[AWG18 (0.75 mm <sup>2</sup> )] [AWG18 (0.75 mm <sup>2</sup> )] [AWG16 (1.25 mm <sup>2</sup> )] [AWG14 (2.0 mm <sup>2</sup> )]

#### Operation with the driver only

◇Run/Stop

When the operating switch is set to the "RUN" position, the motor will start. When it is returned to the "STAND-BY" position, the motor decelerates to a stop.

#### 

Set the motor speed by using the dial. Setting range: 80~4000 r/min

Turning the dial slowly to the right increases the speed by 1 r/min increments, while turning it to the left reduces the speed by 1 r/min increments. Turning the dial fast produces a great variation in speed. Pressing the dial sets the speed.



Operation with the operating switch

Setting the speed with the dial

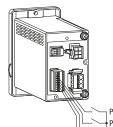
#### Operating Switch

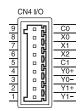


#### Operation by external signals

#### Operating Method ■

- Using the built-in power supply in the driver, the motor is operated through signals from external sources (switches, relays, etc.).
   Connect Pins No. 5~8 of the I/O signal connector (CN4) as in the figure to the right.
- For operation using external signals, change the parameter setting in the "External Operating Signal Input". For details, see the user's guide.
- Multiple speed operation is available in up to 4 levels.





Pin No.8 (X0): FWD Pin No.7 (X1): REV Pin No.6 (X2): M0 Pin No.5 (C1): IN-COM1 (0 V)

Applicable Lead Wire Size

AWG26~20 (0.14~0.5 mm<sup>2</sup>)

#### Applicable Crimp Terminals

Use the following terminals for connection using crimp terminals. Please note that the applicable crimp terminal varies depending on the size of the lead wire.

Manufacturer	PHOENIX CONTACT		
Product No.	A 0.25-7 A 0.34-7 A 0.5-8	[AWG24 (0.2 mm <sup>2</sup> )] [AWG22 (0.3 mm <sup>2</sup> )] [AWG20 (0.5 mm <sup>2</sup> )]	

#### •I/O Signals Connector (CN4)

Pin No.	Terminal Name	Signal Name*	Description
9	CO	IN-COM0	Input signal common (for external power supply)
8	XO	[FWD]	During "ON", the motor rotates in the FWD direction.
7	X1	[REV]	During "ON", the motor rotates in the REV direction.
6	X2	[M0]	Select the operating data.
5	C1	IN-COM1	Input signal common (for internal power supply: 0 V)
4	Y0+		For every rotation of the motor output shaft, 30
3	Y0-	[SPEED-OUT]	pulses are output.
2	Y1+	[ALARM-OUT1]	It turns OFF when an alarm is generated.
1	Y1-		(Normally closed)

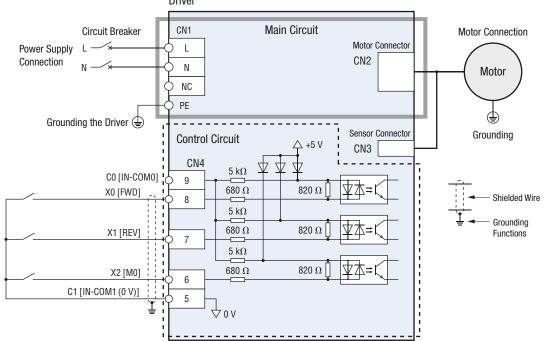
\*The [] indicates the functions assigned in the factory.

Among the following signals, the signals required for the three input signal terminals (X0 - X2) and the two output signal terminals (Y0 - Y1) can be assigned.

Three points for the seven input signal points (FWD, REV, MO, M1, ALARM - RESET, EXT - ERROR, H - FREE) Two points for the six output signal points (ALARM - OUT1, SPEED - OUT, ALARM - OUT2, MOVE, VA, WNG)

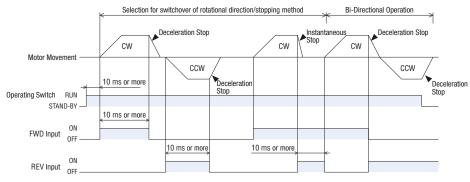
#### $\bigcirc$ Example for connection using switches, relays, etc.

The figure shows a connection example for the operation of the motor using switches having contacts, such as switches or relays. (Single-Phase 100 -120 VAC) Driver



#### 

This is a timing chart when the "External operating signal input" parameter is set to "ON" and the rotation direction switch is set to "FWD".



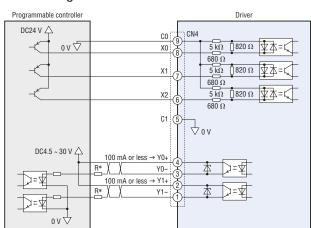
- Switching the FWD input to ON will cause the motor to turn clockwise as viewed from the motor shaft side, while switching the REV input to ON will cause the motor to turn counterclockwise. Turning it OFF decelerates the motor to stop.
- If both the FWD input and REV input are turned ON simultaneously, the motor will stop instantaneously.

With the combination type, the rotation direction varies according to the gear ratio of the gearhead.

#### $\Diamond$ Example of connection of I/O signals with the host controller

This is a connection example for the operation of the motor using the host controller of the transistor output type. •Sink Logic •Source Logic

#### Programmable controller Driver DC24 V 🛆 CN4 C0 5 kΩ 1820 Ω 1 = ζ X0 680 Ω 5 kΩ [820 Ω X1 680 Ω $5 k\Omega$ [ 820 Ω Χ2 680 Ω C1 ψov Υov DC4.5 ~ 30 V 🛆 >=⊈ A or less→ Y0+ 00 r $\mathbf{T}$ Y0-X $R^*$ 100 mA or less $\rightarrow$ Y1+ Y1-0 V



Recommended resistance value

For 24 VDC: 690  $\Omega$  to 27 k $\Omega$  (2 W)

For 5 VDC: 150 Ω to 560 Ω (0.5 W)

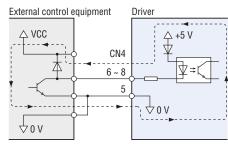
#### Note

The current applied to Y0 and Y1 must be 100 mA or less. If this value is exceeded, connect the limiting resistance R.

#### ♦ When using external control equipment with built-in clamping diodes

With external control equipment with built-in clamping diodes connected, if the power of the external control equipment is turned off with the driver turned on, the motor may rotate due to current flowing around. The motor may also rotate even if the driver and the external control equipment are simultaneously turned off because these two devices have different current capacities.

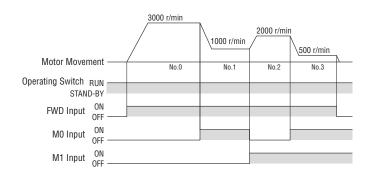
To turn off the power, first turn off the driver and then the external control equipment. To turn on the power, first turn on the external control equipment and then the driver.



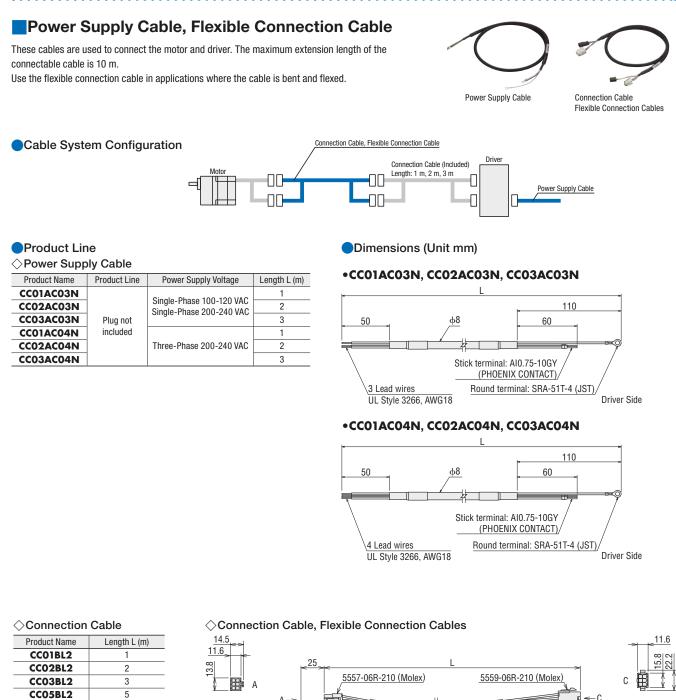
**When using external control equipment with built-in clamping diodes** By switching the ON/OFF of the M0 or M1 input, the multiple speed operation becomes available.

#### •Example of operating conditions

Operating Data No.	MO	M1	Rotation Speed [r/min]
0	0FF	0FF	3000
1	ON	0FF	1000
2	0FF	ON	2000
3	ON	ON	500



### Accessories (Sold separately) RoHS





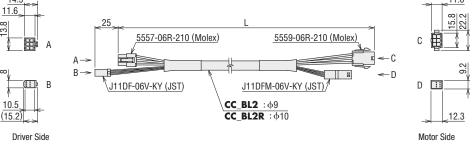
7

10

CC07BL2

CC10BL2

Length L (m)
1
2
3
5
7
10



Note

When extending the connecting cable, make sure that the total length (up to two cables) is 10.5 m or less.

#### Motor and Gearhead Mounting Bracket

These dedicated mounting brackets are for mounting motors and gearheads.

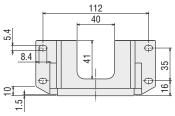


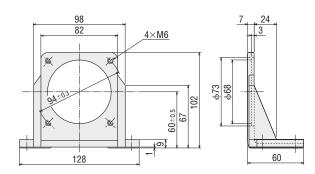
#### Product Line

Product Name	Applicable Product	
SOL2M4F	BMU230, BMU260	
SOL4M6F	BMU460	
SOL5M8F	BMU5120	

#### SOL4M6F

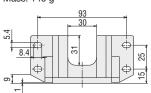


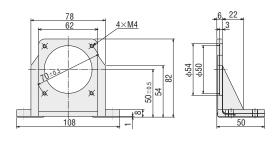




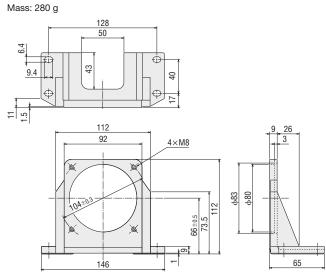
#### Dimensions (Unit mm) SOL2M4F

Mass: 140 g





#### SOL5M8F



#### Circuit products mounting brackets

Mounting brackets for installing the driver are available.

Mounting brackets have product lines for different applications such as for DIN rail installation, installation on the wall surface, and for conveyor guide installation.

#### Product Line

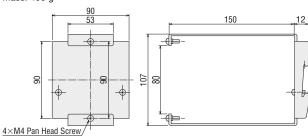
Material: SPCC Surface treatment: Trivalent chromate

Product Name	Application
MADP05-15	For DIN Rail Installation
MAFP04-15	For Wall Surface Installation
MAFP05V	For Convoyor Cuido Installation
MAFP05H	For Conveyor Guide Installation

#### Dimensions (Unit mm)

#### MADP05-15

Mass: 450 g









MAFP05V <Application example>

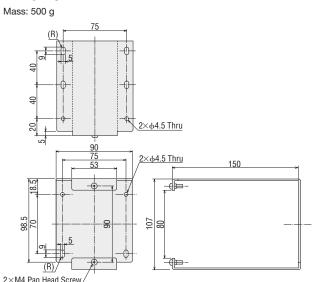
MAFP04-15



MAFP04-15 <Application example>

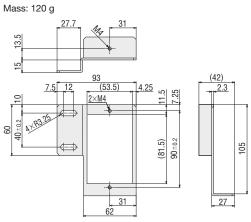


MAFP05H <Application example>

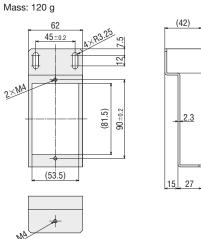


2×M4 Pan Head Screw





#### MAFP05V



# (27.7) 137

#### Flexible Couplings

These are clamp type couplings for connecting the motor/ gearhead shaft with the driven shaft. Couplings usable for the combination type and the round shaft type are available.



#### Product Line

I roudot Ento		
Product Name	Applicable Product	
MCL30 Type	BMU230 Combination Type	
MCL40 Type	BMU460 Combination Type	
MCL55 Type	BMU5120 Combination Type	

### 200W Output Type

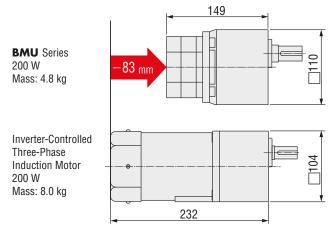
A high power 200 W model of the well known **BMU** Series of "dial and press" brushless motor and driver packages. Thanks to the compact, high power, high efficiency brushless motor, the speed control range has expanded.

#### Features

#### Designed to be Compact, High Power and High Efficiency

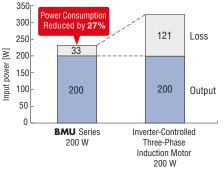
#### Contributes to Downsizing of Equipment.

When compared to a 200 W three-phase induction motor, the overall length is 83 mm (approximately 36%) shorter, and the motor mass is 3.2 kg (40%) lighter. The slimmer, reduced-weight high power motor contributes to the downsizing of the equipment.



#### Contributes to Equipment Energy Savings

When compared to a 200 W three-phase induction motor, the power consumption is reduced by approximately 27%. These motors are effective in equipment energy savings.

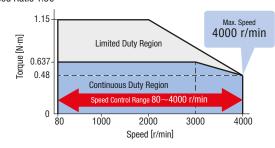


Rated output power at 50 Hz (Representative value)



#### Wide Speed Control Range (Speed ratio 1:50)

Max. Speed 4000 r/min Speed Ratio 1:50



#### **Additional Functions**

Front Panel Operation Can Be Disabled

When being operated by external signal, the front panel operation switches can be disabled.

The Number of I/O Input Signals Increased From 3 to 5.

In response to our customers' requests, it is now possible to change rotation direction when operating at speed 4 and clear alarms without turning the main power supply off.



**Oriental motor** 

#### ORIENTAL MOTOR (EUROPA) GmbH

www.orientalmotor.de European Headquarters Schiessstraße 74 40549 Düsseldorf, Germany Tel: 0211-5206700 Fax: 0211-52067099

Tel: 0211-5206700 Fax: 0211-

Other countries:

www.orientalmotor.eu

#### ORIENTAL MOTOR (UK) LTD.

www.oriental-motor.co.uk

UK Headquarters Unit 5, Faraday Office Park, Rankine Road, Basingstoke, Hampshire RG24 8AH, U.K. Tel: 01256-347099 Fax: 01256-347099

ORIENTAL MOTOR (FRANCE) SARL www.orientalmotor.fr

France Headquarters 56, Rue des Hautes Pâtures

92000 Nanterre Cedex, France Tel: 01 47 86 97 50 Fax: 01 47 82 45 16

#### ORIENTAL MOTOR ITALIA s.r.l.

These products are manufactured at plants certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** (for systems of environmental management).



Specifications are subject to change without notice. Published in April 2015.

ORIENTAL MOTOR CO., LTD.

www.orientalmotor.co.jp

Headquarters 4-8-1 Higashiueno Taito-ku, Tokyo 110-8536, Japan Tel: (03)6744 -0361 Fax: (03)5826-2576

#### **Customer Center (Support in German & English)**

00800-22 55 66 22\* CA LL OM CC

Mon-Thu: 08:00 - 17:30 CET Friday: 08:00 - 16:00 CET

\* Free Call Europe

#### info@orientalmotor.de

For more information please contact: