

# Hydraulic Motors **T series main features**



# **T SERIES**

• The motors of the new T series are featured by 7 cylinders to improve power density and performances



From 240 to 1200 cc/rev POWER: From 110 to 220 kW SPEED: From 0,1 to 1200 rpm PRESSURE: From 350 to 450 bar DUAL (TD)



Min. max. displ. up to 0-1200 cc/rev POWER: From 110 to 220 kW SPEED: From 0,1 to 2500 rpm PRESSURE: From 350 to 450 peak pressure VARIABLE (TV)



Infinite displacement variation from 0 to 1200 cc/rev POWER: From 110 to 220 kW SPEED: From 0,1 to 2500 rpm PRESSURE: From 350 to 450 bar





#### **T SERIES FEATURES**

- High power density + high bearing lifetime
- Higher torque stability with the 7 pistons design
  - High displacement variation (ratio used up to 1:10)
  - High efficiency even at low displacement
- Possibility to reach 0 cc/rev
- Very easy freewheeling at zero displacement









#### **DISPLACEMENT VARIATION CONTROL**

Motor displacement

Ways to control the displacement: DUAL DISPLACEMENT: hydraulic or electric VARIABLE DISPLACEMENT: electric + CPU + angular sensor COSTANT PRESSURE: self adjusting system (READY SOON)







### **DISPLACEMENT VARIATION CONTROL**

**DISTRIBUTOR WITH INTEGRATED HYDRAULIC CIRCUIT:** 

- **DUAL DISPLACEMENT:** hydraulic or electric + override (only electric)
- VARIABLE DISPLACEMENT: electric + CPU + angular sensor
- COSTANT PRESSURE: self adjusting system (READY SOON)

#### FEATURES TO SET :

- fast or low shifting time (orifices that can be regulated from the distributor)
- extremely fast response with extra high pressure line that can be connected to the distributor
- Override (only for electric valve)











#### MAIN FEATURES OF VARIABLE DISPLACEMENT CRANKSHAFT DESIGN HYDRAULIC MOTORS

High efficiency in a wide operational range





## MAIN FEATURES OF VARIABLE DISPLACEMENT **CRANKSHAFT DESIGN HYDRAULIC MOTORS**

Freewheeling at zero displacement without any extra power needed



<u>no extra pressure needed to keep the motor</u> at zero cc/rev or for lubrication

Motor disconnected from hydraulic circuit

No speed limit (no extra pressure needed to keep the motor at zero cc/rev or for Iubrication

No power losses (only few Nm of torque absorbed)

No extra flushing needed





#### **EFFICIENCY COMPARISON: TV1.5 VS AN AXIAL PISTON MOTOR**

## TEST CONDITIONS

Dynamometric brake

Hydraulic motor maximum power (fixed: 100 kW)

Ambient temperature 20°

Oil temperature 50°

Hydraulic oil: ISO VG 46

Hydraulic circuit: open loop circuit

- Working pressure: 100 Bar- 200 Bar-300 400 bar; Flow rate: 0-250 l/min
- TV1.5 working displacement: 216cc\rev - 108 cc\rev - 54cc\rev

Axial piston working displacement: 80cc\rev - 40cc\rev - 20cc\rev





efficiency %

ara

#### **EFFICIENCY COMPARISON: TV1.5 VS AN AXIAL PISTON MOTOR**

#### 100% of the total displacement @ 100-200-400 bar COMPARISON TV1.5 - AXIAL PISTON **COMPARISON TV1.5 - AXIAL PISTON MOTOR** 100% MAX DISPLACEMENT **COMPARISON TV1.5 - AXIAL PISTON** 100% MAX DISPLACEMENT 100% MAX DISPLACEMENT 100% 100% 100% 90% 90% 90% 80% 80% 80% \* 70% 70% 60% 60% 60% Ű. 50% 50% 50% 40% 40% TOVE 40% 30% 30% 30% ---- AXIAL PISTON @ 200 bar 20% 20% 20% 10% 10% 10% 0% 0% 0% 10% 20% 30% 40% 50% 60% 0% 70% 80% 90% 0% 10% 20% 30% 40% 50% 60% 70% 80% 90% 10% 20% 30% 40% 50% 60% 70% 80% 90% 100% 0% % max speed % max speed % max speed Value referred to the overall efficiency of the motors





#### EFFICIENCY COMPARISON: Hydraulic Motors TV1.5 VS AN AXIAL PISTON MOTOR 25% OF THE TOTAL DISPLACEMENT





#### **EFFICIENCY COMPARISON:**

#### TV1.5 VS AN AXIAL PISTON MOTOR CONSIDERING 1 STAGE OF REDUCTION (2.7:1) 50% & 25% OF THE TOTAL DISPLACEMENT @ 200 BAR





- An hydrostatic transmission is a drive or transmission system that uses pressurized hydraulic fluid to drive hydraulic machinery.
- An hydraulic drive system consists of three basic parts:











#### **ADVANTAGES OF HIGH RANGE VARIATION**

Motor type	<i>€</i> <sup>mmin</sup> (maximum)	<i>€</i> <sup>mmin</sup> (minimum)	<i>€</i> <sup>mmin</sup> (average)
Swash plate	0.3	0.35	0.325
Bent axis	0.2	0.25	0.225
New generation radial piston	0.1	0.2	0.15

	With respect to:	
TR increase with new generation radial piston motor	Swash plate	Bent axix
Average	+216%	+50%
Max	+300%	+200%

 $n_{mMax}$ TR = $\mathcal{E}_{pN} \mathcal{E}_{m\min}$ 

With the use of a radial piston motor the TRvalue can increase up to 300% compared to a swash plate motor and up to 200% compared to a bent-axis motor.

Moreover a radial piston motor has a considerably higher efficiency at the start up, respect to swash plate or bent axis and more important the overall efficiency of the motor in low displacement is drastically higher than the axial piston one.





## **SFEL** ADVANTAGES OF HIGH RANGE VARIATION IN SOME APPLICATIONS



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