

MotoLAC

Laser Applied Calibration with verification and automatic correction of the tool position and angle.



The MotoLAC tool for calibration and automatic correction will ensure a long and trouble-free operation with consistent quality. it will also reduce downtime during a change of tools or after a collision.

The MotoLAC sensor design makes it possible to measure several of the tool's positions and thus adjust both its position and angle. Adjustment can be made in X, Y and Z but also in Rx and Ry.

Thanks to its robust housing, the laser sensor can tolerate harsh environments and can be used in almost all robot applications - from laser cutting systems to material handling.

Key benefits

- Quick and easy tool calibration.
- Trouble-free operation.
- Minimizes downtime.
- Ideal when changing fixtures or tools.
- Reduces the need for touch up robot jobs after minor collisions.
- Three levels of control and adjustment from high speed Quick Check to complete control and adjustment of TCP and angle.
- Language: English, German or Swedish.

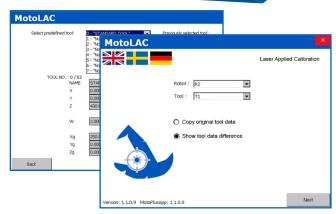
Scope of delivery

- Fork sensor.
- Metal bracket.
- MotoLAC Wizard and cable kit.



MotoLAC

Technical data



MotoLAC at a glance

With the simple and straightforward interface for the teach pendant, you can easily create reference data for up to 64 tools. Positions and I/O can be verified before implementation with a "Dry run". With the command "Show tool data difference", you will see the difference between the current tool data and its original values.

Three robot jobs are generated: Total TCP (including angle and position), positions XYZ only, and a Quick Check.

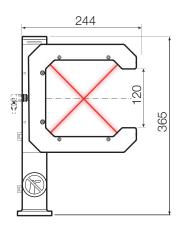
Technical data	
Laser	Red light, 650 nm, class 1
Housing material	Aluminium, anodised
Max/min angle	3°
Tool diameter	5 to 50 mm
Accuracy	0.2 mm
Adjustment size	tool radius

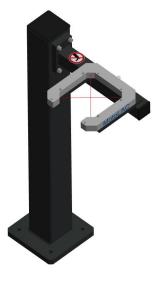
Note

- Not available with ATEX classification.
- The object used for calibration must be circular and with a recommended size of 5 to 50 mm in diameter.

Standard assembly

MotoLAC unit is mounted to the right. However, it is easy to dismantle the sensor unit from the bracket, and mount it to the left instead.



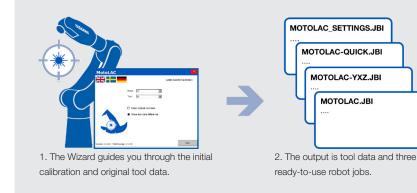


Options

Floor stand.

Calibration tool size

Tool diameter [mm]	Max detection [mm]
50	25
40	20
20	10
30	15
10	5
5	2.5





3. These robot jobs can be implemented at suitable intervals in the production process.





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