Oriental motor



Easy speed control, easier to use.

New connector type with smart wiring.



The new connector type in the compact, high-efficiency **BMU** series, directly connects the motor and driver together.

Smart wiring and watertight and dust-resistant performance (degree of protection IP66) have been achieved.



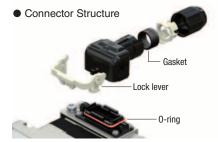
Connector Type Features

A connector has been newly developed for small motors. Direct connection between the motor and driver is now possible.

Together with the improved motor structure, watertight and dust-resistant performance has also been increased, achieving a IP66 level of protection*. *Motor only

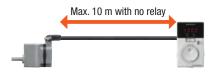
New Connector

The gasket and O-ring are built-in, improving water ingress protection. A lock lever system which does not require screw fitting is employed, making connection easy.



Directly Connect the Motor and Driver

Can be connected up to 10 m max. with no relay. Cable relay processing is unnecessary. The power line, signal line, and ground wire are all contained in one cable, reducing wiring work.



Installation Method







Pull the lock lever down



Connection complete

Select the Cable Pull-out Direction

Two cable pull-out direction options are available to suit the equipment. (The only cable pull-out direction of the round shaft type is the rear of the motor.)



Pull-out on output shaft side Pull-out on rear of the motor

Stainless Steel Shaft Comes Standard

EURONORM X 10 CrNiS 18 9, which has excellent anti-rust and anti-corrosion properties, is used for the shaft. Stainless steel is also used for the parallel key and installation screws.





Brushless Motor Features

Brushless motors don't have brushes, which are the weak point of DC motors, so they create little noise and are maintenance-free.

Since they use a permanent magnet, they are compact, high-power, and high-efficiency.

Broad Speed Control Range

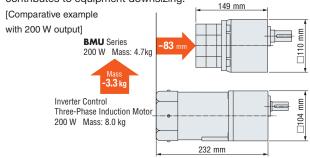
Brushless motors have a broader range of speed control than AC speed control motors and inverters. They are suitable for applications that require constant torque from low speed to high speed.

Product Group	Speed Control Range*	Speed Ratio
BMU Series Brushless Motors	80~4000 r/min	1:50
Inverter-Controlled Three-Phase Induction Motor	200~2400 r/min	1:12
AC Speed Control Motors	50 Hz : 90 ~1400 r/min 60 Hz : 90 ~1600 r/min	1:15 1:17

*The speed control range differs depending on the model.

Slim, Lightweight, High-Power

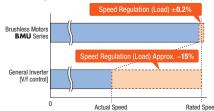
Brushless motors contain a permanent magnet in the rotor, so they are slim, lightweight, and provide high-power. This contributes to equipment downsizing.



Stable Speed Control is Possible

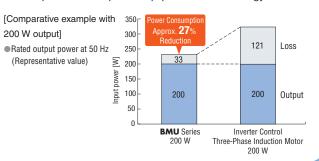
Brushless motors constantly monitor feedback signals from the motor, compared with the setting speed, and adjust the applied voltage. This means that the motor rotates at a stable speed from low speed to high speed, even if the load changes.

●Comparison of Speed Variation at 80% Load Factor (Reference value)



Contributes to Equipment Energy Savings

Brushless motors contain a permanent magnet in the rotor, inhibiting secondary rotor loss and greatly reducing power consumption. This helps the equipment to save energy.



Many convenient functions that a speed control motor requires.

Here are the main points

Speed Indicator

Displays the motor speed in 1 r/min units. By calculating the conveyor gear ratio and setting gear ratio parameters, the conveyor transportation speed can be displayed in m/s. The conveyor transportation speed can be confirmed directly.



Load Factor Indicator

With the rated torque of the motor at 100%, the load factor can be expressed as a percentage (40~200%). The load condition during start-up, as well as the load condition due to the age deterioration of the equipment, can be confirmed.



Indication at a load factor of 50%

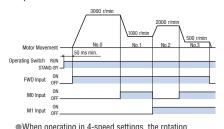
Protective Functions

Contains various protective functions, such as an overload protection function and overvoltage protection function. When a protective function activates, the alarm code is displayed on the indicator and an alarm signal is displayed.



4-Speed Operation

4-speed operation is possible by setting the data to operating data slots No.0, No.1, No.2 or No.3, and switching the input of the M0 and M1 terminals.



direction of the motor cannot be changed by external input signals.

Set the Acceleration/ Deceleration Time

Acceleration time and deceleration time settings can be adjusted with the acceleration/deceleration time potentiometer, as well as digitally set.

Setting Range:

0.0~15.0 sec (initial value: 0.5 sec)

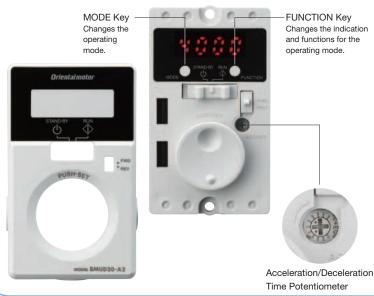
In the case for digital setting, acceleration and deceleration time can be independently set, so times can be freely set by fine-tuning shock alleviation when the load has started and stopped, together with cycle time.

Other Functions

- Lock Dial Operations
 Unintended speed changes and data editing/deletion through dial operations can be prevented.
- Front Panel Operation Can Be
 Disabled
 When the motor is operated in external signal mode, the front panel operation switches can be disabled.
- Output Shaft Holding when Stopped
 The load can be electrically held when
 the motor is at standstill. (Holding
 force up to 50% of rated torque)

If the power supply to the driver is turned OFF, the holding force dissipates. This cannot be used to prevent a fall during a power outage.

Various functions can be set by opening the front panel of the driver.



<Typical Functions that can be Set while the Front Panel is Opened>

- •Motor start/stop*
- •Adjusting the operating speed*
- Setting the operating speed*
- Switching the rotation direction*
- Changing the indication
- •Indicating the operating speed when the speed reduction/speed increasing ratio is set
- Setting the acceleration/deceleration time
- ●Dial operation lock
- Speed setting for the 4-speed operation
- Speed limits setting
- Validating the external operating signals
- ●External input/output signal allocation
- Setting the overload alarm detection time
 Except when shaft is locked
- •Load holding function for output shaft *Setting is possible even if the front panel is attached.

Easy Operation

Turn & Press

Turn the dial and set to the desired speed. The speed can be set just by pressing the dial.



Start/Stop

Can be easily driven and stopped with the operating switch on the front. There is no need to provide a switch externally.



Switching the Rotation Direction

The motor's rotation direction can be switched with the rotation direction switch. It can even be changed during operation.



Easy Wiring

Direct Connection to the Motor

Easy connection between the motor and connection cable by inserting the connector and lowering the lock lever. Newly designed for small motors.



Easy Connection on the Driver Side too

The driver connector is a small format connector that easily passes through flexible conduits and cable glands.



The Power and I/O Connectors Feature a Screwless Connector

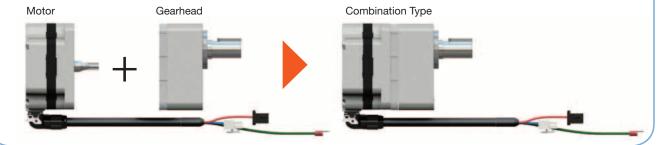
Connection to the power connector and I/O connector do not require any special crimp tools or soldering. Just insert the lead wire.



Easy Assembly

The Combination Type has a New Gearhead

The gearhead has improved gearmotor coupling accuracy due to the use of boss and installation surface cutting. It also produces less noise than conventional products. The combination type comes with the motor and gearhead already assembled, making assembly in the equipment easy.

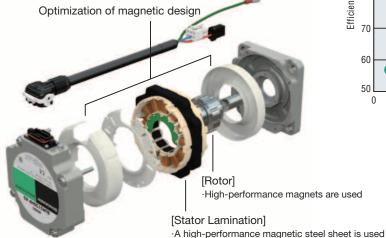


An IP66-Compatible High-Efficiency Brushless Motor.

The New Brushless Motor NexBL

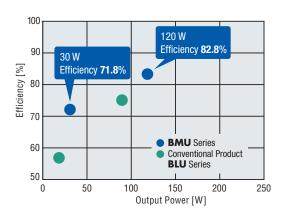
Designed to be Compact, High Power and High Efficiency

Optimal magnetic design and high-performance materials allow for a stator lamination thickness of only 11.2mm in the NexBL. This thinness achieves a highly efficient power unit that can output 120 W. Compared with a conventional brushless motor of the same output power, the stator plate thickness is reduced by half (for motors with a frame size of 90 mm). Moreover, by using high-performance materials while reducing the amount of material used, costs have been reduced significantly.



Greatly Increased Efficiency

The **BMU** series has up to 15% points better efficiency in motor/driver units compared to conventional products*. *Comparison between the BMU series 30 W and the BLU series 20 W.



·11.2 mm thick (50% thinner than conventional products)

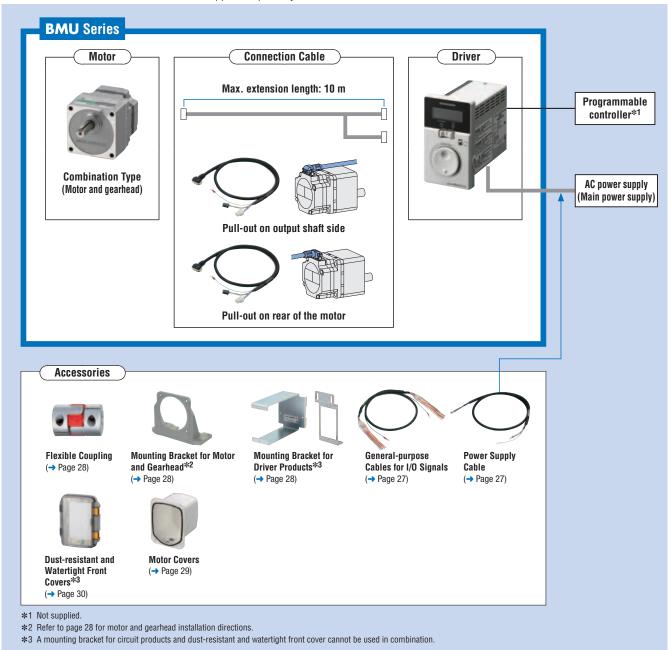
Product Lineup

Motor	Output	Frame Size	Gearhead Gear Ratio (Combination type)	Driver	Power Supply Voltage	Connection Cable
	Power 30 W	Combination Type Round Shaft Type	5, 10, 15, 20, 30, 50, 100, 200			
	60 W	Combination Type 80 mm Round Shaft Type 60 mm	5, 10, 15, 20, 30, 50, 100, 200	0	Single-phase 100-120 VAC Single-phase	Pull-out on output shaft side
Combination Type	120 W	Combination Type 90 mm Round Shaft Type	5, 10, 15, 20, 30, 50, 100, 200		200-240 VAC Three-phase 200-240 VAC	0.5, 1, 1.5, 2, 2.5, 3, 4, 5, 7, 10 m
Round Shaft Type*	200 W	Combination Type 110 mm Round Shaft Type 90 mm	5, 10, 15, 20, 30, 50, 100, 200			0.5, 1, 1.5, 2, 2.5, 3, 4, 5, 7, 10 m
	300 W	Combination Type 110 mm Round Shaft Type 90 mm	5, 10, 15, 20, 30, 50, 100	2	Single-phase 200-240 VAC Three-phase 200-240 VAC	

*Only the rear side pull-out connection cable can be combined with the round shaft type. The round shaft type also includes a shaft flat type.

System Configuration

Motors, drivers, and connection cables are supplied separately.



●Example of System Configuration

BMU Series			Accessories			
Combination Type – Parallel Shaft	Driver	Connection Cable (3m)	+	Mounting Bracket for Motor and Gearhead	Flexible Coupling	Mounting Bracket for Circuit Products
BLM230HP-10S	BMUD30-A2	CC030HBLF		SOL2M4F	MCL301010	MAFP05V

[■]The system configuration shown above is an example. Other combinations are also available.

Product Number

Motor (Parallel shaft combination type/round shaft type)

BLM 4 60 S H P - 50

(1)

Driver

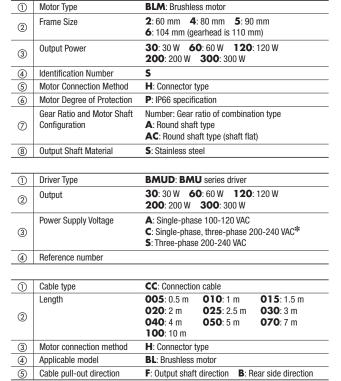
BMUD 60 - C

Connection Cable

CC 010 H BL F







*WARNING: Connecting the BLE2 to three-phase 400 VAC will damage the product.

Product Line

Please purchase a motor, driver, and connection cable.

Combination Type with a Parallel Shaft Gearhead

Combination Type

Motor and gearhead are delivered pre-assembled.

The combination of motors and gearheads can be changed, and they are also available separately. In addition, the gearhead can be removed and the assembly position can be changed in 90° increments.



Output Power	Product Name	Gear Ratio	
		5, 10, 15, 20	
30 W	BLM230HP-□S	30, 50, 100	
		200	
		5, 10, 15, 20	
60 W	BLM460SHP-□S	30, 50, 100	
		200	
		5, 10, 15, 20	
120 W	BLM5120HP-□S	30, 50, 100	
		200	
		5, 10, 15, 20	
200 W	BLM6200SHP- S	30, 50	
		100, 200	
200 W	DI MA 200CLID TO	5, 10, 15, 20	
300 W	300 W BLM6300SHP- □ S	30, 50, 100	

The following items are included in each product.

Motor, Gearhead, Installation Screws, Parallel Key, Operating Manual

ullet A number indicating the gear ratio is specified where the box \Box is located in the product name.



Length	Product Name
0.5 m	CC005HBL
1 m	CC010HBL
1.5 m	CC015HBL
2 m	CC020HBL
2.5 m	CC025HBL

Length	Product Name
3 m	CC030HBL
4 m	CC040HBL
5 m	CC050HBL
7 m	CC070HBL
10 m	CC100HBL

◇Drivers

V DITVCI3		
Output Power	Power Supply Voltage	Product Name
	Single-phase 100-120 VAC	BMUD30-A2
30 W	Single-phase, three-phase 200-240 VAC	BMUD30-C2
	Single-phase 100-120 VAC	BMUD60-A2
60 W	Single-phase, three-phase 200-240 VAC	BMUD60-C2
	Single-phase 100-120 VAC	BMUD120-A2
120 W	Single-phase, three-phase 200-240 VAC	BMUD120-C2
	Single-phase 100-120 VAC	BMUD200-A
200 W	Single-phase, three-phase 200-240 VAC	BMUD200-C
300 W	Single-phase, three-phase	BMUD300-C

The following items are included in each product.

Driver, CN1 Connector, CN4 Connector, Operating Manual, Startup Guide

There are two types of connection cables with different pull-out directions.

F: Pull-out on output shaft side

B: Pull-out on rear of the motor





Round Shaft Type



\Diamond Motors

Output Power	Product Name
30 W	BLM230HP-AS
60 W	BLM260HP-AS
120 W	BLM5120HP-AS
200 W	BLM5200HP-AS
300 W	BLM5300HP-AS

 The following items are included in each product. -Motor, Operating Manual



♦ Connection Cables

V 0000	
Length	Product Name
0.5 m	CC005HBLB
1 m	CC010HBLB
1.5 m	CC015HBLB
2 m	CC020HBLB
2.5 m	CC025HBLB
3 m	CC030HBLB
4 m	CC040HBLB
5 m	CC050HBLB
7 m	CC070HBLB
10 m	CC100HBLB

Note

Other Product Lineup

Round Shaft Type Shaft Flat on Output Shaft

•For details, contact the customer support center.

\Diamond Drivers

V =		
Output Power	Power Supply Voltage	Product Name
	Single-phase 100-120 VAC	BMUD30-A2
30 W	Single-phase, three-phase 200-240 VAC	BMUD30-C2
	Single-phase 100-120 VAC	BMUD60-A2
60 W	Single-phase, three-phase 200-240 VAC	BMUD60-C2
	Single-phase 100-120 VAC	BMUD120-A2
120 W	Single-phase, three-phase 200-240 VAC	BMUD120-C2
	Single-phase 100-120 VAC	BMUD200-A
200 W	Single-phase, three-phase 200-240 VAC	BMUD200-C
300 W	Single-phase, three-phase 200-240 VAC	BMUD300-C

- The following items are included in each product.

Driver, CN1 Connector, CN4 Connector, Operating Manual, Startup Guide

B: Pull-out on rear of the motor



The only cable pull-out direction of the round shaft type is the rear of the

Specifications

30 W



Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM230HP-□S		
		Round Shaft Type	BLM230		
	Driver		BMUD30-A2	BMUD30-C2	
Rated Output Pov	ver (Continuous)	W	30		
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240 / Three-Phase 200-240	
	Permissible Volta	ge Range	-15~-	+10%	
Power Supply	Frequency	Hz	50/6	60	
Input	Permissible Frequency Range		±5	%	
	Rated Input Curre	ent A	1.2	Single-Phase: 0.7 / Three-Phase: 0.38	
	Maximum Input (Current A	2	Single-Phase: 1.2 / Three-Phase: 0.75	
Rated Speed	ated Speed r/min		3000		
Rated Torque		N-m	0.09	96	
Max. Instantaneo	us Torque	N·m	0.14	14	
Rotor Inertia		J: ×10 ⁻⁴ kg.m ²	0.04	12	
Round Shaft Type Inertia	Permissible	J: ×10 ⁻⁴ kg⋅m ²	1.8		
Speed Control Ra	nge		80~4000 r/min (speed ratio 1:50)		
		Load	$\pm 0.2\%$ or less: Conditions 0 \sim rated torque, rated speed, r	ated voltage, normal ambient temperature	
Speed Regulation		Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15 \sim +10\%$, ra	ted speed, no load, normal ambient temperature	
		Temperature	$\pm 0.2\%$ or less: Conditions Operating ambient temperature $0\sim +40^{\circ}$ C, rated speed, no load, rated voltage		

●60 W



Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM460	SHP-□S	
		Round Shaft Type	BLM260	OHP-AS	
	Driver		BMUD60-A2	BMUD60-C2	
Rated Output Pov	ver (Continuous)	W	60	0	
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240 / Three-Phase 200-240	
	Permissible Vol	tage Range	-15~	+10%	
Power Supply	Frequency	Hz	50/60		
Input Permissible Frequ		quency Range	±5%		
Rated Input C	Rated Input Cur	rent A	1.7	Single-Phase: 1.0 / Three-Phase: 0.52	
	Max. Input Curr	ent A	3.3	Single-Phase: 1.9 / Three-Phase: 1.1	
Rated Speed		r/min	300	00	
Rated Torque		N∙m	0.1	91	
Max. Instantaneo	us Torque	N∙m	0.2	87	
Rotor Inertia		J: ×10 ⁻⁴ kg⋅m ²	0.0	82	
Round Shaft Type nertia	Permissible	J: ×10 ⁻⁴ kg·m ²	3.75		
Speed Control Ra	nge		80~4000 r/min (speed ratio 1:50)		
		Load	$\pm 0.2\%$ or less: Conditions $$ 0 \sim rated torque, rated speed,	rated voltage, normal ambient temperature	
Speed Regulation		Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15 \sim +10\%$, ra	ated speed, no load, normal ambient temperature	
Temper		Temperature	$\pm 0.2\%$ or less: Conditions Operating ambient temperature $0\sim +40^{\circ}\text{C}$, rated speed, no load, rated voltage		

●120 W



Product Name	Motor	Combination Type with a Parallel Shaft Gearhead Round Shaft Type	BLM5120			
	Driver	nound Shart Type	BMUD120-A2	BMUD120-C2		
Rated Output Pov	ver (Continuous)	W	12	0		
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240 / Three-Phase 200-240		
	Permissible Volta	age Range	-15~-	+10%		
Power Supply	Frequency	Hz	50/6	60		
Input	Permissible Frequency Range		±5%			
	Rated Input Current		3.3	Single-Phase: 2.0 / Three-Phase: 1.1		
	Max. Input Curre	ent A	6.8	Single-Phase: 4.1 / Three-Phase: 2.0		
Rated Speed		r/min	300	00		
Rated Torque		N·m	0.38	32		
Max. Instantaneo	us Torque	N∙m	0.57	73		
Rotor Inertia		J: ×10 ⁻⁴ kg⋅m ²	0.2	3		
Round Shaft Type Inertia	e Permissible	$J: \times 10^{-4} \text{ kg} \cdot \text{m}^2$	5.0	3		
Speed Control Ra	ınge		80~4000 r/min (s	speed ratio 1:50)		
		Load	$\pm 0.2\%$ or less: Conditions $0\sim$ rated torque, rated speed, r	rated voltage, normal ambient temperature		
Speed Regulation	1	Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15 \sim +10\%$, ra	ited speed, no load, normal ambient temperature		
		Temperature	$\pm 0.2\%$ or less: Conditions Operating ambient temperature	e 0 \sim +40 $^{\circ}$ C, rated speed, no load, rated voltage		

[•] For detailed information about standards, please see the Oriental Motor website.

[■] The values correspond to each specification and characteristics of a stand-alone motor. The speed – torque characteristics show the values when rated voltage is applied.
■ A number indicating the gear ratio is specified where the box □ is located in the product name.



Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM6200	SHP-□S			
		Round Shaft Type	BLM520	OHP-AS			
	Driver		BMUD200-A	BMUD200-C			
Rated Output Pov	ver (Continuous)	W	20	0			
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240 / Three-Phase 200-240			
	Permissible Volta	ge Range	-15~-	+10%			
Power Supply	Frequency	Hz	50/6	60			
Input	Permissible Freq	uency Range	±5%				
-	Rated Input Current		4.6	Single-Phase: 2.7 / Three-Phase: 1.5			
	Max. Input Curre	nt A	9.3	Single-Phase: 4.9 / Three-Phase: 3.4			
Rated Speed		r/min	300	00			
Rated Torque		N∙m	0.63	37			
Max. Instantaneo	us Torque	N·m	1.1	5			
Rotor Inertia		J: ×10 ⁻⁴ kg⋅m ²	0.49	54			
Round Shaft Type Inertia	Permissible	J: ×10 ⁻⁴ kg⋅m ²	8.7	5			
Speed Control Ra	nge		80~4000 r/min (s	speed ratio 1:50)			
		Load	$\pm 0.2\%$ or less: Conditions 0~rated torque, rated speed, r	rated voltage, normal ambient temperature			
Speed Regulation		Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15 \sim +10\%$, ra	ted speed, no load, normal ambient temperature			
		Temperature	$\pm 0.2\%$ or less: Conditions Operating ambient temperature	e $0\sim+40^{\circ}$ C, rated speed, no load, rated voltage			

300 W



			11_0 1			
Product Name Motor		Combination Type with a Parallel Shaft Gearhead	BLM6300SHP-□S			
		Round Shaft Type	BLM5300HP-AS			
	Driver		BMUD300-C			
Rated Output Pov	ver (Continuous)	W	300			
	Rated Voltage	VAC	Single-Phase 200-240 / Three-Phase 200-240			
	Permissible Volta	age Range	−15~+10%			
Power Supply	Frequency	Hz	50/60			
Input	Permissible Freq	uency Range	±5%			
	Rated Input Curr	ent A	Single-Phase: 3.4 / Three-Phase: 2.1			
	Max. Input Curre	nt A	Single-Phase: 7.8 / Three-Phase: 4.7			
Rated Speed		r/min	3000			
Rated Torque		N·m	0.955			
Max. Instantaneo	us Torque	N·m	1.43			
Rotor Inertia		J: ×10 ⁻⁴ kg⋅m ²	0.67			
Round Shaft Type Inertia	Permissible	J: ×10 ⁻⁴ kg⋅m ²	12			
Speed Control Ra	nge		80~4000 r/min (speed ratio 1:50)			
		Load	$\pm 0.2\%$ or less: Conditions $$ 0 \sim rated torque, rated speed, rated voltage, normal ambient temperature			
Speed Regulation	ı	Voltage	$\pm 0.2\%$ or less: Conditions Rated voltage $-15\sim +10\%$, rated speed, no load, normal ambient temperature			
		Temperature	$\pm 0.2\%$ or less: Conditions Operating ambient temperature $0\sim +40^{\circ}$ C, rated speed, no load, rated voltage			

[•]For detailed information about standards, please see the Oriental Motor website.

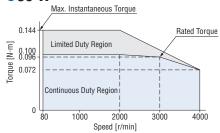
[■] The values correspond to each specification and characteristics of a stand-alone motor. The speed – torque characteristics show the values when rated voltage is applied.

■ A number indicating the gear ratio is specified where the box □ is located in the product name.

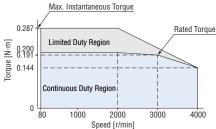
■ Speed – Torque Characteristics

Continuous Duty Region: Continuous operation is possible in this region. Limited Duty Region: This region is used primarily when accelerating.

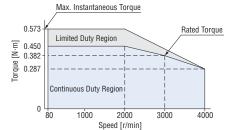
30 W



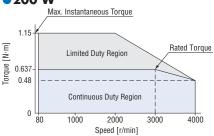
●60 W



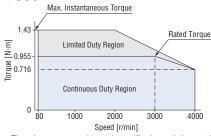
•120 W



200 W



300 W



• The values correspond to each specification and characteristics of a stand-alone motor. The speed – torque characteristics show the values when rated voltage is applied.

■Common Specifications

Item	Specifi	ications					
ILEIII	30 W, 60 W, 120 W	200 W, 300 W					
Speed Setting Methods	Digital setting by 4 speed settings						
Acceleration/Deceleration Time	Analog Setting: 0.1~15.0 s (set time from stopped state to rated speed) Common setting for acceleration/deceleration time with acceleration/deceleration time potentiometer* Digital Setting: 0.0~15.0 s (set time from current speed to setting speed) Individual acceleration times and deceleration times can be set for each operating data* *Acceleration time/deceleration time varies with the load condition of the motor.						
Input Signals	Photocoupler Input Input resistance: $5.7 \text{ k}\Omega$ Operated by Internal Power Supply: 5 VDC Connectable External DC Power Supply: $24 \text{ VDC} -15 \sim +20\%$ Current 100 mA or more Sink Input/Source Input Supported through external wiring	Photocoupler Input Input resistance: $6.6 \text{ k}\Omega$ Operated by Internal Power Supply: 5 VDC Connectable External DC Power Supply: $24 \text{ VDC} -15 \sim +20\%$ Current 100 mA or more Sink Input/Source Input Supported through external wiring					
	Arbitrary signal assignment to $X0{\sim}X2$ input (3 points) is possible. [FWD], [REV], [M0], M1, ALARM-RESET, EXT-ERROR, H-FREE []: Initial setting	Arbitrary signal assignment to INO~IN4 input (5 points) is possible. [FWD], [REV], [M0], [M1], [ALARM-RESET], EXT-ERROR, H-FREE []: Initial setting					
Output Signala	Photocoupler and Open-Collector Output External Power Supply: 4.5~30 VDC 100 mA or less Sink Output/Source Output Supported through external wiring	Photocoupler and Open-Collector Output External Power Supply: 4.5~30 VDC 100 mA or less Sink Output/Source Output Supported through external wiring					
Output Signals	Arbitrary signal assignment to Y0, Y1 output (2 points) is possible. [ALARM-OUT1], [SPEED-OUT], ALARM-OUT2, MOVE, VA, WNG []: Initial setting	Arbitrary signal assignment to OUTO, OUT1 output (2 points) is possible. [ALARM-OUT1], [SPEED-OUT], ALARM-OUT2, MOVE, VA, WNG []: Initial setting					
Protective Function	When the following protective functions are activated, the output from ALARM An alarm code will be displayed at the same time. (Instantaneous stop will or Overcurrent, main circuit overcurrent, overvoltage, undervoltage, sensor error operation stop during initialization, external stop	nly occur when an external stop is applied)					
Max. Extension Distance	Motor and driver distance: 10.5 m [when an	accessory connection cable (for relay) is used]					
Time Rating	Conti	inuous					

Overload alarm detection time

The overload alarm is generated if the operation goes beyond the continuous duty region.

The detection time for this overload alarm can be set from 0.1~60.0 seconds. (Initial value: 30.0 seconds)

However, an alarm will be generated within 5 seconds in the following cases:

- $\boldsymbol{\cdot}$ When a load exceeding the limited duty region is applied
- · When the output shaft is locked

General Specifications

Item	ı	Motor	Driver			
Insulation Resistance		$100\ \text{M}\Omega$ or more when 500 VDC megger is applied between the windings and the case after continuous operation under normal ambient temperature and humidity.	The measured value is 100 $\rm M\Omega$ or more when a 500 VDC megger is applied between the power supply terminal and the protective earth terminal and between the power supply terminal and the signal I/O terminal after continuous operation under normal ambient temperature and humidity.			
Dielectric Voltage		Sufficient to withstand 1.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.	Sufficient to withstand 1.5 kVAC at 50 Hz applied between the power supply terminal and the protective earth terminal for 1 minute, and 1.5 kVAC at 50 Hz applied between the power supply terminal and the I/O signal terminal for 1 minute after continuous operation under normal ambient temperature and humidity.			
Temperature Rise		The temperature rise of the windings is 50°C max. (60°C max. at 300 W) and that of the case surface is 40°C max. (50°C max. at 300 W), measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity*1.	The temperature rise of the heat sink is 50°C max., measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity.			
	Ambient Temperature	0~40°C (Non-freezing)	$0{\sim}40^{\circ}\text{C}$ (Non-freezing) [0 ${\sim}+35^{\circ}\text{C}$ (Non-freezing) if a 300 W type driver is installed with the front side facing upwards. Please check page 24 for the front side of the driver.]			
Operating Environment	Ambient Humidity	85% max. (Non-condensing)				
	Altitude	Max. of 1000 m	above sea level			
	Atmosphere	No corrosive gases or dust. Cannot be used in a radioactive area, magne	tic field, vacuum, or other special environments.			
	Vibration	Must not be subjected to continuous vibration or excessive shock. Confor Frequency range: 10~55 Hz Half amplitude: 0.15 mm Sweep direction:				
	Ambient Temperature	-20∼+70°C (Non-freezing)	-25∼+70°C (Non-freezing)			
Storage Condition*2	Ambient Humidity	85% max. (No	n-condensing)			
	Altitude	Max. of 3000 m	above sea level			
Heat-Resistant Class		UL/CSA Standards: 105 (A), EN Standards: 120 (E)	_			
Degree of Protection*	3	When the cable is connected: IP66 (Excluding the installation surface of the round shaft type)	IP20			

^{*1} For round shaft types, install on a heat sink (material: aluminum) of one of the following sizes to maintain a motor case surface temperature of 90°C or less.

30 W type: 115×115 mm thickness 5 mm, 60 W type: 135×135 mm thickness 5 mm, 120 W type: 165×165 mm thickness 5 mm, 200 W type: 200×200 mm thickness 5 mm, 300 W type: 250×250 mm thickness 6 mm

Note

Do not measure insulation resistance or perform a dielectric strength test while the motor and driver are connected.

Motor Materials and Surface Treatment

• Materials Case: Aluminum

Output shaft: Stainless steel

Screws: Stainless steel (externally facing screws only; protective earth terminals excluded)

• Surface treatment Case: Paint (installation surface excluded)

Permissible Torque of Combination Types

Combination Type with a Parallel Shaft Gearhead

Unit: N⋅m

Output Power	Gear Ratio Motor Shaft Speed	5	10	15	20	30	50	100	200
	At 80~2000 r/min	0.45	0.9	1.4	1.8	2.6	4.3	6	6
30 W	At 3000 r/min	0.43	0.86	1.3	1.7	2.5	4.1	6	6
	At 4000 r/min	0.32	0.65	0.97	1.3	1.9	3.1	5.4	5.4
	At 80~2000 r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
60 W	At 3000 r/min	0.86	1.7	2.6	3.4	4.9	8.2	16	16
	At 4000 r/min	0.65	1.3	1.9	2.6	3.7	6.2	12.4	14
	At 80~2000 r/min	2	4.1	6.1	8.1	11.6	19.4	30	30
120 W	At 3000 r/min	1.7	3.4	5.2	6.9	9.9	16.4	30	30
	At 4000 r/min	1.3	2.6	3.9	5.2	7.4	12.3	24.7	27
200 W	At 80~3000 r/min	2.9	5.7	8.6	11.5	16.4	27.4	51.6	70
200 W	At 4000 r/min	2.2	4.3	6.5	8.6	12.4	20.6	38.9	63
300 W	At 80~3000 r/min	4.3	8.6	12.9	17.2	24.6	41.1	70	
	At 4000 r/min	3.2	6.4	9.7	12.9	18.5	30.8	58	-

[•] A colored ______ indicates gear shaft rotation in the same direction as the motor shaft. Other models rotate in the opposite direction.

Output Shaft Speed of Combination Types

Unit: r/min

			-					
Gear Ratio Motor Shaft Speed	5	10	15	20	30	50	100	200
80 r/min	16	8	5.3	4	2.7	1.6	0.8	0.4
2000 r/min	400	200	133	100	66.7	40	20	10
3000 r/min	600	300	200	150	100	60	30	15
4000 r/min	800	400	267	200	133	80	40	20

 $[\]ensuremath{\bigstar2}$ The storage condition applies to short periods such as the period during transport.

^{*3} The IP display indicating watertight and dust-resistant performance is regulated by IEC 60529 and IEC 60034-5.

Permissible Radial Load and Permissible Axial Load

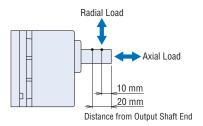
Combination Type with a Parallel Shaft Gearhead

			Permissible			
Output	Geal	r Ratio	10 mm from the end of the	20 mm from the end of the	Permissible Axial Load	
			· ·	output shaft output shaft N N 100 150 90 110 150 200 130 170 200 300 180 230 200 250 180 220		
		T			N	
	5	At 80~3000 r/min		1 1		
		At 4000 r/min	90	i i		
30 W	10, 15, 20	At 80~3000 r/min	150	200	40	
00 11	10, 13, 20	At 4000 r/min	130	170	40	
	30, 50, 100, 200	At 80~3000 r/min	200	300		
	30, 30, 100, 200	At 4000 r/min	180	230		
	5	At 80~3000 r/min	200	250		
	3	At 4000 r/min	180	220		
40 W	10 15 20	At 80~3000 r/min	300	350	100	
60 W	10, 15, 20	At 4000 r/min	270	330	100	
	20 50 100 000	At 80~3000 r/min	450	550		
	30, 50, 100, 200	At 4000 r/min	420	500		
	-	At 80~3000 r/min	300	400		
	5	At 4000 r/min	230	300		
100 147	10.15.00	At 80~3000 r/min	400	500	450	
120 W	10, 15, 20	At 4000 r/min	370	430	150	
	22 -2 -22 222	At 80~3000 r/min	500	650		
	30, 50, 100, 200	At 4000 r/min	450	550		
	5 10 15 00	At 80~3000 r/min	550	800	000	
	5, 10, 15, 20	At 4000 r/min	500	700	200	
200 W	20.50	At 80~3000 r/min	1000	1250		
300 W	30, 50	At 4000 r/min	900	1100	300	
	100 000°	At 80~3000 r/min	1400	1700	400	
	100, 200*	At 4000 r/min	1200	1400	400	

^{*}Only when output power is 200 W

Round Shaft Type

	Permissible		
Output Power	10 mm from the end of the output shaft N	20 mm from the end of the output shaft N	Permissible Axial Load
30 W 60 W	80	100	
120 W 200 W 300 W	150	170	Half of motor mass max.



■Permissible Inertia J of Combination Types

Combination Type with a Parallel Shaft Gearhead

Unit: $\times 10^{-4}$ kg·m²

	O Pal's								
Output Power	Gear Ratio	5	10	15	20	30	50	100	200
		12	50	110	200	370	920	2500	5000
30 W	When instantaneous stop or instantaneous bi-directional operation is performed*	1.55	6.2	14	24.8	55.8	155	155	155
		22	95	220	350	800	2200	6200	12000
60 W	When instantaneous stop or instantaneous bi-directional operation is performed*	5.5	22	49.5	88	198	550	550	550
		45	190	420	700	1600	4500	12000	25000
120 W	When instantaneous stop or instantaneous bi-directional operation is performed*	25	100	225	400	900	2500	2500	2500
		100	460	1000	1700	3900	9300	18000	37000
200 W	When instantaneous stop or instantaneous bi-directional operation is performed*	50	200	450	800	1800	5000	5000	5000
		100	460	1000	1700	3900	9300	18000	_
300 W	When instantaneous stop or instantaneous bi-directional operation is performed*	50	200	450	800	1800	5000	5000	-

^{*}It is also applicable when digitally setting the deceleration time to below 0.1 seconds.

Dimensions (Unit = mm)

- The motor dimensions in this catalogue are the dimensions when a separately sold connection cable (the color in the diagrams) is attached.
 - Listed masses do not include the mass of the connection cable.
- Refer to page 20 for the dimensions and masses of connection cables.
- ■Installation screws are included with the combination type. Dimensions for installation screws → Page 20
- lacktriangle A number indicating the gear ratio is specified where the box \Box is located in the product name.

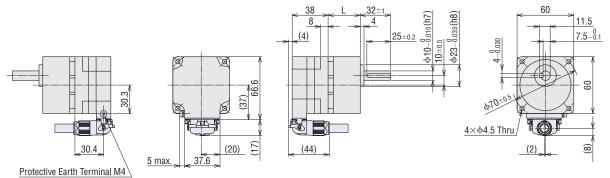
Motor

<>30 W

• Combination Type with a Parallel Shaft Gearhead

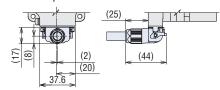
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
			5~20	34	
BLM230HP-□S	BLM230HP-GFV	GFV2G□S	30~100	38	0.85
			200	43	

• When connection cable is attached for pull-out on output shaft side



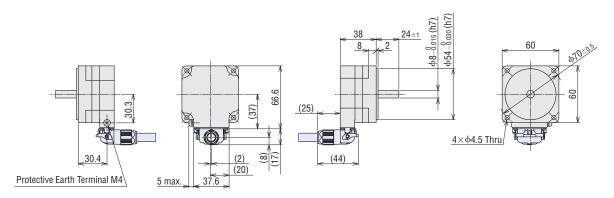
•At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor



• Round Shaft Type **BLM230HP-AS**

Mass: 0.35 kg

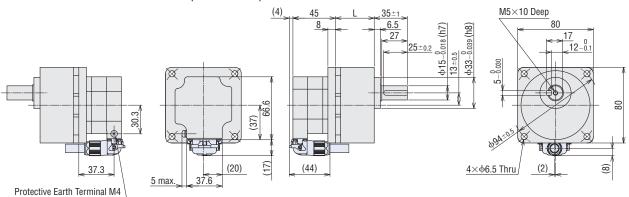


♦60 W

• Combination Type with a Parallel Shaft Gearhead

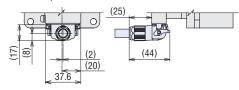
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
			5~20	41	
BLM460SHP-□S	BLM460SHP-GFV	GFV4G□S	30~100	46	1.6
			200	51	

• When connection cable is attached for pull-out on output shaft side



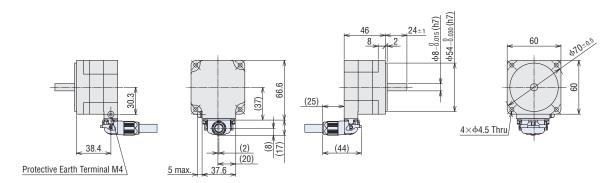
●At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor



• Round Shaft Type **BLM260HP-AS**

Mass: 0.52 kg

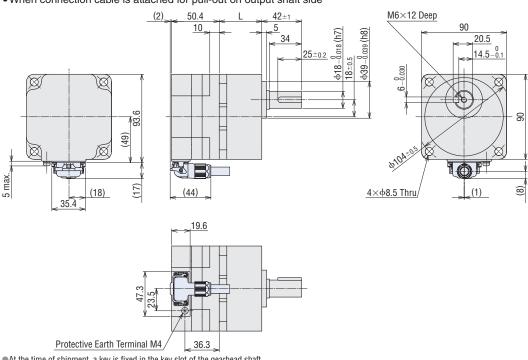


♦120 W

• Combination Type with a Parallel Shaft Gearhead

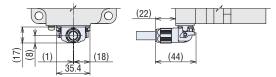
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
			5~20	45	
BLM5120HP-□S	BLM5120HP-GFV	GFV5G□S	30~100	58	2.6
			200	64	

• When connection cable is attached for pull-out on output shaft side



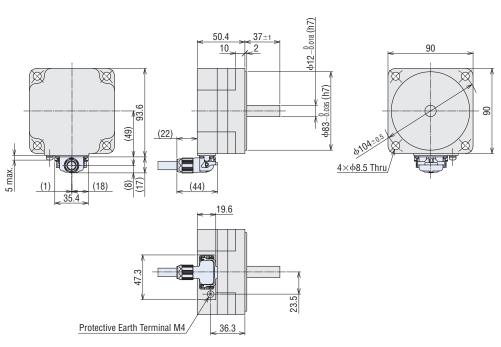
At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor



• Round Shaft Type BLM5120HP-AS

Mass: 1.1 kg

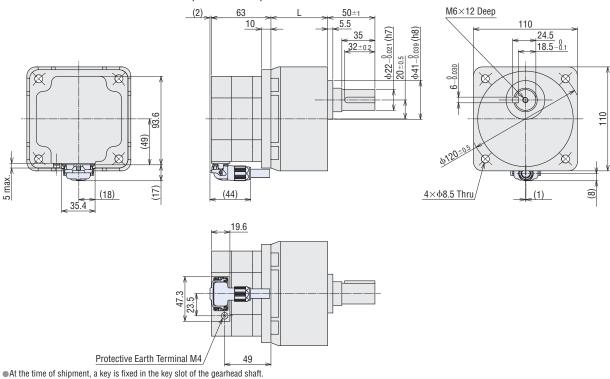


♦200 W

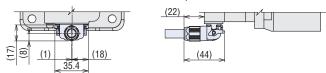
• Combination Type with a Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
BLM6200SHP-□S			5~20	60	
	BLM6200SHP-GFV	GFV6G□S	30, 50	72	4.7
			100, 200	86	

• When connection cable is attached for pull-out on output shaft side

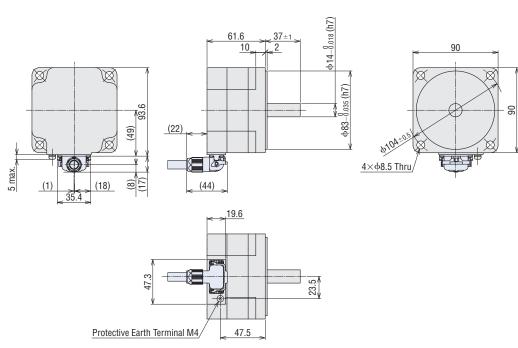


• When connection cable is attached for pull-out on rear of the motor



Round Shaft Type BLM5200HP-AS

Mass: 1.6 kg

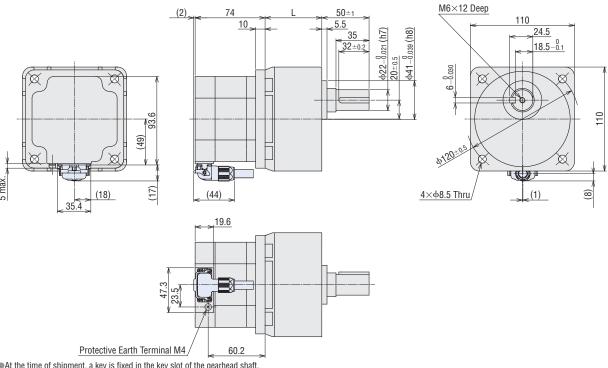


♦300 W

• Combination Type with a Parallel Shaft Gearhead

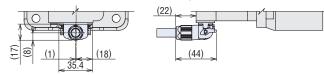
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
BLM6300SHP-□S			5~20	60	
	BLM6300SHP-GFV	GFV6G□S	30, 50	72	5.2
			100	86	

• When connection cable is attached for pull-out on output shaft side



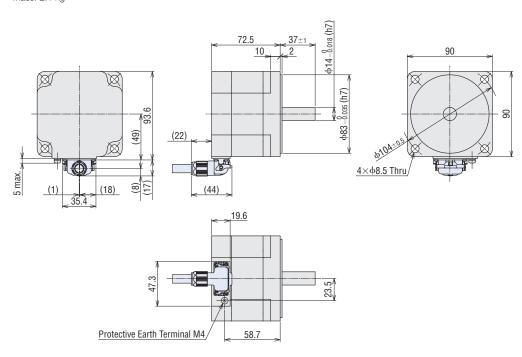
•At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor



Round Shaft Type BLM5300HP-AS

Mass: 2.1 kg

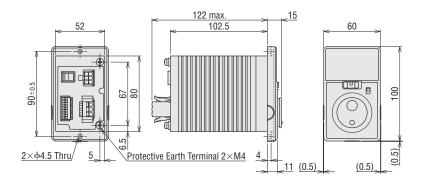


Drivers

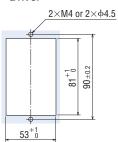
♦30 W, 60 W, 120 W

BMUD30-A2, BMUD30-C2, BMUD60-A2, BMUD60-C2, BMUD120-A2, BMUD120-C2

Mass: 0.4 kg



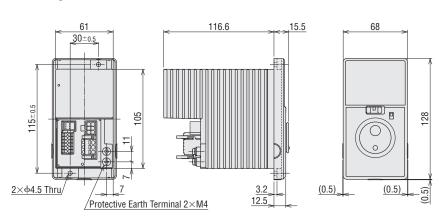
Panel Cut-Out Dimension for Driver



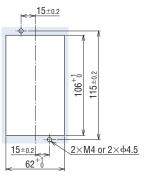
♦200 W, 300 W

BMUD200-A, BMUD200-C, BMUD300-C

Mass: 0.8 kg

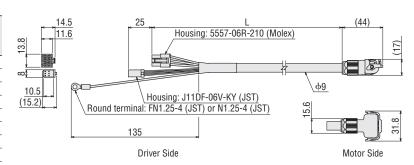


• Panel Cut-Out Dimension for Driver



Connection Cables

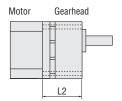
Longth	Produc		
Length L (m)	Pull-out on output shaft side	Pull-out on rear of the motor	Mass (kg)
0.5	CC005HBLF	CC005HBLB	0.08
1	CC010HBLF	CC010HBLB	0.12
1.5	CC015HBLF	CC015HBLB	0.2
2	CC020HBLF	CC020HBLB	0.25
2.5	CC025HBLF	CC025HBLB	0.32
3	CC030HBLF	CC030HBLB	0.38
4	CC040HBLF	CC040HBLB	0.49
5	CC050HBLF	CC050HBLB	0.62
7	CC070HBLF	CC070HBLB	0.86
10	CC100HBLF	CC100HBLB	1.2



Installation Screw Dimensions

Combination Type with a Parallel Shaft Gearhead





Gearhead	Installatio	on Screws	L2
Product Name	L1 (mm)	Screw Size	(mm)
GFV2G5S~20S	50		42
GFV2G30S~100S	55	M4 P0.7	46
GFV2G200S	60		51
GFV4G5S~20S	60		49
GFV4G30S~100S	65	M6 P1.0	54
GFV4G200S	70		59
GFV5G5S~20S	70		55
GFV5G30S~100S	85	M8 P1.25	68
GFV5G200S	90		74
GFV6G5S~20S	85		70
GFV6G30S~50S	100	M8 P1.25	82
GFV6G100S~200S	110		96

[•]Installation Screws: Plain washer, spring washer included (4 each)

ullet The installation screw material is stainless steel.

Connection and Operation (30 W, 60 W, 120 W)

Names and Functions of Driver Parts

Display

Displays the monitor contents, alarm, etc.

Dial

Changes the speed and parameters.

The value is set when the dial is pressed after changes are made.



Operating Switch

The motor is started by setting it to the "RUN" position.

Setting it to the "STAND-BY" position stops the motor.

Rotation Direction Switch

Changes the rotation direction of the motor.

Front Panel

Sensor Signal Connector (CN3)

Connects to the sensor connector (black) on the motor.

I/O Signal Connector (CN4)

Connects the I/O signals



Motor Connector (CN2)

Connects to the motor connector (white) on the motor

Main Power Connector (CN1)

Connects the main power supply.

Protective Earth

Terminals (2 locations)

Ground either one of the protective earth terminals.

[Front of Driver]

MODE Key

Changes the operating mode.



FUNCTION Key

Changes the indication and functions for the operating mode.

Acceleration/ Deceleration Time Potentiometer

Sets the acceleration time for starting the motor and deceleration time for motor standstill.

Setting Range: 0.1 s~15.0 s

Installation Holes (2 locations)

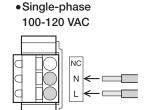
Extended Functions

These settings can be made with key operations after removing the front panel.

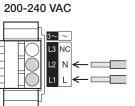
[Back of Driver]

Operating Mode	Details	
Monitoring	Speed, load factor, operating data number, alarm code, warning, I/O monitor	
Data	4 data points Operating speed, acceleration time, deceleration time, reset	
Parameters	Gear ratio, speed increasing ratio, initial panel display, initial operation prohibition alarm, initial operation prohibition alarm cancellation method selection, analog acceleration/deceleration, speed upper limit/ lower limit setting function, simple holding selection, external operating signal input, input function selection, output function selection, overload alarm detection time except when shaft is locked, overload warning level, speed attainment band, parameter mode reset	

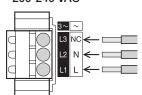
Connects the main power supply. Connect a power supply that matches the power supply voltage to be used.



Single-phase 200-240 VAC



•Three-phase 200-240 VAC



• Applicable Lead Wire Size

AWG18~14 (0.75~2.0 mm²)

Operation with the Driver Only

When the operating switch is set to the "RUN" position, the motor will start.

When it is returned to "STAND-BY, " the motor will decelerate to a stop.

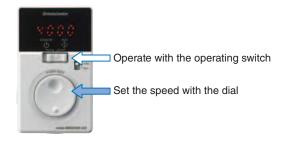
♦ Speed Setting Method

Set the motor speed by using the dial.

Turning the dial slowly to the right increases the speed by 1 r/min increments, while turning it to the left reduces the speed by 1 r/min increments.

Turning the dial quickly increases the speed variation.

Pressing the dial sets the speed.



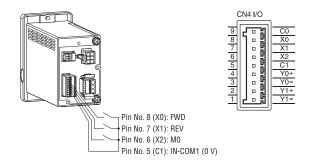
Operating Switch



Operation by External Signals

○Operating Method

- Using the built-in power supply in the driver, the motor is operated through signals from external sources (switches, relays, etc.).
 Connect Pins No. 5∼8 of the I/O signal connector (CN4) as shown in the figure to the right.
- When operating using external signals, change the parameter setting in the "External Operating Signal Input." Refer to the operating manual for details.
- Multistep speed-change operation up to 4 steps can be performed.



• Applicable Lead Wire Size AWG26~20 (0.14~0.5 mm²)

•I/O Signal Connector (CN4)

-	•	` ,	
Pin No.	Terminal Name	Function*	Description
9	CO	IN-COM0	Input signal common (for external power supply)
8	X0	[FWD]	The motor rotates in the forward direction when "ON".
7	X1	[REV]	The motor rotates in the reverse direction when "ON".
6	X2	[M0]	Selects the operating data.
5	C1	IN-COM1	Input signal common (for internal power supply: 0 V)
4	Y0+	[SPEED-OUT]	30 pulses are output when the motor output shaft
3	Y0-	[3FEED-001]	makes one rotation.
2	Y1+	[ALARM-OUT1]	Turns OFF when an alarm activates.
1	Y1 —	[ALANIVI-UUTT]	(Normally closed)

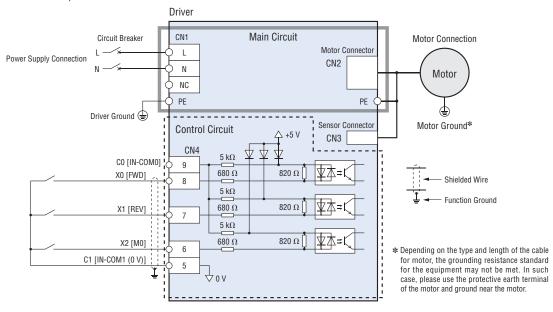
*The text inside the [] represents the factory default function assignment.

The following signals can be assigned as necessary to 3 input signal terminals $(X0 \sim X2)$ and 2 output signal terminals (Y0, Y1).

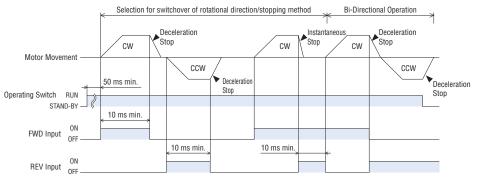
- 3 of the 7 input signals (FWD, REV, M0, M1, ALARM-RESET, EXT-ERROR, H-FREE)
- 2 of the 6 output signals (ALARM-OUT1, SPEED-OUT, ALARM-OUT2, MOVE, VA, WNG)

♦ Connection Example Using Switches and Relays

The figure shows a connection example when operating a motor with a contact switch, such as switches and relays. (Single-phase 200-240 VAC)



This is when the "External Operating Signal Input" parameter setting is "ON" and the rotation direction switch is set to "FWD."

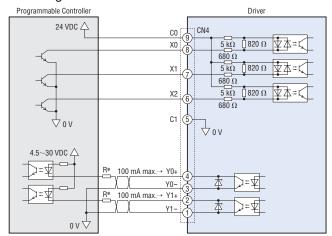


- Switching the FWD input to ON will cause the motor to rotate clockwise as viewed from the motor shaft side, while switching the REV input to ON will cause the motor to rotate counterclockwise. Turning it OFF decelerates the motor to a stop.
- If the FWD input and REV input are turned ON simultaneously, the motor will stop instantaneously.
- With the combination type, the rotation direction varies according to the gear ratio of the gearhead.

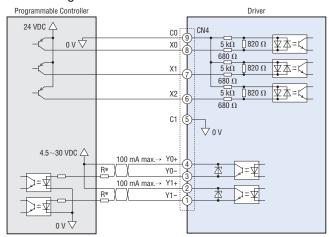
♦ I/O Signal and Programmable Controller Connection Examples

This is a connection example for operating a motor using a transistor output type programmable controller.

Sink Logic



•Source Logic



*Recommended Resistance Value

24 VDC: 680 $\Omega{\sim}2.7~\text{k}\Omega$ (2 W)

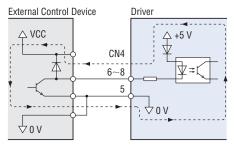
5 VDC: 150 $\Omega{\sim}560~\Omega$ (0.5 W)

Note

Maintain the current value of Y0 and Y1 at 100 mA or less. If this current value is exceeded, connect the limiting resistor R.

♦ When an External Control Device with a Built-In Clamp Diode is Used

If an external control device with a built-in clamp diode is connected and the external control device is turned off when the driver power is on, current may flow, and the motor may turn. Because the current capacity between the driver and external control device is different, the motor may also rotate when their power supplies are turned ON/OFF simultaneously. To turn the power off, turn off the driver and then the external control device. To turn the power on, turn on the external control device and then the driver.

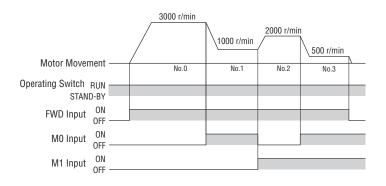


♦ When Multistep Speed-Change Operation is Used

Multistep speed-change operation is possible by switching the M0 and M1 inputs ON / OFF.

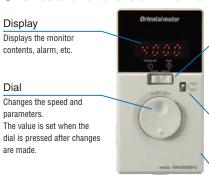
Operating Condition Example

Operating Data No.	MO	M1	Speed [r/min]
0	0FF	0FF	3000
1	ON	0FF	1000
2	0FF	ON	2000
3	ON	ON	500



■ Connection and Operation (200 W, 300 W)

Names and Functions of Driver Parts



Operating Switch

The motor is started by setting it to the "RUN" position.

Setting it to the "STAND-BY" position stops the motor.

Rotation Direction Switch

Changes the rotation direction of the motor.

Front Panel

Sensor Signal Connector (CN3)

Connects to the sensor connector (black) on the motor

I/O Signal Connector (CN4)

Connects the I/O signals



Motor Connector (CN2)

Connects to the motor connector (white) on the motor.

Main Power Connector (CN1)

Connects the main power supply.

Protective Earth
Terminals (2 locations)

Ground either one of the protective earth terminals.

[Front of Driver]

♦ When Front Panel is Removed

MODE Key Changes the operating mode.

FUNCTION Key

Changes the indication and functions for the operating mode.

Acceleration/ Deceleration Time Potentiometer

Sets the acceleration time for starting the motor and deceleration time for motor standstill.

Setting Range: 0.1 s~15.0 s

Installation Holes (2 locations)

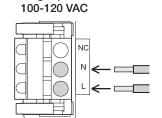
Extended Functions

These settings can be made with key operations after removing the front panel.

[Back of Driver]

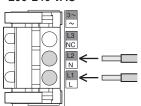
pa	
Operating Mode	Details
Monitoring	Speed, load factor, operating data number, alarm, warning, I/O monitor
Data	4 data points Speed, acceleration time, deceleration time, reset
Parameters	Gear ratio, speed increasing ratio, initial panel display, initial operation prohibition alarm, initial operation prohibition alarm cancellation method selection, analog acceleration/deceleration, speed upper limit/ lower limit setting function, simple holding selection, external operating signal input, input function selection, output function selection, overload alarm detection time except when shaft is locked, overload warning level, speed attainment band, parameter mode reset

Connects the main power supply. Connect a power supply that matches the power supply voltage to be used.

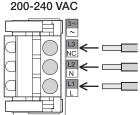


Single-phase

Single-phase 200-240 VAC



•Three-phase 200-240 VAC



For the 300 W type, only L1, L2, and L3 are shown.

Applicable Lead Wire Size

AWG18~14 (0.75~2.0 mm²)

Operation with the Driver Only

When the operating switch is set to the "RUN" position, the motor will start.

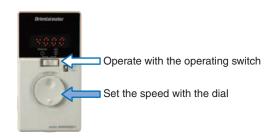
When it is returned to "STAND-BY," the motor will decelerate to a stop.

Set the motor speed by using the dial.

Turning the dial slowly to the right increases the speed by 1 r/min increments, while turning it to the left reduces the speed by 1 r/min increments.

Turning the dial quickly increases the speed variation.

Pressing the dial sets the speed.



Operating Switch



Operation by External Signals

○Operating Method

- Using the built-in power supply in the driver, the motor is operated through signals from external sources (switches, relays, etc.).
 Connect pins No.1~5 and No.7 of the I/O signal connector (CN4) as shown in the chart below.
- When operating using external signals, change the "external operation input signal" parameter. For more details, refer to the operating manual.
- Multistep speed change operations involving up to 4 steps are possible.

12 6 6 5 5 10 9 9 0 3 3 8 0 2 2 7 1 1 1 CN4

◆Applicable Lead Wire Size AWG24~18 (0.2~0.75 mm²)

•I/O Signal Connector (CN4)

Signal Name	Function*	Description
IN4	[ALARM-RESET]	Alarms are reset.
IN3	[M1]	Selects the operating data.
IN2	[M0]	Selects the operating data.
IN1	[REV]	The motor rotates in the reverse direction when "ON".
INO	[FWD]	The motor rotates in the forward direction when "ON".
IN-COM0	IN-COMO	Input signal common (for external power supply)
IN-COM1	IN-COM1	Input signal common (for internal power supply: 0 V)
N.C.	N.C.	No connection.
0UT1-	[ALADM OUT1]	Turns OFF when an alarm activates.
0UT1+	[ALANIVI-UUTT]	(Normally closed)
OUTO-	ISDEED OUT	30 pulses are output with each rotation of
0UT0+	[3FLLD-001]	the motor output shaft.
	Name IN4 IN3 IN2 IN1 IN0 IN-COM0 IN-COM1 N.C. OUT1 — OUT1 + OUT0 —	Name

*Text inside the [] represents the factory default function assignment.

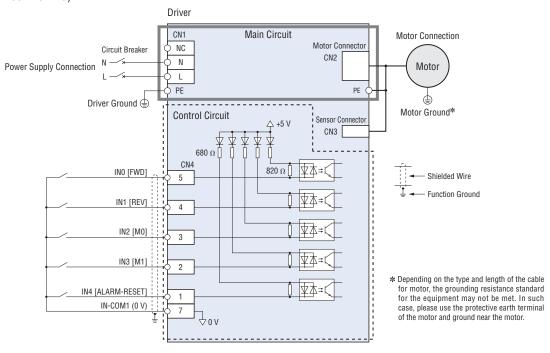
The following signals can be assigned as necessary to 5 input signal terminals (IN0 \sim IN4) and 2 output signal terminals (OUT0, OUT1).

5 out of the 7 possible input signals (FWD, REV, M0, M1, ALARM-RESET, EXT-ERROR, H-FREE)

2 out of the 6 possible output signals (ALARM-OUT1, SPEED-OUT, ALARM-OUT2, MOVE, VA, WNG)

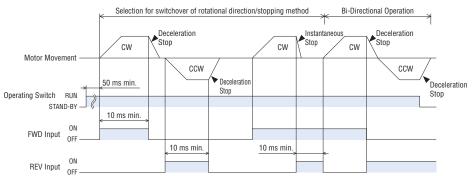
\Diamond Connection Example using Switches and Relays

The figure shows a connection example when operating a motor with a contact switch, such as switches and relays. (Single-phase 200-240 VAC)



♦Timing Chart

This is when the "External Operating Signal Input" parameter setting is "ON" and the rotation direction switch is set to "FWD."

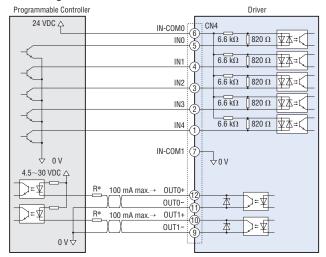


- Switching the FWD input to ON will cause the motor to rotate clockwise as viewed from the motor shaft side, while switching the REV input to ON will cause the motor to rotate counterclockwise. Turning it OFF decelerates the motor to a stop.
- If the FWD input and REV input are turned ON simultaneously, the motor will stop instantaneously.
- With the combination type, the rotation direction varies according to the gear ratio of the gearhead.

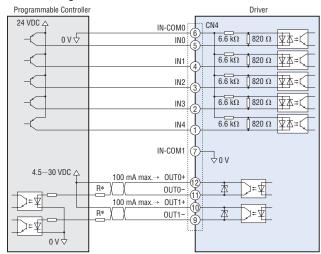
♦ I/O Signal and Programmable Controller Connection Examples

This is a connection example for operating a motor using a transistor output type programmable controller.

Sink Logic



Source Logic



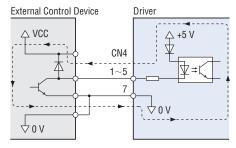
*Recommended Resistance Value 24 VDC: 680 $\Omega{\sim}2.7$ k Ω (2 W)

5 VDC: 150 $\Omega{\sim}560~\Omega~(0.5~\mathrm{W})$ Note

Maintain the current value of OUTO and OUT1 at 100 mA or less. If this current value is exceeded, connect the limiting resistor R.

♦ When an External Control Device with a Built-In Clamp Diode is Used

If an external control device with a built-in clamp diode is connected and the external control device is turned off when the driver power is on, current may flow in and rotate the motor. Because the current capacity of the driver and external control device is different, the motor may also rotate when their power supplies are turned ON or OFF simultaneously. To turn the power off, turn off the driver and then the external control device. To turn the power on, turn on the external control device and then the driver.

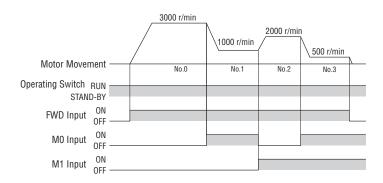


♦ When Multistep Speed-Change Operation is Used

Multistep speed-change operation is possible by switching the M0 and M1 inputs ON / OFF.

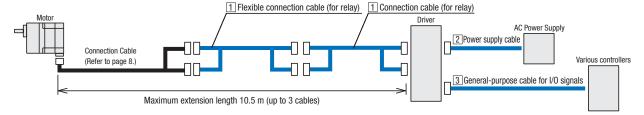
Operating Condition Example

Operating Data No.	MO	M1	Speed [r/min]
0	0FF	0FF	3000
1	ON	0FF	1000
2	0FF	ON	2000
3	ON	ON	500



Accessories (Sold separately)

Cable System Configuration



1 Connection Cables (For relay), Flexible Connection Cables (For relay)

When using a connection cable (for relay) or flexible connection cable (for relay) in tandem to extend the length, please keep the total cable length under 10.5 m (up to 3 cables total).

Product Line

♦ Connection Cables

Product Name	Length L (m)
CC01BL2	1
CC02BL2	2
CC03BL2	3
CC05BL2	5
CC07BL2	7
CC10BL2	10



Product Name	Length L (m)
CC01BL2R	1
CC02BL2R	2
CC03BL2R	3
CC05BL2R	5
CC07BL2R	7
CC10BL2R	10



2 Power Supply Cables

These cables are used to connect the driver and the AC power supply. Cables are available with or without a power supply plug.



Plug Included

3 General-Purpose Cables for I/O Signals

These are cables for connecting the driver and programmable controller.



Product Line

Product Name	Product Line	Power Supply Voltage	Length L (m)
CC01AC03N	- No plug	Single-phase 100-120 VAC Single-phase 200-240 VAC	1
CC02AC03N			2
CC03AC03N			3
CC01AC04N			1
CC02AC04N		Three-phase 200-240 VAC	2
CC03AC04N			3

Product Line

Product Name	Length L (m)	Number of Lead Wire Cores	Outer diameter D (mm)	AWG
CC06D005B-1	0.5	6	ф5.4	24
CC06D010B-1	1			
CC06D015B-1	1.5			
CC06D020B-1	2			
CC10D005B-1	0.5	10	ф6.7	
CC10D010B-1	1			
CC10D015B-1	1.5		ψυ.7	
CC10D020B-1	2			

For details, check the website or contact the customer support center.

http://www.orientalmotor.eu

Flexible Coupling

shaft diameter.

A clamp type coupling for connecting the motor and gearhead shaft with a driven shaft. Couplings that can be used with combination type and round shaft type models are available. Couplings can also be used on the round shaft type. Please

select a coupling with the same inner diameter as the motor



Product Name	Applicable Product (Motor)	
MCL30 type	BLM230 combination type	
MCL40 type	BLM460 combination type	
MCL55 type	BLM5120 combination type	
MCL65 type	BLM6200 combination type	
	BLM6300 combination type	

Mounting Bracket for Motor and Gearhead

These dedicated installation brackets are for installing motors and gearheads.



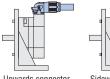
Product Line

Product Line

Product Name	Applicable Product (Motor)	
SOL2M4F	BLM230 BLM260 (round shaft type)	
SOL4M6F	BLM460 (combination type)	
SOL5M8F	BLM5120 BLM5200, BLM5300 (round shaft type)	
SOL6M8F	BLM6200, BLM6300 (combination type)	

Note

When fixing a mounting bracket and motor, please ensure that the motor connector is above or beside the installation surface. We do not recommend installing below the installation surface, since this causes interference with the mounting bracket and installation surface.





Upwards connector

Sideways connector

Mounting Bracket for Circuit Products

Handy installation brackets are available for installation of drivers. A variety of application-specific mounting brackets are available, including DIN rail mounting brackets, surface mounting brackets, and conveyor guide mounting brackets.

Product Line

Material: SPCC Surface Treatment: Trivalent chromate

Product Name	Application	Applicable Product (Driver)	
MADP05-15	DIN rail mounting model		
MAFP04-15	Surface mounting model	BMUD30 BMUD60 BMUD120	
MAFP05V	Conveyor guide	BMOD I 20	
MAFP05H	mounting model		
MADP05-12B	DIN rail mounting model	BMUD200	
MAFP04-12B	Surface mounting model	BMUD300	

Note

A mounting bracket for circuit products and dust-resistant and watertight front cover (→ page 30) cannot be used in combination.



MADP05-15 <usage example>



MADP05-12B <usage example>



MAFP04-15 <usage example>



MAFP05V <usage example>



MAFP05H <usage example>

For details, check the website or contact the customer support center.

http://www.orientalmotor.eu

■ Motor Covers NEW

These are covers that protect the motor. They are compatible with the degree of protection IP66 specification, and can be used in wet and dusty environments.

Product Line

♦Motor Covers

Product Name
PCM5
PCM5-C

Please aim to replace the gaskets every year.



Applicable Product

Output Power	Motor	Cable pull-out direction
		Pull-out on output shaft side
30 W, 60 W, 120 W	Parallel Shaft Combination Type*	
30 11, 30 11, 120 11	Round Shaft Type	Pull-out on rear of the motor

^{*}The parallel shaft combination type cannot be used for pull-out on the rear of the motor









With cable gland **PCM5-C**

For details, check the website or contact the customer support center.

http://www.orientalmotor.eu

■ Dust-Resistant and Watertight Front Covers

These are covers that protect the driver's front panel.

They satisfy the degree of protection IP64 specification.

They can also be used to prevent erroneous operations from being performed on the front panel.

Product Line

Product Name	Applicable Product (Driver)
PCF12	BMUD30 BMUD60 BMUD120

Note

A dust-resistant and watertight front cover and mounting bracket for circuit products
 (→ page 28) cannot be used in combination.



For details, check the website or contact the customer support center.

Introduction of Related Products

Brushless Motors

BLE2 Series



The BLE Series has undergone a full model change. The motor, driver, and cable are all new, realizing both high function and ease of use. It is an advanced model that feels more evolved the more you use it.

Features

- · Digital setting and operation with the driver.
- External speed setting is possible.
- · Torque limiting is possible.
- · Multistep speed-change operation up to 16 speeds
- The motor and driver can be directly connected up to 20 m.
- Watertight and dust-resistant performance (degree of protection IP66) *Motor only
- · High anti-rust and anti-corrosion properties thanks to the stainless steel shaft.
- · Cables with two pull-out options for smart wiring.

Orientalmotor

These products are manufactured at plants certified with the international standards ISO 9001 (for quality assurance) and ISO 14001 (for systems of environmental management).

Specifications are subject to change without notice. This catalogue was published in June, 2016.

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Printed in Germany LIK/062016/VFRS01